

Redistribution and Disability Insurance

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1 Introduction

- Design of welfare programs
- Several types of insurance
- Insurance against permanent low ability shocks – redistribution.
- Disability insurance
- Incentives
- Analyze interaction in optimal design in simple model
- Evaluate consequences of lack of coordination (multiple agencies)

2 The model

- Two periods
- Two types of agents with productivities $\{x_l, x_h\}$, shares $(1 - \pi), \pi$
- Agent's type private (Mirrlees.)
- No disutility of work first period.
- Second period independent shock to disutility of work $e \sim F(e)$.
- Utilitarian Principal.

2.1 Design problem and incentives

- Contracts specify $\{c_{1h}, c_{2h}, c_{dh}\}, \{c_{1l}, c_{2l}, c_{dl}\}$.

- Employment decision in second period:

$$\begin{aligned}u(c_{2h}) - e_h &= u(c_{dh}) \\ u(c_{2l}) - e_l &= u(c_{dl})\end{aligned}$$

- Simplified notation for second period utility:

$$\begin{aligned}U_2(c_2, c_d) &= \max_e \left(1 - F(e_j)\right) u(c_d) \\ &\quad + \int_0^e (u(c) - a) F(da)\end{aligned}$$

- Self selection constraint:

$$u(c_{1h}) + U_2(c_{2h}, c_{dh}) \geq u(c_{1l}) + U_2(c_{2l}, c_{dl})$$

2.2 The optimal contract

- For convenience take $\pi = \frac{1}{2}$

$$\max u(c_{1h}) + U_2(c_{2h}, c_{dh}) + u(c_{1l}) + U(c_{2l}, c_{dl})$$

subject to:

$$u(c_{1h}) + U_2(c_{2h}, c_{dh}) \geq u(c_{1l}) + U_2(c_{2l}, c_{dl})$$

$$0 \leq x_h - c_{1h} + (x_h - c_{2h})F(e_h) - (1 - F(e_h))c_{dh} \\ + x_l - c_{1l} + (x_l - c_{2l})F(e_l) - (1 - F(e_l))c_{dl}$$

2.3 Some results

- First order condition for first period consumption:

$$\begin{aligned}u'(c_{1h}) &= \lambda - \mu \\u'(c_{1l}) &= \lambda + \mu\end{aligned}$$

- $c_{1l} < c_{1h}$ if and only if self-selection binds ($\mu > 0$).

- $e_h > e_l$

- If $\mu > 0$, then:

1. $c_{2h} > c_{2l} > c_{dl} > c_{dh}$

2. $U_{2h} < U_{2l}$

- Remark: with no second period incentive constraint \rightarrow full insurance \rightarrow all consumptions identical.

- Incentives for disability limit redistribution.

3 Numerical results

- Calibration (π, x_l, x_h, F, u)

1. $\pi = 0.25$

2. $x_h = 3x_l$

3. $u(c) = \ln c$

4. F exponential hazard rate $\lambda \in \{0.5, 1, 2\}$

Median Disutility of Effort
(equivalent % loss in wages)

<i>Hazard</i>	<i>disutility</i>
$\lambda = 0.5$	75%
$\lambda = 1$	50%
$\lambda = 2$	29%

Consumption
(Constrained/Optimal)

	$\lambda = 0.5$	$\lambda = 1$	$\lambda = 2$
C_1l	85	89	96
C_2l	127	118	110
C_dl	70	65	58
replacement	55%	55%	53%
C_1h	106	123	110
C_2h	169	135	110
C_dh	40	13	0
replacement	24%	9%	0%
Avg. Replacement	45%	50%	53%

- Limited replacement ratios
- Very low for H types.
- Less redistribution first period.
- Replacement rates decreasing with λ .

Employment and Disability

	$\lambda = 0.5$		$\lambda = 1$ <input type="checkbox"/>		$\lambda = 2$	
	Optimal	Constrained	Optimal	Constrained	Optimal	Constrained
F(e_l)	35.1%	25.8%	53.9%	45.1%	75.9%	72.3%
F(e_h)	72.7%	51.2%	90.2%	90.6%	98.6%	100.0%
% disabled	55.5%	67.8%	37.0%	43.5%	18.4%	20.7%
autharky		53%		22%		0%

- Lower employment of low types.
- Increase in % disabled.
- Much more than under autharky.

Welfare

	$\lambda = 0.5$	$\lambda = 1$	$\lambda = 2$
First Best	100.0	100.0	100.0
Constrained	92.7	95.4	98.3
Autharky	75.9	77.5	83.6

- Big gains relative to autharky.
- Considerable difference to first best for low λ .

4 Uncoordinated decisions

- Advantages of coordinated redistribution and disability policies.
- Two principals.
- First principal:
 1. Decides on wage taxes
 2. Budget for disability insurance office.
- Second principal – disability insurance office:
- Decides c_{dh} and c_{dl} .

4.1 Coordination problem

- Free riding on self-selection.
- Does not internalize changes in tax revenue.
- Dynamic game.

4.2 Disability insurance office

- Takes as given c_{2h}, c_{2l} (follows from taxes)
- Can discriminate between h, l .
- Offers c_{dh}, c_{dl} to solve:

$$\max_{c_{dh}, c_{dl}} F(e_h) u(c_{2h}) - \int_0^{e_h} a f(a) da + (1 - F(e_h)) u(c_{2l}) + F(e_l) u(c_{2l}) - \int_0^{e_l} a f(a) da + (1 - F(e_l)) u(c_{2l})$$

subject to

$$e_j = u(c_{2j}) - u(c_{dj}), j = h, l$$

$$B = F(e_h) c_{dh} + F(e_l) c_{dl}$$

- Marginal cost of increasing c_{dj} :

$$\begin{aligned}
 & 1 - F(e_j) - f(e_j) c_{dj} \frac{\partial e_j}{\partial c_{dj}} \\
 &= F(e_j) + f(e_j) c_{dj} u'(c_{dj})
 \end{aligned}$$

- Marginal benefit: $F(e_j) u'(c_{dj})$
- Optimal rule equate Mg benefit/Mg cost on both types.

$$\frac{(1 - F(e_j)) u'(c_{dj})}{(1 - F(e_j)) + f(e_j) u'(c_{dj}) c_{dj}} = \lambda$$

where λ satisfies budget constraint.

4.3 First Principal's problem

- Same as before with the additional constraint:

$$= \frac{\frac{(1 - F(e_h)) u'(c_{dh})}{(1 - F(e_h)) + f(e_h) u'(c_{dh}) c_{dh}}}{\frac{(1 - F(e_l)) u'(c_{dl})}{(1 - F(e_l)) + f(e_l) u'(c_{dl}) c_{dl}}}$$

- Rewriting:

$$\frac{1}{\frac{1}{u'(c_{dj})} + \frac{f(e_j)}{1 - F(e_j)} c_{dj}} = \lambda$$

- Decreasing in c_{dj} and increasing (decreasing) in e_j if and only if hazard rate is decreasing (increasing).
- If F is exponential, then $c_{dh} = c_{dl}$ is only additional constraint. If hazard rate is increasing $c_{dh} < c_{dl}$ and $e_h > e_l$. If hazard rate is decreasing, opposite!

4.4 Two principals - numerical results

- Same case as before.
- F is exponential, so only add constraint $c_{dh} = c_{dl}$.

Consumption (two planners/one planner)

	$\lambda = 0.5$	$\lambda = 1$	$\lambda = 2$
C_1l	104	104	104
C_2l	93	96	94
C_dl	81	89	70
replacement	47.6	51.2	39.5
one planner	55%	55%	53%
C_1h	75	83	91
C_2h	117	109	116
C_dh	414	155	-
replacement	33%	34%	32%
one planner	24%	9%	0%
Avg. Replacement	42%	44%	37%
one planner	45%	50%	53%

- More redistribution first period (same consumption!)
- Replacement increases for h and decreases for l .

Employment and Disability

	$\lambda = 0.5$		$\lambda = 1$ □		$\lambda = 2$	
	Constrained	2 Principals	Constrained	2 Principals	Constrained	2 Principals
F(e_l)	25.8%	28.5%	45.1%	52.4%	72.3%	84.4%
F(e_h)	51.2%	41.8%	90.6%	66.5%	100.0%	89.9%
% disabled	67.8%	68.2%	43.5%	44.0%	20.7%	14.2%
autharky		53%		22%		0%

- e_l goes up and e_h goes down.

Welfare

	$\lambda = 0.5$	$\lambda = 1$	$\lambda = 2$
First Best	100.0	100.0	100.0
Constrained	92.7	95.4	98.3
Two Principals	91.7	93.1	96.5
Autharky	75.9	77.5	83.6

- Effects not negligible but small.

4.5 Redistribution and incentives

Redistribution (avg. Taxes on H)

	$\lambda = 0.5$	$\lambda = 1$	$\lambda = 2$
Optimal	55%	55%	53%
One planner	46%	44%	48%
two planners	45%	45%	46%

- Interaction with disability insurance incentives leads to lower income redistribution.
- Less so in later period.
- Disability much lower for high wage workers.
- Lack of coordination can lead to more equal disability.