# Tests of Equal Forecast Accuracy and Encompassing for Nested Models 

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#### Abstract

This paper examines the asymptotic and finite-sample properties of out-of-sample tests for equal accuracy and encompassing as applied to nested models. With nested models, these tests can be viewed as Granger causality tests. Applied to nested models, however, the standard asymptotic critical values for many tests of equal accuracy and encompassing are invalid. Statistics such as those proposed by Diebold and Mariano (1995) and Harvey, et. al. (1998) fail to converge to the standard normal distribution when the models are nested rather than nonnested. Building on McCracken's (1999) results for equal accuracy tests, this paper derives the asymptotic distributions for a set of standard encompassing tests and one new encompassing test. Numerical simulations are used to generate the appropriate asymptotic critical values. Monte Carlo simulations are then used to evaluate the size and power of a battery of equal forecast accuracy and encompassing tests, as well as standard F-tests of causality. In these experiments, forecasts from an estimated VAR model are compared to those from a null estimated AR model. The simulation results indicate that McCracken's out-of-sample F-type test of equal accuracy and the encompassing test proposed in this paper can be more powerful than standard F-tests of causality. The Monte Carlo simulations also show that using invalid asymptotic critical values can produce misleading inferences.


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## 1. INTRODUCTION

As evident from recent studies such as Amano and van Norden (1995), Blomberg and Hess (1997), Bram and Ludvigson (1998), Krueger and Kuttner (1996), and Mark (1995), interest often lies in examining whether one variable helps predict another, both in-sample or out-of-sample. The standard in-sample metric is a simple Granger causality test. Out-of-sample predictive ability is usually gauged by first constructing forecasts from models that include and exclude the variable that may have predictive capacity and then testing for equal accuracy or encompassing. Typically, there is concern that in-sample Granger causality tests may lead to overfitting of the model. Out-of-sample forecast comparison is widely viewed as a more stringent test of the relationship between the variables. Moreover, Ashley, Granger, and Schmalensee (1980) argue that it is more in the spirit of their "reasonable" definition of Granger causality to employ post-sample forecast tests than to employ the standard in-sample tests of causality. ${ }^{1}$ According to Ashley, et. al., if forecasts of y from a VAR in x and y are superior to forecasts from an AR model for y , then x carries information about y and hence x causes y .

This paper examines the ability of different post-sample forecast tests to determine whether one variable has predictive ability for another. Particularly, this paper examines the asymptotic and finite-sample properties of tests for equal accuracy and encompassing applied to nested models. Used with nested forecasts from models such as a VAR vs. an AR, the tests can be viewed as Granger causality tests. However, many of the standard tests of equal accuracy and encompassing are designed for forecasts from non-nested, rather than nested, models. Many of the standard test statistics - such as the Diebold and Mariano (1995) equal accuracy and the Harvey, Leybourne, and Newbold (1998) encompassing statistics - fail to converge to the

[^1]standard normal distribution when the models are nested rather than non-nested. ${ }^{2}$ Therefore, the standard asymptotic critical values are invalid with nested models.

This study's analysis of the use of equal accuracy and encompassing tests for nested forecasts complements the non-nested forecast analyses of, among others, Corradi, Swanson, and Olivetti (1998), Diebold and Mariano (1995), Harvey, Leybourne, and Newbold (1997, 1998), West (1996), West and McCracken (1998) and McCracken (1998). In another related analysis, Swanson, Ozyildirim, and Pisu (1996) examine the finite-sample performance - principally, the size - of different Granger causality tests and Diebold-Mariano equal accuracy tests with both stationary and non-stationary data. The equal accuracy tests they consider, however, are all compared against standard asymptotic critical values that are invalid because the models are nested. The same problem applies to the Monte Carlo results of Corradi, et. al. (1998) on how Diebold and Mariano tests perform when applied to models with cointegrating relationships.

Building on McCracken's (1999) results for equal accuracy tests, this paper first derives the asymptotic distributions for a set of standard encompassing tests and one new encompassing test. The standard encompassing tests for which this paper derives asymptotic distributions are the Harvey, et. al. (1998) and Ericsson (1992) statistics. The set of standard statistics also includes the Chong and Hendry (1986) test, which remains asymptotically normal when applied to nested rather than non-nested forecasts. The new test proposed below is a variant of the Harvey, et. al. statistic. As in Corradi, et. al. (1998), McCracken (1999), West (1996), and West and McCracken (1998), the derived distributions of the tests explicitly account for the uncertainty introduced by model estimation. In order to facilitate the use of the limiting distributions derived here, asymptotically valid critical values are generated numerically and

[^2]reported in appendix tables. The equal accuracy tests include an out-of-sample F-type test of equal mean squared error (MSE) developed in McCracken (1999) and the Diebold and Mariano (1995) test of equal MSE, statistics for which McCracken develops the correct asymptotic distributions and provides critical values.

In order to evaluate the finite-sample size and size-adjusted power of these tests we conduct a series of Monte Carlo simulations based on VAR data-generating processes. For comparison, the set of tests considered also includes standard F-tests of Granger causality. In addition, in order to evaluate the extent to which using invalid critical values can produce misleading inferences, results are presented for Diebold and Mariano (1995), Harvey, et. al. (1998), and Ericsson (1992) statistics compared to the distributions that would be appropriate if the forecasts were from non-nested models. To further illustrate how the different tests perform in practical settings, the battery of tests is applied to determining whether the unemployment rate has predictive power for inflation in quarterly U.S. data.

Results summary. Asymptotics. Finite-sample. Monte Carlo simulations show that using invalid asymptotic critical values can produce misleading inferences in small samples. The simulations also indicate that out-of-sample F-type and encompassing tests can be more powerful than standard, in-sample F-tests of causality.

The remainder of the paper will proceed as follows. Section two introduces the notation and general environment under which the forecasts are generated and the tests of forecast accuracy and encompassing are constructed. Section three, and its subsections, introduce the test statistics considered and provide the asymptotic results under the null. In section four we present a collection of Monte Carlo experiments designed to determine the finite-sample size and power properties of the test statistics. Section five contains an empirical application of the tests the
problem of determining whether the unemployment rate has predictive power for inflation in quarterly U.S. data. Section six concludes. All proofs are contained within the Appendix.

## 2. General Environment

In order to present the tests considered we first provide some general notation, describe the forecasting schemes, and present the assumptions under which the asymptotic results are derived. The sample of data $\left\{y_{j}, x_{j}^{\prime}\right\}_{j=1}^{T+1}$ is divided into in-sample and out-of-sample portions. The in-sample observations span 1 to $R$. Letting $P$ denote the number of 1 -step ahead predictions constructed, the out-of-sample observations span $R+1$ through $R+P$. The total number of observations in the sample is then $\mathrm{R}+\mathrm{P}=\mathrm{T}+1$. The largest number of observations used to estimate the model under the forecast schemes considered is $\mathrm{T}=\mathrm{R}+\mathrm{P}-1$.

The scalar variable to be predicted is $y_{t+1}, t=R, \ldots, T$. Forecasts of $y_{t+1}$ are generated using parametric models $\mathrm{g}_{\mathrm{i}}\left(\mathrm{x}_{\mathrm{t}+1}, \beta_{\mathrm{i}}^{*}\right) \equiv \mathrm{g}_{\mathrm{i}, t+1}\left(\beta_{\mathrm{i}}^{*}\right)$ denoted by $\mathrm{i}=1$ and 2, each of which is estimated. Model 2 is the unrestricted model, which nests the restricted model 1. Under the null hypothesis, model 2 includes $k_{2}$ excess parameters. Without loss of generality let $\beta_{2}^{*}=\left(\beta_{1 \times \times k_{1}}^{* *}, 0_{1 \times k_{2}}\right)^{\prime}\left(k_{1}+\mathrm{k}_{2}=\mathrm{k} \times 1\right)$ such that for all $\mathrm{t}, \mathrm{g}_{1, \mathrm{tt1}}\left(\beta_{1}^{*}\right)=\mathrm{g}_{2, \mathrm{t}+1}\left(\beta_{2}^{*}\right)$. Under the alternative hypothesis, the $\mathrm{k}_{2}$ restrictions are not true, and model 2 is correct. Note that while models 1 and 2 take the form of AR and VAR models in the Monte Carlo analysis, the asymptotic results permit the use of nonlinear models.

Following West and McCracken (1998), three forecast schemes are considered. Under the recursive scheme, each model's parameters, $\beta_{\mathrm{i}}^{*} \mathrm{i}=1,2$, are estimated with added data as forecasting moves forward. The first prediction, $g_{i, R+1}\left(\hat{\beta}_{i, R}\right)$, is created using model parameter
estimates $\hat{\beta}_{i, R}$ estimated using data from 1 to $R$, the second prediction $g_{i, R+2}\left(\hat{\beta}_{i, R+1}\right)$ is created using model parameter estimates $\hat{\beta}_{\mathrm{i}, \mathrm{R}+1}$ estimated using data from 1 to $\mathrm{R}+1$, etc. In general, for $t=R, \ldots, T$, the prediction of $y_{t+1}, g_{i, t+1}\left(\hat{\beta}_{i, t}\right)$, from time $t$ is created using model parameter estimates $\hat{\beta}_{\mathrm{i}, \mathrm{t}}$ estimated using data from 1 to t .

Under the rolling forecast scheme, the model is estimated using only the most recent R observations. The first rolling prediction, $\mathrm{g}_{\mathrm{i}, \mathrm{R}+1}\left(\hat{\beta}_{\mathrm{i}, \mathrm{R}}\right)$, is created using model parameter estimates $\hat{\beta}_{i, R}$ estimated using data from 1 to $R$, the second prediction $g_{i, R+2}\left(\hat{\beta}_{i, R+1}\right)$ is created using model parameter estimates $\hat{\beta}_{i, R+1}$ estimated using data from 2 to $R+1$, etc. In general, for $t=R, \ldots, T$, the prediction of $y_{t+1}, g_{i, t+1}\left(\hat{\beta}_{i, t}\right)$, from time $t$ is created using model parameter estimates $\hat{\beta}_{\mathrm{i}, \mathrm{t}}$ estimated using data from $\mathrm{t}-\mathrm{R}+1$ to t . Note that under the rolling scheme the parameter estimates $\hat{\beta}_{\mathrm{i}, \mathrm{t}}$ should also be subscripted by R in order to reflect the size of the sample window. To reduce notation we leave that subscript implicit.

Under the fixed scheme, all forecasts are generated using models estimated with data from 1 to $R$. Hence for each prediction of $y_{t+1}, g_{i, t+1}\left(\hat{\beta}_{i, t}\right)=g_{i, t+1}\left(\hat{\beta}_{i, R}\right)$, from time $t=R, \ldots, T$, the prediction is created using the same model parameter estimate $\hat{\beta}_{\mathrm{i}, \mathrm{t}}=\hat{\beta}_{\mathrm{i}, \mathrm{R}}$ estimated using data from 1 to $R$. As was the case for the rolling scheme, the parameter estimates $\hat{\beta}_{\mathrm{i}, \mathrm{t}}$ under the fixed scheme should also be subscripted by R to reflect the sample window. To reduce notation we also leave this subscript implicit.

For each of the three forecasting schemes, the 1-step ahead forecast errors are $\hat{u}_{1, t+1}=y_{t+1}-g_{1, t+1}\left(\hat{\beta}_{1, t}\right)$ and $\hat{u}_{2, t+1}=y_{t+1}-g_{2, t+1}\left(\hat{\beta}_{2, t}\right)$ for models 1 and 2 , respectively. Using
the two sequences of P forecast errors the out-of-sample tests of forecast accuracy and encompassing are constructed. In all cases the out-of-sample statistics rely on sums of functions of these forecast errors. To simplify notation, for any variable $z_{t}$ we will let $\sum_{t} z_{t}$ denote the summation $\sum_{t=R}^{T} z_{t}$. For example, the mean squared error (MSE) for model i is $\mathrm{MSE}_{\mathrm{i}} \equiv$ $P^{-1} \sum_{t=R}^{T} \hat{u}_{i, t}^{2}=P^{-1} \sum_{t} \hat{u}_{i, t}^{2}$.

Before getting to the assumptions some final notation is needed. Let $\mathrm{g}_{\mathrm{i}, \mathrm{ttl}, \mathrm{\beta}}\left(\beta_{\mathrm{i}}\right)=$ $\frac{\partial}{\partial \beta_{i}} g_{i, t+1}\left(\beta_{i}\right), q_{i, t+1}\left(\beta_{i}\right)=g_{i, t+1, \beta}\left(\beta_{i}\right) g_{i, t+1, \beta}^{\prime}\left(\beta_{i}\right)-\left(y_{t+1}-g_{i, t+1}\left(\beta_{i}\right)\right) \frac{\partial^{2}}{\partial \beta_{i} \partial \beta_{i}^{\prime}} g_{i, t+1}\left(\beta_{i}\right), f_{i, t+1}=$ $\mathrm{f}_{\mathrm{i}, \mathrm{t+1}}\left(\beta_{\mathrm{i}}^{*}\right)$ and $\mathrm{f}_{\mathrm{t}+1}=\mathrm{f}_{2, \mathrm{t+1}}$ for any function f , $\mathrm{h}_{\mathrm{i}, \mathrm{t+1}}\left(\beta_{\mathrm{i}}\right)=\left(\mathrm{y}_{\mathrm{t}+1}-\mathrm{g}_{\mathrm{i}, \mathrm{t+1}}\left(\beta_{\mathrm{i}}\right)\right) \mathrm{g}_{\mathrm{i}, \mathrm{t+1,} \mathrm{\beta}}\left(\beta_{\mathrm{i}}\right), \mathrm{B}_{\mathrm{i}}=$ $\left(\mathrm{Eq}_{\mathrm{i}, \mathrm{t}+1}\right)^{-1}, \mathrm{~W}(\mathrm{~s})$ is a $\left(\mathrm{k}_{2} \times 1\right)$ vector standard Brownian Motion, and for any $(\mathrm{m} \times \mathrm{n})$ matrix A with column vectors $a_{i}$ let $\operatorname{vec}(A)$ denote the $(m n \times 1)$ vector $\left[a_{1}^{\prime}, a_{2}^{\prime}, \ldots, a_{n}^{\prime}\right]^{\prime}$.

Given the definitions and the three forecasting schemes described above, the following five assumptions are those used to derive the limiting distributions of encompassing tests presented in Theorems 3.4, 3.5, and 3.6. The assumptions are also sufficient for the results of McCracken (1999) when MSE is the measure of predictive ability. These assumptions are not intended to be necessary and sufficient, only sufficient. All proofs can be found within the Appendix.

Assumption 1: The parameter estimates $\hat{\beta}_{\mathrm{i}, \mathrm{t}}, \mathrm{i}=1,2, \mathrm{t}=\mathrm{R}, \ldots, \mathrm{T}$, satisfy $\hat{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}=\mathrm{B}_{\mathrm{i}}(\mathrm{t}) \mathrm{H}_{\mathrm{i}}(\mathrm{t})$ where for $\dot{\beta}_{i, t}$ on the line between $\hat{\beta}_{i, t}$ and $\beta_{i}^{*}, B_{i}(t) H_{i}(t)$ equals
$\left(t^{-1} \sum_{j=1}^{t} q_{i, j}\left(\dot{\beta}_{i, t}\right)\right)^{-1}\left(t^{-1} \sum_{j=1}^{t} h_{i, j}\right),\left(R^{-1} \sum_{j=t-R+1}^{t} q_{i, j}\left(\dot{\beta}_{i, t}\right)\right)^{-1}\left(t^{-1} \sum_{j=t-R+1}^{t} h_{i, j}\right)$ and $\left(R^{-1} \sum_{j=1}^{R} q_{i, j}\left(\dot{\beta}_{i, t}\right)\right)^{-1}\left(R^{-1} \sum_{j=1}^{R} h_{i, j}\right)$ respectively for the recursive, rolling and fixed schemes.

This first assumption provides us with one primary piece of information. Analytically it tells us that the parameters are estimated by OLS, NLLS, or maximum likelihood under normality assumptions. In the case where a VAR is being used, the system must be exactly identified and estimated by multivariate OLS. This type of restriction is imposed to insure that the statistics in Theorems 3.4-3.6 are pivotal. As in McCracken (1999), achieving a limiting distribution that does not depend upon the data-generating process requires that the loss function used to estimate the parameters be closely related to the loss function used to measure predictive ability. Each of the statistics in Theorems 3.4-3.6 is in one way or another testing whether the two models have equal mean square errors. In order then to achieve a pivotal statistic the parameters must be estimated using mean square error as the loss function. Although this assumption is restrictive in how the parameters are estimated, it otherwise does not place any restrictions on the type of model. Single and multiple equation models as well as linear and nonlinear models are permitted.

Assumption 2: For $\mathrm{i}=1,2$, (a) $\beta_{\mathrm{i}} \in \Theta_{\mathrm{i}}$, $\Theta_{\mathrm{i}}$ compact, (b) $\mathrm{E}\left[\mathrm{y}_{\mathrm{t}}-\mathrm{g}_{\mathrm{i}, \mathrm{t}}\left(\beta_{\mathrm{i}}\right)\right]^{2}$ is uniquely minimized at $\beta_{\mathrm{i}}^{*} \in \Theta_{\mathrm{i}}$ with $\mathrm{Eq}_{\mathrm{i}, \mathrm{t}}$ nonsingular, (c) In some open neighborhood $\mathrm{N}_{\mathrm{i}}$ around $\beta_{\mathrm{i}}^{*}$, and with probability one $\left[y_{t}-g_{i, t}\left(\beta_{i}\right)\right]^{2}$ is twice continuously differentiable, (d) In the open neighborhood $\mathrm{N}_{\mathrm{i}}$, and for all t there exists a positive constant $\varphi$ and a positive random variable $m_{t}$ such that $\left|q_{i, t}\left(\beta_{i}\right)-q_{i, t}\left(\beta_{i}^{*}\right)\right| \leq m_{t}\left|\beta_{i}-\beta_{i}^{*}\right|^{\varphi}$ with $E m_{t}<\infty$ and $\varphi<\infty$.

Most of Assumption 2 is imposed in order to insure that the parameters are identified and are consistently estimated. It is directly comparable to Theorem (2.1) of Newey and McFadden (1994). The substantive components of this assumption are that the predictive function, $\mathrm{g}_{\mathrm{i}, \mathrm{t}}\left(\beta_{\mathrm{i}}\right)$, is the conditional mean function and that the conditional mean function is twice continuously differentiable.

Assumption 3: Let $U_{t} \equiv\left[h_{t}^{\prime}, \operatorname{vec}\left(h_{t} h_{t}^{\prime}-\sigma^{2} B^{-1}\right)^{\prime}, \operatorname{vec}\left(q_{t}-B^{-1}\right)^{\prime}\right]^{\prime}$. (a) $E U_{t}=0$, (b) $U_{t}$ is uniformly $L^{8}$ bounded, (c) For some $8>d>2, U_{t}$ is strong mixing with coefficients of size $\frac{-8 d}{8-d}$, (d) $\lim _{\mathrm{T} \rightarrow \infty} \mathrm{T}^{-1} \mathrm{E} \sum_{\mathrm{j}=1}^{\mathrm{T}} \mathrm{U}_{\mathrm{j}} \mathrm{U}_{\mathrm{j}}^{\prime}=\Omega<\infty$.

Assumption 4: (a) $E h_{t} h_{t}^{\prime}=\sigma^{2} E q_{t} \equiv \sigma^{2} B^{-1}$, (b) $E\left(h_{t} \mid h_{t-j}, q_{t-j}, j=1,2, \ldots\right)=0$.

Both Assumptions 3 and 4 largely consist of technical conditions sufficient for the application of an invariance principle. Moreover they are sufficient for joint weak convergence of partial sums and averages of these partial sums to Brownian Motion and integrals of these Brownian Motion. Assumption 3 is directly comparable to the assumptions in Hansen (1992) and hence we are able to apply his Theorems (2.1) and (3.1).

The reasons for imposing Assumption 4 are much the same as Assumption 1. In order to insure that the limiting distribution does not depend upon the underlying data generating process we must impose some extra conditions. Here we essentially require that the disturbances form a conditionally homoskedastic martingale difference sequence.

Assumption 5: $\lim _{\mathrm{T} \rightarrow \infty} \mathrm{P} / \mathrm{R}=\pi, 0<\pi<\infty, \lambda \equiv(1+\pi)^{-1}$.

This final assumption introduces the means by which the asymptotics are achieved. As in Hoffman and Pagan (1989), West (1996), and White (1998) the limiting distribution results are derived by imposing a slightly stronger condition than simply that the sample size, $\mathrm{T}+1$, becomes arbitrarily large. Here we impose the additional condition that both the number of in-sample (R) and out-of-sample (P) observations also become arbitrarily large at the same rate. In this way we insure that the parameters estimated in-sample and certain out-of-sample averages are both consistent estimators of their population level analogs.

It should be noted that the assumption that $\pi$ is bounded from above and below is not trivial. Certainly in practice $\mathrm{P} / \mathrm{R}$ will be bounded but whether it is near zero or much larger could affect how well the asymptotic approximation behaves in finite samples. If $\mathrm{P} / \mathrm{R}$ is small then the parameters may be well estimated but, for example, the out-of-sample MSE will be estimated by too few observations for the empirical MSE to form a strong estimate of the population MSE. If $\mathrm{P} / \mathrm{R}$ is large then we cannot expect the parameters to be well approximated, especially under the fixed scheme, and thus regardless of the out-of-sample size the empirical MSE may form a poor estimate of the population MSE. Hence when choosing how to split the sample into in-sample and out-of-sample portions one should consider choosing a split that leaves a sizable number of observations in each of the in-sample and out-of-sample portions.

Unless otherwise noted, the notation and assumptions presented in this section hold throughout the remainder of the paper.

## 3. TESTS

While Ashley, et. al. (1980) specifically advocate using tests of equal forecast accuracy to examine causality, given their definition of causality, any test designed to examine whether x carries information about y could reasonably be used. Accordingly, this paper considers the ability of simple Granger causality tests, equal forecast accuracy tests, and forecast encompassing tests to determine whether one variable has predictive power for another. Since a large number of tests for equal accuracy and encompassing already exist, for tractability the set examined is limited based on considerations of computational simplicity and performance in the non-nested investigations of Clark (1999), Diebold and Mariano (1995), and Harvey, Leybourne, and Newbold (1997, 1998). The set of tests includes: simple Granger causality statistics; McCracken's (1999) out-of-sample F-type test for equal MSE; Diebold and Mariano's statistic for equal MSE; the Harvey, et. al. (1998) encompassing test; the Ericsson (1992) encompassing statistic; a modified, asymptotically valid version of the Harvey, et. al. test developed below; and the Chong and Hendry (1986) encompassing statistic.

In the results below, the tests are applied to 1 -step ahead forecasts. When multi-step forecasts from nested models are used, the asymptotic distributions of the tests appear to depend on the parameters of the data-generating process. For practical purposes, such dependence eliminates the possibility of using asymptotic approximations to test for equal accuracy or encompassing. Lutkepohl and Burda (1997) note similar difficulties associated with in-sample tests involving multi-step forecasts. Our belief is that researchers comfortable with assuming linear models should be adequately served by tests based on 1-step ahead forecasts. With linear models, multi-step forecasts are simply linear combinations of 1 -step ahead forecasts. Hence there does not appear to be any reason to expect tests based on multi-step forecasts to be better at determining predictive power than tests based on 1-step ahead forecasts.

### 3.1 Simple Granger Causality (GC) Tests

The emphasis of this paper is on using ex-ante forecasts, rather than ex-post predictions, to test for forecast accuracy and encompassing. Even so, we include simple F-type Granger causality tests in the Monte Carlo simulations. We do so because they are the most commonly used statistics for testing for causality. We construct these statistics using both in-sample and out-of-sample data, using R observations in the former case and P observations in the latter.

In the results of section 4, the tests are computed as simple F-statistics for exclusion restrictions. ${ }^{3}$ When lag lengths are set using data-based procedures, the out-of-sample GC tests rely on the lag order determined using the in-sample data. While standard GC tests are rarely applied to out-of-sample data, they are no less valid for the purpose of testing causality in out-ofsample data than are forecast accuracy or encompassing tests. Like out-of-sample accuracy and encompassing tests, simple out-of-sample GC tests may be less prone to spurious results due to overfitting than are in-sample causality tests.

### 3.2 The Out-of-Sample F (OOS F) Test

McCracken (1999) develops an out-of-sample F-type test of equal MSE, given by

$$
\begin{equation*}
\text { OOS } F=P \cdot \frac{M S E_{1}-M S E_{2}}{M S E_{2}}=P \cdot \frac{P^{-1} \sum_{t} \hat{u}_{1, t+1}^{2}-P^{-1} \sum_{t} \hat{u}_{2, t+1}^{2}}{P^{-1} \sum_{t} \hat{u}_{2, t+1}^{2}} . \tag{1}
\end{equation*}
$$

This statistic is comparable to the simple F-test form of the standard in-sample GC test and offers the advantage of being particularly simple to compute if forecast summary statistics are already
available. Using assumptions broadly similar to those used in this paper, McCracken shows that the OOS F statistic converges to a function of stochastic integrals of quadratics of Brownian motion. The limiting distribution under the null, which varies with the forecasting scheme, is a function of the ratio of post-sample to in-sample observations, $\pi$, and excess parameters, $\mathrm{k}_{2}$, in model 2.

In the results of section 4, the test statistic is compared against asymptotically valid critical values tabulated by McCracken. Since the models are nested, the null hypothesis is $\mathrm{MSE}_{1} \leq \mathrm{MSE}_{2}$, and the alternative is $\mathrm{MSE}_{1}>\mathrm{MSE}_{2}$. The alternative is one-sided because, if the restrictions imposed on model 1 are not true, there is no reason to expect forecasts from model 1 to be superior to those from model 2 .

### 3.3 The Diebold-Mariano (DM) Test

Define $d_{t+1}=\hat{u}_{1, t+1}^{2}-\hat{u}_{2, t+1}^{2}$ and $\overline{\mathrm{d}}=\mathrm{P}^{-1} \sum_{\mathrm{t}} \mathrm{d}_{\mathrm{t}+1}=\mathrm{MSE}_{1}-\mathrm{MSE}_{2}$. The Diebold and

Mariano (1995) test for equal MSE is formed as

$$
\begin{equation*}
D M=\frac{M S E_{1}-M S E_{2}}{\sqrt{\hat{\operatorname{var}}\left(M S E_{1}-M S E_{2}\right)}}=\frac{\bar{d}}{\sqrt{\hat{\operatorname{var}}(\bar{d})}}=\frac{\bar{d}}{\sqrt{P^{-2} \sum_{t}\left(d_{t+1}-\bar{d}\right)^{2}}} . \tag{2}
\end{equation*}
$$

While the DM statistic is asymptotically standard normal when applied to non-nested forecasts (see Diebold and Mariano (1995) and West (1996)), the asymptotic distribution is non-normal when the forecasts are nested under the null hypothesis.

The root of the problem is that, under the null, $g_{1, t+1}\left(\beta_{1}^{*}\right)=g_{2, t+1}\left(\beta_{2}^{*}\right)$ and thus both $u_{1, t+1}=y_{t+1}-g_{1, t+1}\left(\beta_{1}^{*}\right) \equiv u_{t+1}$ and $u_{2, t+1}=y_{t+1}-g_{2, t+1}\left(\beta_{2}^{*}\right)=y_{t+1}-g_{1, t+1}\left(\beta_{1}^{*}\right) \equiv u_{t+1}$. Hence, at

[^3]least heuristically, asymptotically the difference in squared forecast errors is exactly 0 , with 0 variance. The usual DM test - in which the statistic is compared against the standard normal distribution - is therefore asymptotically invalid. McCracken (1999) shows that, for forecasts from nested models, the DM test statistic converges to a function of stochastic integrals of quadratics of Brownian motion. This limiting distribution depends on the forecasting scheme, $\pi$, and $\mathrm{k}_{2}$.

In the results of section 4, the test statistic is compared against asymptotically valid critical values tabulated by McCracken. Because models 1 and 2 are nested rather than nonnested, the alternative hypothesis is one-sided instead of two-sided. Under the null, $\mathrm{MSE}_{1} \leq \mathrm{MSE}_{2} ;$ under the alternative, $\mathrm{MSE}_{1}>\mathrm{MSE}_{2}$.

To evaluate how using invalid asymptotic critical values would affect inference, results are also reported for a version of the test comparing the DM statistic against the $\mathrm{t}_{\mathrm{P}-1}$ distribution. While the DM statistic is asymptotically standard normal when the forecasts are non-nested, Harvey, et. al. (1997) find that comparing the $D M$ statistic against the $t_{P-1}$ distribution yields better small-sample properties. In the reported results, the invalid version of the test (but not the asymptotically valid version) also incorporates an adjustment, developed in Harvey, et. al (1997), to correct for bias in the estimated variance of $\overline{\mathrm{d}}$. This adjustment takes the form of multiplying the test statistic (2) by $\sqrt{(\mathrm{P}-1) / \mathrm{P}}$.

### 3.4 The Harvey, et. al. (HLN) Test

Harvey, et. al. (1998) use the basic methodology of Diebold and Mariano (1995) to develop a test of forecast encompassing drawn from the conditional efficiency framework of

Granger and Newbold (1973) and Nelson (1972). ${ }^{4}$ Conditional efficiency is tested with the
OLS-based regression

$$
\begin{equation*}
\hat{u}_{1, t+1}=\lambda\left(\hat{u}_{1, t+1}-\hat{u}_{2, t+1}\right)+\eta_{t+1} . \tag{3}
\end{equation*}
$$

If $\lambda=0$, forecast 2 carries no useful information not already in forecast 1 , so forecast 1 is conditionally efficient. If $\lambda>0$, forecasts from model 2 do carry information not already in forecasts from model 1.

Harvey, et. al. (1998) propose testing encompassing with a t-statistic for the covariance between $\hat{u}_{1, t+1}$ and $\hat{u}_{1, t+1}-\hat{u}_{2, t+1}$ rather than with a $t$-statistic for the regression coefficien $\hat{\imath}$. Let $c_{t+1}=\hat{u}_{1, t+1}\left(\hat{u}_{1, t+1}-\hat{u}_{2, t+1}\right)=\hat{u}_{1, t+1}^{2}-\hat{u}_{1, t+1} \hat{u}_{2, t+1}$ and $\overline{\mathrm{c}}=\mathrm{P}^{-1} \sum_{\mathrm{t}} \mathrm{c}_{\mathrm{t}}$. The Harvey, et. al. encompassing test is formed as

$$
\begin{equation*}
H L N=\frac{\bar{c}}{\sqrt{\hat{\operatorname{var}}(\bar{c})}}=\frac{\bar{c}}{\sqrt{P^{-2} \sum_{t}\left(c_{t}-\bar{c}\right)^{2}}}=P^{1 / 2} \cdot \frac{P^{-1} \sum_{t} \hat{u}_{1, t+1}^{2}-P^{-1} \sum_{t} \hat{u}_{1, t+1} \hat{u}_{2, t+1}}{\sqrt{P^{-1} \sum_{t}\left\{\left(\hat{u}_{1, t+1}^{2}-\hat{u}_{1, t+1} \hat{u}_{2, t+1}\right)-\bar{c}\right\}^{2}}} . \tag{4}
\end{equation*}
$$

Under the null that model 1 forecast encompasses model 2, the covariance between $u_{1, t}$ and $u_{1, t}-u_{2, t}$ will be less than or equal to 0 , while under the alternative that model 2 contains added information, the covariance should be positive. The test is one-sided when applied to either nested or non-nested forecasts.

While the HLN statistic is asymptotically standard normal when applied to non-nested forecasts, the asymptotic distribution is non-normal when the forecasts are nested under the null. The actual limiting distribution is provided in Theorem 3.4.

[^4]Theorem 3.4: For HLN defined in (4), HLN $\rightarrow_{\mathrm{d}} \frac{\chi_{1}}{\left(\chi_{2}\right)^{0.5}}$ where $\chi_{1}$ equals

$$
\begin{array}{ll}
\int_{\lambda}^{1} s^{-1} \mathrm{~W}^{\prime}(\mathrm{s}) \mathrm{dW}(\mathrm{~s}) & \text { for the recursive scheme }, \\
\lambda^{-1}\{\mathrm{~W}(1)-\mathrm{W}(\lambda)\}^{\prime} \mathrm{W}(\lambda) & \text { for the fixed scheme }, \\
\lambda^{-1} \int_{\lambda}^{1}\{\mathrm{~W}(\mathrm{~s})-\mathrm{W}(\mathrm{~s}-\lambda)\}^{\prime} \mathrm{dW}(\mathrm{~s}) & \text { for the rolling scheme },
\end{array}
$$

and $\chi_{2}$ equals

| $\int_{\lambda}^{1} s^{-2} W^{\prime}(s) W(s) d s$ | for the recursive scheme, |
| :--- | :---: |
| $\pi \lambda^{-1} W^{\prime}(\lambda) W(\lambda)$ | for the fixed scheme, |
| $\lambda^{-2} \int_{\lambda}^{1}\{W(s)-W(s-\lambda)\}^{\prime}\{W(s)-W(s-\lambda)\} d s$ | for the rolling scheme. |

There are a couple things to notice about Theorem 3.4. The first is that for each forecasting scheme the statistic is pivotal. This fact is not particularly useful if asymptotic critical values, associated with the limiting distributions, are used to construct asymptotically valid tests. If the bootstrap is used, as in Ashley (1998), then we know from Hall (1992) that the bootstrap provides refinements to first order asymptotics and hence in finite samples may provide more accurate inference.

Though the null limiting distributions do not depend upon the data generating process itself, the distributions are dependent upon two parameters. The first is the number of excess parameters $\mathrm{k}_{2}$. It arises since the vector Brownian Motion, W(s), is $\left(\mathrm{k}_{2} \times 1\right)$. The second parameter, $\pi$, also affects the null limiting distribution. It affects the limiting distribution in two
and 2 will have a smaller MSE than forecast 1 unless the covariance between $\hat{\mathrm{e}}_{1, t+1}$ and $\hat{\mathrm{e}}_{1, t+1}-\hat{\mathrm{e}}_{2, t+1}$ and, equivalently, the coefficient $\lambda$, are 0 .
ways. It directly affects the weights on each of the components of the statistics (recall that $\lambda=$ $\left.(1+\pi)^{-1}\right)$. It also affects the range of integration on each of the stochastic integrals through $\lambda$.

Since the limiting distribution of the HLN statistic is nonstandard (i.e. neither normal nor chi-square) we provide asymptotically valid critical values in Tables A1-A3. These were generated numerically using the limiting distribution in Theorem 3.4 and hence can be considered estimates of the true asymptotic critical values. The reported critical values are the $90^{\text {th }}, 95^{\text {th }}$ and $99^{\text {th }}$ percentiles of 5000 independent draws from the distribution of $\frac{\chi_{1}}{\left(\chi_{2}\right)^{0.5}}$ for a given value of $k_{2}$ and $\pi$. Generating these draws proceeded as follows. Weights that depend upon $\pi$ were estimated in the obvious way using $\hat{\pi}=P / R$. The necessary $\mathrm{k}_{2}$ Brownian Motions were simulated as random walks each using an independent sequence of 10,000 i.i.d. $\mathrm{N}\left(0, \mathrm{~T}^{0.5}\right)$ increments. The integrals were emulated by summing the relevant weighted quadratics of the random walks from the $\mathrm{R}+1^{\text {st }}$ observation to the $\mathrm{T}^{\text {th }}$ observation. The random number generator was seeded so that all $k_{2}$ and $\pi$ pairs and all sampling schemes use the same 5000 draws of $k_{2}$ sequences of 10,000 i.i.d. $\mathrm{N}\left(0, \mathrm{~T}^{-0.5}\right)$ increments.

A brief listing of critical values is provided in Tables A1, A2, and A3. Each of the tables corresponds to either the recursive, rolling, or fixed forecasting scheme. Within each table there are 330 critical values. Each of these correspond to one permutation of three parameters: $\mathrm{k}_{2}=$ $\{1,2,3, \ldots, 9,10\}, \pi=\{0.1,0.2,0.4, \ldots, 1.0,1.2, \ldots, 2.0\}$ and nominal size of the test $=\{0.01$, $0.05,0.10\}$. Tables that allow for larger values of both $\mathrm{k}_{2}$ and $\pi$ are available upon request.

In the results of section 4, the HLN statistic is compared against the asymptotically valid critical values tabulated in Tables A1-A3. To evaluate how using invalid asymptotic critical values would affect inference, results are also reported for a version of the test comparing the

HLN statistic against the $\mathrm{t}_{\mathrm{P}-1}$ distribution. For non-nested models, Harvey, et. al. (1998) find that comparing the HLN statistic against the $\mathrm{t}_{\mathrm{P}-1}$ distribution, rather than the standard normal, yields better small-sample properties. In the reported results, the invalid version of the test (but not the asymptotically valid version) also incorporates an adjustment, developed in Harvey, et. al (1997), to correct for bias in the estimated variance of $\overline{\mathrm{d}}$. This adjustment takes the form of multiplying the test statistic (4) by $\sqrt{(\mathrm{P}-1) / \mathrm{P}}$.

### 3.5 A New Encompassing (CM) Test

As discussed below, Monte Carlo simulations suggest that the denominators of tests like the DM statistic (2) and the HLN statistic (4) adversely affect the small-sample properties of the tests. The denominator of the HLN statistic, for example, is the sample variance of $c_{t}$ (normalized by P ), which is asymptotically equal to 0 . In parallel to the OOS F test, this paper proposes a variant of the HLN statistic in which $\overline{\mathrm{c}}$ is scaled by the variance of one of the forecast errors rather than an estimate of the variance of $\overline{\mathrm{c}}$.

This statistic, which we will refer to as the CM statistic, takes the form

$$
\begin{equation*}
C M=P \cdot \frac{\bar{c}}{M S E_{2}}=P \cdot \frac{P^{-1} \sum_{t} \hat{u}_{1, t+1}^{2}-P^{-1} \sum_{t} \hat{u}_{1, t+1} \hat{u}_{2, t+1}}{P^{-1} \sum_{t} \hat{u}_{2, t+1}^{2}} . \tag{5}
\end{equation*}
$$

The numerator is the object of interest in the HLN test - the covariance between $u_{1, t}$ and $u_{1, t}-u_{2, t}$. The denominator, $\mathrm{MSE}_{2}$, serves as a scale correction. As was the case for the HLN statistic, the limiting distribution is non-normal when the forecasts are nested under the null. The actual limiting distribution is provided in Theorem 3.5.

Theorem 3.5: For CM defined in (5) and $\chi_{1}$ defined in Theorem 3.4, CM $\rightarrow_{d} \chi_{1}$.

Given Theorem 3.4, this result is not surprising. The sole difference between the HLN and CM statistics is the denominator. Hence we expect their limiting distributions to be somewhat related. As was the case for the HLN statistic, the limiting distribution is pivotal and relies upon the parameters $\mathrm{k}_{2}$ and $\pi$.

In the results of section 4, the CM statistic is compared against asymptotically valid critical values tabulated in Tables A4-A6. As was done for Tables A1-A3, these were generated numerically using the limiting distribution in Theorem 3.5 and hence can be considered estimates of the true asymptotic critical values. The numerical methods used to construct 5000 independent draws from the distribution of $\chi_{1}$ were identical to those used to construct Tables A1-A3. Moreover the random number generator was seeded so that the same $\chi_{1}$ values were used in the construction of both Tables A1-A3 and A4-A6. Tables A4-A6 contain the same 330 permutations of $\mathrm{k}_{2}, \pi$ and nominal size that are used in Tables A1-A3. Tables that allow for larger values of both $\mathrm{k}_{2}$ and $\pi$ are available upon request.

### 3.6 The Ericsson (ERIC) Test

Ericsson's (1992) forecast-differential encompassing test takes the same form as the conditional efficiency regression presented above: ${ }^{5}$

$$
\begin{equation*}
\hat{u}_{1, t+1}=\lambda\left(\hat{u}_{1, t+1}-\hat{u}_{2, t+1}\right)+\eta_{t+1} . \tag{6}
\end{equation*}
$$

[^5]The test statistic is simply the $t$-statistic for the OLS-based regression coefficient $\hat{\lambda}$, which can be expressed as

$$
\begin{equation*}
\text { ERIC }=\frac{\mathrm{P}^{1 / 2} \mathrm{a}_{0, \mathrm{~T}}}{\left[\mathrm{a}_{1, \mathrm{~T}} \mathrm{a}_{2, \mathrm{~T}}-\mathrm{a}_{0, \mathrm{~T}}^{2}\right]^{0.5}} \tag{7}
\end{equation*}
$$

where $a_{0, T}=P^{-1} \sum_{t} \hat{u}_{1, t+1}\left(\hat{u}_{1, t+1}-\hat{u}_{2, t+1}\right), a_{1, T}=P^{-1} \sum_{t}\left(\hat{u}_{1, t+1}-\hat{u}_{2, t+1}\right)^{2}$ and $a_{2, T}=P^{-1} \sum_{t} \hat{u}_{1, t+1}^{2}$. Under the null that model 1 forecast encompasses model 2, the covariance between $u_{1, t}$ and $u_{1, t}-u_{2, t}$ will be less than or equal to 0 , while under the alternative that model 2 contains added information, the covariance should be positive. The test is one-sided when applied to either nested or non-nested forecasts.

Once again the ERIC statistic is asymptotically standard normal when applied to nonnested forecasts but the asymptotic distribution is non-normal when the forecasts are nested under the null. The actual limiting distribution is provided in Theorem 3.6.

Theorem 3.6: For ERIC defined in (7) and $\frac{\chi_{1}}{\left(\chi_{2}\right)^{0.5}}$ defined in Theorem 3.4, ERIC $\rightarrow_{d} \frac{\chi_{1}}{\left(\chi_{2}\right)^{0.5}}$.

In Theorem 3.6 we find that the ERIC and HLN statistics have the same limiting distribution under the null. ${ }^{6}$ Hence we can use Tables A1-A3 to construct asymptotically valid tests of forecast encompassing when the ERIC statistic is used. It should be mentioned however, that this does not imply that the two statistics will have similar finite sample properties. It is for this reason that we include both the HLN and ERIC statistics in the Monte Carlo experiments of section 4.

In the results of section 4, the ERIC statistic is compared against asymptotically valid critical values tabulated in Tables A1-A3. To evaluate how using invalid asymptotic critical values would affect inference, results are also reported for a version of the test comparing the ERIC statistic against the standard normal distribution.

### 3.7 The Chong-Hendry (CH) Test

Under the null that the restrictions on model 2 are correct, model 1 forecast encompasses model 2. The Chong and Hendry (1986) test of encompassing is formed as the $t$-statistic on $\hat{\alpha}$ from the OLS-based regression

$$
\begin{equation*}
\hat{u}_{1, t+1}=\alpha g_{2, t+1}\left(\hat{\beta}_{2, t}\right)+n_{t+1}, \tag{8}
\end{equation*}
$$

where $g_{2, t+1}\left(\hat{\beta}_{2, t}\right)$ denotes the model 2 forecast. ${ }^{7}$ It follows from West and McCracken (1998) that the CH statistic is asymptotically standard normal even when the models considered are nested. Accordingly, the t-statistic on $\hat{\alpha}$ is compared against the standard normal distribution. As with the DM, HLN, and ERIC statistics, to allow for non-normal data, the estimated variance of $\hat{\alpha}$ is robust to heteroskedasticity. Since the nesting of the models has no clear implications for the sign of $\hat{\alpha}$, the null $\alpha=0$ is tested against a two-sided alternative.

## 4. MONTE CARLO RESULTS

Results on the small-sample properties of the tests described in section 3 are generated using a bivariate VAR data generating process, with forecasts of the variable of interest from an

[^6]estimated AR model (model 1) compared to forecasts from a VAR (model 2). The presented results are based on data generated from the normal distribution. The results are essentially unchanged when data are generated from a heavier-tailed distribution, suggested by Diebold and Mariano (1995), in which one forecast error follows a $t_{6}$ distribution and the other is a linear combination of $t_{6}$ variables.

### 4.1 Experiment Design

In the presented results (currently), data are generated using one artificial VAR(1) model and one empirical VAR(2) model. The artificial VAR(1) takes the form

$$
\begin{align*}
& y_{t}=0.3 y_{t-1}+b x_{t-1}+u_{y, t}  \tag{9-10}\\
& x_{t}=0.5 x_{t-1}+u_{x, t},
\end{align*}
$$

where $y_{t}$ is the variable to be forecast and $x_{t}$ is an auxiliary variable. The error terms are independent standard normal variables. To evaluate size in finite samples, the coefficient $b$ is set at 0 . To evaluate power, $b$ is set at $0.1,0.2$, and 0.4 . Simulations based on VAR(2) models taking a comparable form, and simulations based on the trivariate stationary $\operatorname{VAR}(1)$ and VAR(3) models of Swanson, et. al. (1996), produced results in line with those from the bivariate VAR(1).

Alternative models. I. Models that generate larger size biases for in-sample GC tests due to pure pre-test bias effects (models with just much richer dynamics?). II. Misspecified models: (a) $\operatorname{A~VAR}(2)$ in which the true model is an $\operatorname{AR}(2)$ in $y$ and $x(t-1)$ is strongly correlated with $y(t-$ 2). (b) Forecasts from bivariate VAR and AR when the true model is trivariate. (c) Forecasts from VAR and AR when the true model is a VARMA.

The empirical VAR is fit from quarterly data on the change in core CPI inflation and the change in the prime-age male unemployment rate, where the change in core inflation is the variable to be forecast. While the integration orders of these data are admittedly debatable, the use of changes is based on the results of unit root tests and produces autoregressive roots well within the unit circle. Consistent with the empirical application considered in section 5, the models are fit exclusively with in-sample data that span 1958:Q3-1987:Q1. ${ }^{8}$ Under the null that unemployment does not affect inflation, the estimated model used in a size experiment is

$$
\begin{align*}
& \Delta \operatorname{Infl}=.024-.288 \Delta \operatorname{Infl}_{\mathrm{t}-1}-.237 \Delta \operatorname{Infl}_{\mathrm{t}-2}+\mathrm{u}_{\mathrm{t}}  \tag{11-12}\\
& \Delta \mathrm{Unemp}=-.009+.057 \Delta \operatorname{Infl}_{\mathrm{t}-1}+.015 \Delta \operatorname{Infl}_{\mathrm{t}-2}+.703 \Delta \operatorname{Unemp}_{\mathrm{t}-1}-.182 \Delta \operatorname{Unemp}_{\mathrm{t}-2}+\mathrm{v}_{\mathrm{t}} \\
& \operatorname{var}\left(\mathrm{u}_{\mathrm{t}}\right)=2.795, \operatorname{var}\left(\mathrm{v}_{\mathrm{t}}\right)=.107, \operatorname{cov}\left(\mathrm{u}_{\mathrm{t}}, \mathrm{v}_{\mathrm{t}}\right)=-.084 .
\end{align*}
$$

With unemployment affecting inflation, the estimated model used in a power experiment is

$$
\begin{align*}
& \Delta \operatorname{Infl}=.033-.391 \Delta \operatorname{Infl}_{\mathrm{t}-1}-.266 \Delta \operatorname{Infl}_{\mathrm{t}-2}-1.207 \Delta \mathrm{Unemp}_{\mathrm{t}-1}-.137 \Delta \operatorname{Unemp}_{\mathrm{t}-2}+\mathrm{u}_{\mathrm{t}}  \tag{13-14}\\
& \Delta \operatorname{Unemp}=-.009+.057 \Delta \operatorname{Infl}_{\mathrm{t}-1}+.015 \Delta \operatorname{Infl}_{\mathrm{t}-2}+.703 \Delta \operatorname{Unemp}_{\mathrm{t}-1}-.182 \Delta \operatorname{Unemp}_{\mathrm{t}-2}+\mathrm{v}_{\mathrm{t}} \\
& \operatorname{var}\left(\mathrm{u}_{\mathrm{t}}\right)=2.519, \operatorname{var}\left(\mathrm{v}_{\mathrm{t}}\right)=.107, \operatorname{cov}\left(\mathrm{u}_{\mathrm{t}}, \mathrm{v}_{\mathrm{t}}\right)=-.084 .
\end{align*}
$$

The lag lengths of both models were selected to minimize the Akaike criterion, allowing a maximum of four lags.

Letting R denote the number of in-sample observations and P represent the number of predictions, Monte Carlo methods are used to generate a total of $\mathrm{R}+\mathrm{P}+4$ observations. ${ }^{9}$ The additional four observations generated allow for data-determined lag lengths in the forecasting models estimated in each simulation. Letting $L$ denote the lag length of the data-generating

[^7]process (DGP), the first $L$ observations are generated by drawing from the unconditional normal distribution implied by the model parameterization. The remaining $\mathrm{R}+\mathrm{P}+4-\mathrm{L}$ observations are constructed using the autoregressive model structure and draws of the error terms from the normal distribution.

With observations 1 through 4 reserved as initial observations necessary to allow for as many as four lags in the estimated models, a VAR in y and x (or $\Delta \mathrm{Infl}$ and $\Delta \mathrm{Unemp}$ ) and an AR model for y (or $\Delta \mathrm{Infl}$ ) are fit over the in-sample period spanning observations 5 through $\mathrm{R}+4$. In the interest of brevity the lag length of each estimated model was set at the "true" order, L, of the data generating process. ${ }^{10}$ Results for forecasts based on lags set at the order minimizing the in-sample Akaike criterion for the VAR or the AR model are essentially the same. ${ }^{11}$ In one unsurprising exception, the in-sample GC test tends to have slightly greater size and lower power than the presented results when the lag length is set to minimize the in-sample Akaike criterion for the VAR. Observations $\mathrm{R}+5$ through $\mathrm{R}+\mathrm{P}+4$ are then used to form P 1-step ahead forecasts. The first forecast is for period $R+4$; the last is for period $\mathrm{R}+\mathrm{P}+4$. For brevity,

[^8]results are only presented for recursive forecasts, as the basic conclusions are essentially the same for rolling and fixed forecasts. ${ }^{12}$

Results are reported for simple, empirically relevant combinations of P and R such that $\hat{\pi} \equiv \mathrm{P} / \mathrm{R}$ takes a value of $0.1,0.2,0.4,0.6,1.0$, or 2.0 . Specifically, in one set of experiments based on the artificial $\operatorname{VAR}(1), R=100$ and $P=10,20,40,60,100$, and 200. In another set using the $\operatorname{VAR}(1), \mathrm{R}=200$ and $\mathrm{P}=20,40,80,120,200$, and 400 . In experiments based on the inflation-unemployment model, as suggested above P and R are chosen to be consistent with the empirical application considered in section 5. Particularly, $R=115$ and $P=46$, for which $\hat{\pi}=0.4$.

### 4.2 Size Results

Table 1 presents the empirical sizes of Granger causality, equal accuracy, and encompassing tests for data from the $\operatorname{VAR}(1)$ of equations (9)-(10), using a nominal size of $10 \%$. The general results are the same at the nominal size of 5\%. In these size experiments, data are generated imposing the null of $b=0$, under which the AR and VAR forecasts of $y$ have equal MSE (asymptotically), and the AR forecast encompasses the VAR forecast.

Four general results are evident from Table 1. First, OOS F and CM tests perform quite well, suffering only slight size distortions. For example, when $R=100$ and $P=20$, the empirical sizes of the OOS F and CM tests are $10.7 \%$ and $11.0 \%$ respectively. Given R, any distortions in the OOS F and CM tests generally decline as P rises. Second, the asymptotically valid versions of the DM and ERIC statistics and the CH test are modestly oversized in finite

[^9]samples. For example, when $\mathrm{R}=100$ and $\mathrm{P}=20$, the empirical sizes of the asymptotically valid DM, ERIC, and CH tests are $13.5 \%, 14.2 \%$, and $15.5 \%$, respectively. The distortions decline as P rises for a given $\mathrm{R} .{ }^{13}$ With $\mathrm{R}=100$ and $\mathrm{P}=200$, for instance, the ERIC test is essentially correctly sized, rejecting the null in $10.4 \%$ of the simulations.

The third general result is that comparing the DM, HLN, and ERIC tests against invalid asymptotic critical values will generally lead to too-infrequent rejections, the DM test more so than the HLN test and the HLN test somewhat more so than the ERIC test. In the cases of the DM and HLN statistics, using the incorrect asymptotic distribution causes the tests to be undersized for all sample sizes, and the tests become more undersized as P rises given R . For instance, with $\mathrm{R}=100$ and $\mathrm{P}=20$, the DM and HLN tests reject the null in, respectively, $5.5 \%$ and $8.3 \%$ of the simulations. With P increased to 40 , the DM and HLN sizes fall to $3.8 \%$ and $7.4 \%$, respectively. In the case of the ERIC statistic, the invalid version of the test is oversized for very small samples but undersized for larger samples. With $R=100$, for instance, the size of the test falls from $13.5 \%$ when $\mathrm{P}=10$ to $6.6 \%$ when $\mathrm{P}=100$.

Finally, simple GC tests are sometimes slightly oversized when the number of observations is small, but about correctly sized otherwise. The out-of-sample GC test used with $\mathrm{P}=20$, for example, has an empirical size of $11.6 \%$, and the in-sample GC test with $\mathrm{R}=100$ has size of essentially $10 \%$. While not shown in the interest of brevity, when the model lags are chosen to minimize the Akaike criterion for the in-sample VAR, the in-sample GC test suffers modest size distortions, while the size of the out-of-sample GC test is about the same as when the

[^10]lag is fixed at the DGP order. ${ }^{14}$ With $\mathrm{R}=100$ and $\mathrm{P}=20$, setting the lags of the AR and VAR models at the optimal VAR lag yields an in-sample GC test size of 13.7 percent, up from 10.4 percent in the fixed-lag results. The out-of-sample GC test size is $11.8 \%$ and $11.6 \%$ with the optimal VAR lag and fixed lag, respectively.

Table 2 presents size results based on the restricted VAR(2) model for the changes in core inflation and unemployment, equations (11) and (12). In this size experiment, data are generated imposing the null that unemployment does not affect inflation. This implies that AR and VAR forecasts of $\Delta$ Infl have equal MSE (asymptotically), and that the AR forecast encompasses the VAR forecast. Using this empirical model produces results the same as those for the artificial VAR(1). Again, the performance of the OOS F and CM tests is quite good, with both each essentially correctly sized. The asymptotically valid versions of the DM and ERIC statistics and the CH test are subject to modestly larger distortions. Comparing the DM, HLN, and ERIC tests against invalid asymptotic critical values continues to produce too-infrequent rejections, with the DM test more undersized than the HLN or ERIC tests. Finally, for the R and P combination used in this experiment, standard GC tests are about correctly sized when the lag length is set at the true order. In results not reported, however, the in-sample GC test is still subject to modest distortions when the lag length is determined with data-based criteria.

Interpretation/explanation of results.

### 4.3 Power Results

Tables 3-5 present results on the power of simple Granger causality, equal accuracy, and encompassing tests for data from the simple $\operatorname{VAR}(1)$, equations (9)-(10). In these power

[^11]experiments, data are generated using $\mathrm{b}=0.1,0.2$, and 0.4 , so VAR forecasts of y have lower MSE than AR forecasts, and the AR forecast does not encompass the VAR forecast. Because the tests are, to varying degrees, subject to size distortions, the reported power figures are based on empirical critical values and therefore size-adjusted. ${ }^{15}$ With empirical rather than asymptotic critical values used, there is no distinction between the valid and invalid versions of the DM, HLN, and ERIC tests. The size of the tests is $10 \%$; using 5\% produces essentially the same results. For the OOS F, DM, CM, HLN, and ERIC tests, which are one-sided, the null is rejected if the test statistic is greater than the $90 \%$ fractile of the statistic in the corresponding size experiment (for the same R and P ) with $\mathrm{b}=0$. The same applies to the GC tests. For the CH test, which is two-sided, the null is rejected if the test statistic lies outside the 5\% and $95 \%$ fractiles of the empirical distribution generated in the corresponding size experiment.

Several general results are evident in Tables 3-5. First, the powers of the tests permit some simple rankings: (1) $\mathrm{CM}>\mathrm{OOS} \mathrm{F}>\mathrm{DM}>\mathrm{CH}$; (2) OOS F > out-of-sample GC; and (3) $\mathrm{CM}>\mathrm{ERIC} \geq \mathrm{HLN}>\mathrm{DM}$. In the VAR experiment design, the CM test for encompassing is clearly the most powerful out-of-sample test of predictive power in finite samples. Both the CM encompassing and OOS F accuracy tests dominate GC tests applied to just the out-of-sample data. For example, as shown in Table 3, with $\mathrm{b}=0.1, \mathrm{R}=100$, and $\mathrm{P}=40$, the CM test rejects the null in $32.4 \%$ of the simulations, compared to $28.0 \%$ for the OOS F test and $18.1 \%$ for the out-of-sample GC test. Moreover, when the explanatory power of the Granger-causal variable is weak, as when $b=0.1$, the power of the $C M$ test sometimes exceeds that of the in-sample GC test. This holds even though the CM uses fewer observations than does the in-sample GC test. In the preceding example, the in-sample GC test rejects the null in $30.9 \%$ of the simulations.

[^12]The power of the DM and CH tests is lower, often substantially, than the other equal accuracy and encompassing tests. The HLN and ERIC encompassing tests have power somewhere in between the power of the CM and DM tests.

The second general result is that, given R, power rises with P . For example, as shown in Table 4, with $b=0.2$ and $R=100$, the power of the OOS F test increases from $48.4 \%$ when $\mathrm{P}=20$ to $58.1 \%$ when $\mathrm{P}=40$. Third and finally, power increases with the coefficient b , which determines the explanatory power of the causal variable. Power is systematically higher when $\mathrm{b}=0.4$ than when $\mathrm{b}=0.2$ and, in turn, than when $\mathrm{b}=0.1$.

Table 6 presents size-adjusted power based on the $\operatorname{VAR}(2)$ for the changes in core inflation and unemployment, equations (13)-(14). In the DGP underlying this power experiment, unemployment does affect inflation, so VAR forecasts of $\Delta$ Infl have lower MSE than AR forecasts (asymptotically), and the AR forecast does not encompass the VAR forecast. The critical values used to evaluate power are calculated from the distribution of statistics generated in the Table 2 size experiment. Using the empirical model produces results the same as those for the artificial VAR(1). The rankings (1) $\mathrm{CM}>\mathrm{OOS} \mathrm{F}>\mathrm{DM}>\mathrm{CH}$, (2) OOS F $>$ out-of-sample GC, and (3) CM > ERIC $\geq \mathrm{HLN}>$ DM still apply. In this example, the power of the CM test is not only greater than that of an out-of-sample GC test but also essentially the same as an insample GC test, despite the fact that $\mathrm{P}<\mathrm{R}$. These results suggest that, if the DGP were the true model, statistics like the CM test would be almost sure to correctly pick up the predictive power of unemployment.

## Interpretations and explanations.

## 5. EMPIRICAL EXAMPLE

To provide a sense of the ability of the different tests to determine predictive power in practice, this section presents results on a question that many studies have examined: whether unemployment has predictive power, in-sample and post-sample, for inflation. Recent examples of studies addressing this question include Cecchetti (1995) and Staiger, Stock, and Watson (1997). In this analysis, tests on Granger causality, equal forecast accuracy, and forecast encompassing are applied to data on core CPI inflation and the prime-age male unemployment rate.

In the specification used here, both inflation and unemployment are differenced, consistent with the results of augmented Dickey-Fuller tests for unit roots. The quarterly data available from 1957:Q1-1998:Q4 are divided into an in-sample portion and an out-of-sample portion of modest length, so as to produce a $\hat{\pi}=P / R$ value for which McCracken (1999) reports asymptotic critical values. Allowing for data differencing and a maximum of four lags in determining the model's lag order, the in-sample period spans 1958:Q3-1987:Q1, a total of $\mathrm{R}=$ 115 observations. The out-of-sample period spans 1987:Q2-1998:Q3, yielding a total of $\mathrm{P}=46$ 1 -step ahead predictions. For this split, $\hat{\pi}=0.4$. Over the in-sample period, the Akaike criterion for both the AR and the VAR is minimized at two lags.

Table 7 presents in-sample estimates of an AR(2) fit to changes in core CPI inflation and a VAR(2) fit to changes in core CPI inflation and prime-age male unemployment. The $\overline{\mathrm{R}}^{2}$,s and GC tests reported in the table suggest that, over the in-sample period, unemployment has predictive power for inflation. The out-of-sample evidence, however, is weaker. ${ }^{16}$ The CM encompassing test, shown above to be more powerful than all the other post-sample tests, indicates that unemployment has predictive power for inflation. The ERIC test, which has lower
power than the CM test but higher power than the DM test, also rejects the null when compared against the empirical critical value. Surprisingly, the CH test, generally the weakest, also suggests unemployment has predictive power. None of the other tests reject the null of no predictive content in unemployment.

These results might lead to the conclusion that unemployment in fact has no predictive power for inflation. In this view the in-sample results, and out-of-sample test results suggesting otherwise, are spurious. The problem with this interpretation is that the Monte Carlo experiments of section 4 suggest that any size biases in in-sample Granger causality tests and, in particular, the out-of-sample CM test, should be small, even with data-determined lags. Accordingly, the in-sample GC and CM statistics strongly reject the null when compared against both asymptotic and empirical critical values.

A more reasonable interpretation of the results is that unemployment does have predictive power for inflation, power perhaps weakened by model instabilities. Both an in-sample GC test and the CM test for forecast encompassing overwhelmingly indicate that unemployment has predictive content. The Monte Carlo results in section 4 indicate these tests have the greatest power in finite samples. Nonetheless, the failure of other out-of-sample tests to detect any predictive power, despite the strong in-sample predictive power of unemployment, suggests there is a difference between the in-sample and out-of-sample predictive content of unemployment. This difference may reflect model instabilities. Neither the AR model nor the VAR pass the

[^13]supremum Wald or exponential Wald tests for stability developed in Andrews (1993) and Andrews and Ploberger (1994), respectively. ${ }^{17}$

## 6. CONCLUSIONS

[^14]
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Appendix
Lemmas A1 - A11 also appear in McCracken (1999) with a slightly different numerical ordering. In order to facilitate reference, but also conserve space, those Lemmas are repeated below without proof. Lemmas A12-A14 are new and hence their proofs are provided.

Throughout the remainder the following notation will be used: J denotes the selection matrix $\left(\mathrm{I}_{\mathrm{k}_{1} \times \mathrm{k}_{1}}, 0_{\mathrm{k}_{1} \times \mathrm{k}_{2}}\right)\left(\mathrm{k}_{1} \times \mathrm{k}, \mathrm{k}>\mathrm{k}_{1}\right), \Rightarrow$ denotes weak convergence, $\Sigma_{\mathrm{t}}$ denotes the summation $\Sigma_{\mathrm{t}=\mathrm{R}}^{\mathrm{T}}$, for any function $f_{i, t}(\beta) i=1,2$ we will usually denote $f_{2, t}\left(\beta_{2}^{*}\right)$ as $f_{t}$, for matrices $A$ and $C$ defined in Lemma A2 $\tilde{h}_{t+1}$ denotes $\sigma^{-1} \mathrm{~A}^{\prime} \mathrm{CB}^{0.5} \mathrm{~h}_{\mathrm{t}+1}$, $\mathrm{H}_{\mathrm{i}}(\mathrm{t})$ equals $\mathrm{t}^{-1} \sum_{\mathrm{s}=1}^{\mathrm{t}} \mathrm{h}_{\mathrm{i}, \mathrm{s}}, \mathrm{R}^{-1} \sum_{\mathrm{s}=\mathrm{t}-\mathrm{R}+1}^{\mathrm{t}} \mathrm{h}_{\mathrm{i}, \mathrm{s}}$ and $R^{-1} \sum_{s=1}^{R} h_{i, s}$ for the recursive, rolling and fixed schemes respectively, $\tilde{H}(t)$ denotes $\sigma^{-1} \mathrm{~A} \mathrm{CB}^{0.5} \mathrm{H}(\mathrm{t}), \dot{\beta}_{\mathrm{i}, \mathrm{t}}$ is some vector on the line between $\hat{\beta}_{\mathrm{i}, \mathrm{t}}$ and $\beta_{\mathrm{i}}^{*}, \nabla \dot{\mathrm{~g}}_{\mathrm{i}, \beta, \mathrm{t}+1}$ denotes $\mathrm{g}_{\mathrm{i}, \beta, \mathrm{t+1}}^{\prime}\left(\dot{\beta}_{\mathrm{i}, \mathrm{t}}\right)\left(\hat{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right)$.

Lemma A1: For all $a \in[0,0.5)$ and each $i=1,2$, (a) $\sup _{t}\left|\hat{\beta}_{i, t}-\beta_{i}^{*}\right|=o_{p}(1)$, (b) $\sup _{t}\left|B_{i}(t)-B_{i}\right|=o_{p}(1)$, (c) $\sup _{t} t^{a}|U(t)|=o_{p}(1),(d) \sup _{t} t^{a}\left|\hat{\beta}_{i, t}-\beta_{i}^{*}\right|=o_{p}(1)$, (e) $\sup _{\mathrm{t}}\left|\mathrm{T}^{0.5}\left(\operatorname{vec}\left[\mathrm{~B}_{\mathrm{i}}(\mathrm{t})\right]-\operatorname{vec}\left[\mathrm{B}_{\mathrm{i}}\right]\right)\right|=\mathrm{O}_{\mathrm{p}}(1)$.

Lemma A2: (a) Let $-\mathrm{J}^{\prime} \mathrm{B}_{1} \mathrm{~J}+\mathrm{B}_{2}=\mathrm{M}$ and $\mathrm{B}_{2}^{-1 / 2} \mathrm{MB}_{2}^{-1 / 2}=\mathrm{Q}$, then Q is idempotent. (b) Let A be $\mathrm{a}\left(\mathrm{k} \times \mathrm{k}_{2}\right)$ matrix with $\mathrm{I}_{\mathrm{k}_{2} \times \mathrm{k}_{2}}$ on the upper $\left(\mathrm{k}_{2} \times \mathrm{k}_{2}\right)$ block and zeroes elsewhere. There exists a symmetric orthonormal matrix C such that $\mathrm{Q}=\mathrm{CAA}^{\prime} \mathrm{C}$.

Lemma A3: For $\mathrm{s} \in[\lambda, 1]$, (a) $\mathrm{T}^{-1 / 2} \sum_{\mathrm{j}=1}^{\mathrm{t}} \tilde{\mathrm{h}}_{\mathrm{j}} \Rightarrow \mathrm{W}(\mathrm{s})$, (b) $\left(\frac{\mathrm{T}}{\mathrm{t}}\right) \mathrm{T}^{-1 / 2} \sum_{\mathrm{j}=1}^{\mathrm{t}} \tilde{\mathrm{h}}_{\mathrm{j}} \Rightarrow \mathrm{s}^{-1} \mathrm{~W}(\mathrm{~s})$, (c) $\left(\frac{\mathrm{T}}{\mathrm{R}}\right) \mathrm{T}^{-1 / 2} \sum_{\mathrm{j}=-\mathrm{R}+1}^{\mathrm{t}} \tilde{\mathrm{h}}_{\mathrm{j}} \Rightarrow \lambda^{-1}\{\mathrm{~W}(\mathrm{~s})-\mathrm{W}(\mathrm{s}-\lambda)\}$.

Lemma A4: $\sum_{\mathrm{t}} \tilde{\mathrm{H}}^{\prime}(\mathrm{t}) \tilde{\mathrm{h}}_{\mathrm{t}+1} \rightarrow_{\mathrm{d}} \chi_{1}$ where $\chi_{1}$ equals

| $\int_{\lambda}^{1} s^{-1} W^{\prime}(s) d W(s)$ | for the recursive scheme, |
| :--- | :---: |
| $\lambda^{-1}\{W(1)-W(\lambda)\}^{\prime} W(\lambda)$ | for the fixed scheme, |
| $\lambda^{-1} \int_{\lambda}^{1}\{W(s)-W(s-\lambda)\}^{\prime} d W(s)$ | for the rolling scheme. |

Lemma A5: $\Sigma_{\mathrm{t}} \tilde{\mathrm{H}}^{\prime}(\mathrm{t}) \tilde{\mathrm{H}}(\mathrm{t}) \rightarrow_{\mathrm{d}} \chi_{2}$ where $\chi_{2}$ equals

| $\int_{\lambda}^{1} s^{-2} W^{\prime}(s) W(s) d s$ | for the recursive scheme, |
| :--- | :--- |
| $\pi \lambda^{-1} W^{\prime}(\lambda) W(\lambda)$ | for the fixed scheme, |
| $\lambda^{-2} \int_{\lambda}^{1}\{W(s)-W(s-?)\}^{\prime}\{W(s)-W(s-?)\} d s$ | for the rolling scheme. |

Lemma A6: $\sum_{\mathrm{t}}\left\{-\mathrm{h}_{\mathrm{t}+\mathrm{I}}^{\prime}{ }^{\prime} \mathrm{B}_{1}(\mathrm{t}) \mathrm{JH}(\mathrm{t})+\mathrm{h}_{\mathrm{t}+1}^{\prime} \mathrm{B}(\mathrm{t}) \mathrm{H}(\mathrm{t})\right\}^{2}=\sum_{\mathrm{t}}\left\{-\mathrm{h}_{\mathrm{t}+\mathrm{I}}^{\prime}{ }^{\prime} \mathrm{B}_{1} \mathrm{JH}(\mathrm{t})+\mathrm{h}_{\mathrm{t}+1}^{\prime} \mathrm{BH}(\mathrm{t})\right\}^{2}+$ $\mathrm{o}_{\mathrm{p}}(1)$.

Lemma A7: $\sum_{t}\left\{-h_{t+1}^{\prime} \mathrm{J}^{\prime} \mathrm{B}_{1} \mathrm{JH}(\mathrm{t})+\mathrm{h}_{\mathrm{t}+1}^{\prime} \mathrm{BH}(\mathrm{t})\right\}^{2}=\mathrm{c}^{2} \sum_{\mathrm{t}}\left\{\tilde{\mathrm{H}}(\mathrm{t}) \tilde{\mathrm{h}}_{\mathrm{t}+1}\right\}^{2}$.

Lemma A8: $\sum_{\mathrm{t}}\left\{\tilde{\mathrm{H}}(\mathrm{t}) \tilde{\mathrm{h}}_{\mathrm{t}+1}\right\}^{2} \rightarrow_{\mathrm{d}} \chi_{2}$ for $\chi_{2}$ defined in Lemma A5.

Lemma A9: $\sum_{t} u_{t+1} g_{i, \beta, t+1}^{\prime}\left(\dot{\beta}_{i, t}\right) B_{i}(t) H_{i}(t)=\sum_{t} h_{i, t+1}^{\prime} B_{i} H_{i}(t)+o_{p}(1)$.

Lemma A10: For $\mathrm{i}, \mathrm{j}=1,2, \quad \sum_{\mathrm{t}} \mathrm{H}_{\mathrm{i}}^{\prime}(\mathrm{t}) \mathrm{B}_{\mathrm{i}}(\mathrm{t}) \mathrm{g}_{\mathrm{i}, \beta, \mathrm{t}+1}\left(\dot{\beta}_{\mathrm{i}, \mathrm{t}}\right) \mathrm{g}_{\mathrm{j}, \mathrm{\beta}, \mathrm{t}+1}^{\prime}\left(\dot{\beta}_{\mathrm{j}, \mathrm{t}}\right) \mathrm{B}_{\mathrm{j}}(\mathrm{t}) \mathrm{H}_{\mathrm{j}}(\mathrm{t})=$ $\sum_{\mathrm{t}} \mathrm{H}_{\mathrm{i}}^{\prime}(\mathrm{t}) \mathrm{B}_{\mathrm{i}} \mathrm{E}\left(\mathrm{g}_{\mathrm{i}, \mathrm{\beta}, \mathrm{t}+1} \mathrm{~g}_{\mathrm{j}, \mathrm{\beta}, \mathrm{t+1}}^{\prime}\right) \mathrm{B}_{\mathrm{j}} \mathrm{H}_{\mathrm{j}}(\mathrm{t})+\mathrm{o}_{\mathrm{p}}(1)$.

Lemma A11: $\sum_{\mathrm{t}}\left(\mathrm{u}_{1, \mathrm{t}+1}\left(\hat{\beta}_{1, \mathrm{t}}\right)-\mathrm{u}_{2, \mathrm{t}+1}\left(\hat{\beta}_{2, \mathrm{t}}\right)\right)^{2} \rightarrow_{\mathrm{d}} \sigma^{2} \chi_{2}$.

Lemma A12: For all $a \in[0,0.5), \sup _{\mathrm{t}}\left|\mathrm{T}^{\mathrm{a}} \nabla \dot{\mathrm{g}}_{\mathrm{i}, \mathrm{t}+1}\right|=\mathrm{o}_{\mathrm{p}}(1)$.

Proof of Lemma A12: If we take a first order Taylor expansion of $g_{i, \beta, t+1}^{\prime}\left(\dot{\beta}_{i, t}\right)$ about $\beta_{i}^{*}$ we immediately know that for some $\ddot{\beta}_{\mathrm{i}, \mathrm{t}}$ on the line between $\dot{\beta}_{\mathrm{i}, \mathrm{t}}$ and $\beta_{\mathrm{i}}^{*}$,

$$
\begin{aligned}
& \sup _{\mathrm{t}}\left|\mathrm{~T}^{\mathrm{a}} \nabla \dot{\mathrm{~g}}_{\mathrm{i}, \mathrm{t}+1}\right| \leq \\
& \sup _{\mathrm{t}}\left|\mathrm{~T}^{\mathrm{a}}\left(\dot{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right)^{\prime} \mathrm{q}_{\mathrm{i}, \mathrm{t}+1}\left(\ddot{\beta}_{\mathrm{i}, \mathrm{t}}\right)\left(\hat{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right)\right|+\sup _{\mathrm{t}}\left|\mathrm{~T}^{\mathrm{a}} \mathrm{~g}_{\mathrm{i}, \beta, \mathrm{t}+1}^{\prime}\left(\hat{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right)\right| \\
& \leq \sup _{\mathrm{t}}\left|\mathrm{~T}^{\mathrm{a}}\left(\dot{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right)^{\prime} \mathrm{q}_{\mathrm{i}, \mathrm{t}+1}\left(\ddot{\beta}_{\mathrm{i}, \mathrm{t}}\right)\left(\hat{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right)\right|+ \\
& \quad \mathrm{k}\left(\sup _{\mathrm{t}}\left|\mathrm{~g}_{\mathrm{i}, \beta, \mathrm{p}, 1}\right|\right)\left(\sup _{\mathrm{t}}\left|\mathrm{~T}^{\mathrm{a}}\left(\hat{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right)\right|\right) .
\end{aligned}
$$

Adding and subtracting $\mathrm{q}_{\mathrm{i}, \mathrm{t}+1}$, the r.h.s. of the final inequality is then less than or equal to

$$
\begin{aligned}
& \mathrm{k}^{2}\left(\sup _{\mathrm{t}}\left|\dot{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right|\right)\left(\sup _{\mathrm{t}}\left|\mathrm{q}_{\mathrm{i}, \mathrm{t}+1}\left(\ddot{\beta}_{\mathrm{i}, \mathrm{t}}\right)-\mathrm{q}_{\mathrm{i}, \mathrm{t}+1}\right|\right)\left(\sup _{\mathrm{t}}\left|\mathrm{~T}^{\mathrm{a}}\left(\hat{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right)\right|\right)+ \\
& \mathrm{k}^{2}\left(\sup _{\mathrm{t}}\left|\dot{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right|\right)\left(\sup _{\mathrm{t}}\left|\mathrm{q}_{\mathrm{i}, \mathrm{t}+1}\right|\right)\left(\sup _{\mathrm{t}}\left|\mathrm{~T}^{\mathrm{a}}\left(\hat{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right)\right|\right)+ \\
& \mathrm{k}\left(\sup _{\mathrm{t}}\left|g_{\mathrm{i}, \beta, \mathrm{t}+1}\right|\right)\left(\sup _{\mathrm{t}}\left|\mathrm{~T}^{\mathrm{a}}\left(\hat{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right)\right|\right) .
\end{aligned}
$$

That $\sup _{\mathrm{t}}\left|\mathrm{q}_{\mathrm{i}, \mathrm{t}+1}\right|$ and $\sup _{\mathrm{t}}\left|\mathrm{g}_{\mathrm{i}, \mathrm{\beta}, \mathrm{t+1}}\right|$ are $\mathrm{O}_{\mathrm{p}}(1)$ follows from Assumption 3. That $\sup _{t}\left|T^{a}\left(\hat{\beta}_{i, t}-\beta_{i}^{*}\right)\right|$ is $o_{p}(1)$ follows from Lemma A1. Since $\sup _{t}\left|T^{a}\left(\dot{\beta}_{i, t}-\beta_{i}^{*}\right)\right| \leq$ $\sup _{t}\left|T^{a}\left(\hat{\beta}_{i, t}-\beta_{i}^{*}\right)\right|$ it follows from Lemma A1 that $\sup _{t}\left|T^{a}\left(\dot{\beta}_{i, t}-\beta_{i}^{*}\right)\right|$ is $o_{p}(1)$. The result then follows since by Assumption 2 and Lemma A1, $\sup _{\mathrm{t}}\left|\mathrm{q}_{\mathrm{i}, \mathrm{t}+1}\left(\ddot{\beta}_{\mathrm{i}, \mathrm{t}}\right)-\mathrm{q}_{\mathrm{i}, \mathrm{t}+1}\right| \leq$ $\left(\sup _{\mathrm{t}}\left|\mathrm{m}_{\mathrm{t}}\right|\right)\left(\sup _{\mathrm{t}}\left|\mathrm{T}^{\mathrm{a}}\left(\dot{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right)\right|\right)^{\varphi} \leq\left(\sup _{\mathrm{t}}\left|\mathrm{m}_{\mathrm{t}}\right|\right)\left(\sup _{\mathrm{t}}\left|\mathrm{T}^{\mathrm{a}}\left(\hat{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right)\right|\right)^{\varphi}=\mathrm{O}_{\mathrm{p}}(1) \mathrm{o}_{\mathrm{p}}(1)$.

Lemma A13: For $\mathrm{i}, \mathrm{j}=1,2, \quad \sum_{\mathrm{t}} \mathrm{u}_{\mathrm{t}+1}^{2} \nabla \dot{\mathrm{~g}}_{\mathrm{i}, \mathrm{t}+1} \nabla \dot{\mathrm{~g}}_{\mathrm{j}, \mathrm{t}+1}=\sum_{\mathrm{t}} \mathrm{H}_{\mathrm{i}}(\mathrm{t})^{\prime} \mathrm{B}_{\mathrm{i}} \mathrm{h}_{\mathrm{i}, \mathrm{t}+1} \mathrm{~h}_{\mathrm{j}, \mathrm{t}+1}^{\prime} \mathrm{B}_{\mathrm{j}} \mathrm{H}_{\mathrm{j}}(\mathrm{t})+\mathrm{o}_{\mathrm{p}}(1)$.

Proof of Lemma A13: First rewrite $\sum_{\mathrm{t}} \mathrm{u}_{\mathrm{t}+1}^{2} \nabla \dot{\mathrm{~g}}_{\mathrm{i}, \mathrm{t}+1} \nabla \dot{\mathrm{~g}}_{\mathrm{j}, \mathrm{t}+1}$ as

$$
\begin{aligned}
& \sum_{\mathrm{t}} \mathrm{H}_{\mathrm{i}}(\mathrm{t})^{\prime}\left[\left(\mathrm{B}_{\mathrm{i}}(\mathrm{t})-\mathrm{B}_{\mathrm{i}}\right)+\mathrm{B}_{\mathrm{i}}\right]\left[\left(\mathrm{u}_{\mathrm{t}+1} \mathrm{~g}_{\mathrm{i}, \beta, \mathrm{t}+1}\left(\dot{\beta}_{\mathrm{i}, \mathrm{t}}\right)-\mathrm{h}_{\mathrm{i}, \mathrm{t}+1}\right)+\mathrm{h}_{\mathrm{i}, \mathrm{t}+1}\right] \times \\
& \quad\left[\left(\mathrm{u}_{\mathrm{t}+1} \mathrm{~g}_{\mathrm{j}, \mathrm{\beta}, \mathrm{t}+1}\left(\dot{\beta}_{\mathrm{j}, \mathrm{t}}\right)-\mathrm{h}_{\mathrm{j}, \mathrm{t}+1}\right)+\mathrm{h}_{\mathrm{j}, \mathrm{t}+1}\right]^{\prime}\left[\left(\mathrm{B}_{\mathrm{j}}(\mathrm{t})-\mathrm{B}_{\mathrm{j}}\right)+\mathrm{B}_{\mathrm{j}}\right] \mathrm{H}_{\mathrm{j}}(\mathrm{t}) .
\end{aligned}
$$

Expanding the above equation we then know that $\sum_{\mathrm{t}} \mathrm{u}_{\mathrm{t}+1}^{2} \nabla \dot{\mathrm{~g}}_{\mathrm{i}, \mathrm{t}+1} \nabla \dot{\mathrm{~g}}_{\mathrm{j}, \mathrm{t}+1}$ equals

$$
\begin{aligned}
& \sum_{t} H_{i}^{\prime}(t) B_{i} h_{i, t+1} h_{j, t+1}^{\prime} B_{j} H_{j}(t)+ \\
& \sum_{t} H_{i}^{\prime}(t)\left(B_{i}(t)-B_{i}\right) h_{i, t+1} h_{j, t+1}^{\prime} B_{j} H_{j}(t)+ \\
& \sum_{t} H_{i}^{\prime}(t) B_{i}\left(u_{t+1} g_{i, \beta, t+1}\left(\dot{\beta}_{i, t}\right)-h_{i, t+1}\right) h_{j, t+1}^{\prime} B_{j} H_{j}(t)+ \\
& \sum_{t} H_{i}^{\prime}(t) B_{i} h_{i, t+1} h_{j, t+1}^{\prime}\left(B_{j}(t)-B_{j}\right) H_{j}(t)+ \\
& \quad \sum_{t} H_{i}^{\prime}(t) B_{i} h_{i, t+1}\left(u_{t+1} g_{j, \beta, t+1}\left(\dot{\beta}_{j, t}\right)-h_{j, t+1}\right)^{\prime} B_{j} H_{j}(t)+ \\
& \sum_{t} H_{i}^{\prime}(t)\left(B_{i}(t)-B_{i}\right)\left(u_{t+1} g_{i, \beta, t+1}\left(\dot{\beta}_{i, t}\right)-h_{i, t+1}\right) h_{j, t+1}^{\prime} B_{j} H_{j}(t)+ \\
& \sum_{t} H_{i}^{\prime}(t)\left(B_{i}(t)-B_{i}\right) h_{i, t+1}\left(u_{t+1} g_{j, \beta, t+1}\left(\dot{\beta}_{j, t}\right)-h_{j, t+1}\right) B_{j} H_{j}(t)+ \\
& \sum_{t} H_{i}^{\prime}(t)\left(B_{i}(t)-B_{i}\right) h_{i, t+1} h_{j, t+1}^{\prime}\left(B_{j}(t)-B_{j}\right) H_{j}(t)+
\end{aligned}
$$

$$
\begin{aligned}
& \sum_{t} H_{i}^{\prime}(t) B_{i}\left(u_{t+1} g_{i, \beta, t+1}\left(\dot{\beta}_{i, t}\right)-h_{i, t+1}\right)\left(u_{t+1} g_{j, \beta, t+1}\left(\dot{\beta}_{j, t}\right)-h_{j, t+1}\right) B_{j} H_{j}(t)+ \\
& \sum_{t} H_{i}^{\prime}(t) B_{i}\left(u_{t+1} g_{i, \beta, t+1}\left(\dot{\beta}_{i, t}\right)-h_{i, t+1}\right) h_{j, t+1}^{\prime}\left(B_{j}(t)-B_{j}\right) H_{j}(t)+ \\
& \sum_{t} H_{i}^{\prime}(t) B_{i} h_{i, t+1}\left(u_{t+1} g_{j, \beta, t+1}\left(\dot{\beta}_{j, t}\right)-h_{j, t+1}\right)^{\prime}\left(B_{j}(t)-B_{j}\right) H_{j}(t)+ \\
& \sum_{t} H_{i}^{\prime}(t)\left(B_{i}(t)-B_{i}\right)\left(u_{t+1} g_{i, \beta, t+1}\left(\dot{\beta}_{i, t}\right)-h_{i, t+1}\right)\left(u_{t+1} g_{j, \beta, t+1}\left(\dot{\beta}_{j, t}\right)-h_{j, t+1}\right)^{\prime} B_{j} H_{j}(t)+ \\
& \sum_{t} H_{i}^{\prime}(t)\left(B_{i}(t)-B_{i}\right)\left(u_{t+1} g_{i, \beta, t+1}\left(\dot{\beta}_{i, t}\right)-h_{i, t+1}\right) h_{j, t+1}^{\prime}\left(B_{j}(t)-B_{j}\right) H_{j}(t)+ \\
& \sum_{t} H_{i}^{\prime}(t)\left(B_{i}(t)-B_{i}\right) h_{i, t+1}\left(u_{t+1} g_{j, \beta, t+1}\left(\dot{\beta}_{j, t}\right)-h_{j, t+1}\right)\left(B_{j}(t)-B_{j}\right) H_{j}(t)+ \\
& \sum_{t} H_{i}^{\prime}(t) B_{i}\left(u_{t+1} g_{i, \beta, t+1}\left(\dot{\beta}_{i, t}\right)-h_{i, t+1}\right)\left(u_{t+1} g_{j, \beta, t+1}\left(\dot{\beta}_{j, t}\right)-h_{j, t+1}\right)^{\prime}\left(B_{j}(t)-B_{j}\right) H_{j}(t)+ \\
& \sum_{t} H_{i}^{\prime}(t)\left(B_{i}(t)-B_{i}\right)\left(u_{t+1} g_{i, \beta, t+1}\left(\dot{\beta}_{i, t}\right)-h_{i, t+1}\right) \times \\
& \quad\left(u_{t+1} g_{j, \beta, t+1}\left(\dot{\beta}_{j, t}\right)-h_{j, t+1}\right)^{\prime}\left(B_{j}(t)-B_{j}\right) H_{j}(t) .
\end{aligned}
$$

The result will follow if the latter fifteen terms are each $o_{p}(1)$. The proof of each is largely the same hence we will do so only for the final term. The absolute value of the final term is less than or equal to

$$
\begin{aligned}
& \mathrm{k}^{5}\left(\sup _{\mathrm{t}}\left|\mathrm{~T}^{0.5} \mathrm{H}_{\mathrm{i}}(\mathrm{t})\right|\right)\left(\sup _{\mathrm{t}}\left|\mathrm{~T}^{0.5} \mathrm{H}_{\mathrm{j}}(\mathrm{t})\right|\right)\left(\sup _{\mathrm{t}}\left|\mathrm{~B}_{\mathrm{i}}(\mathrm{t})-\mathrm{B}_{\mathrm{i}}\right|\right)\left(\sup _{\mathrm{t}}\left|\mathrm{~B}_{\mathrm{j}}(\mathrm{t})-\mathrm{B}_{\mathrm{j}}\right|\right) \times \\
& \quad\left(\sup _{\mathrm{t}}\left|\mathrm{u}_{\mathrm{t}+1} g_{\mathrm{i}, \beta, \mathrm{t}+1}\left(\dot{\beta}_{\mathrm{i}, \mathrm{t}}\right)-\mathrm{h}_{\mathrm{i}, \mathrm{t}+1}\right|\right)\left(\sup _{\mathrm{t}}\left|\mathrm{u}_{\mathrm{t}+1} g_{\mathrm{j}, \beta, \mathrm{t}+1}\left(\dot{\beta}_{\mathrm{j}, \mathrm{t}}\right)-\mathrm{h}_{\mathrm{j}, \mathrm{t}+1}\right|\right)
\end{aligned}
$$

That $\sup _{\mathrm{t}}\left|\mathrm{T}^{0.5} \mathrm{H}_{\mathrm{i}}(\mathrm{t})\right|$ and $\sup _{\mathrm{t}}\left|\mathrm{T}^{0.5} \mathrm{H}_{\mathrm{j}}(\mathrm{t})\right|$ are each $\mathrm{O}_{\mathrm{p}}(1)$ follows from Assumption 3 and Theorem 3.1 of Hansen (1992). That $\sup _{t}\left|B_{i}(t)-B_{i}\right|$ and $\sup _{t}\left|B_{j}(t)-B_{j}\right|$ are each $o_{p}(1)$ follows from Lemma A1. It remains to show that both $\sup _{t}\left|u_{t+1} g_{i, \beta, t+1}\left(\dot{\beta}_{i, t}\right)-h_{i, t+1}\right|$ and $\sup _{\mathrm{t}}\left|\mathrm{u}_{\mathrm{t}+1} \mathrm{~g}_{\mathrm{j}, \mathrm{\beta}, \mathrm{t}+1}\left(\dot{\beta}_{\mathrm{j}, \mathrm{t}}\right)-\mathrm{h}_{\mathrm{j}, \mathrm{t+1}}\right|$ are $\mathrm{O}_{\mathrm{p}}(1)$. We will do so for the former. If we take a first order

Taylor expansion of $g_{i, \beta, t+1}^{\prime}\left(\dot{\beta}_{i, t}\right)$ about $\beta_{i}^{*}$ we immediately know that for some $\ddot{\beta}_{i, t}$ on the line between $\dot{\beta}_{\mathrm{i}, \mathrm{t}}$ and $\beta_{\mathrm{i}}^{*}$,

$$
\begin{aligned}
& \sup _{t}\left|u_{t+1} g_{i, \beta, t+1}\left(\dot{\beta}_{i, t}\right)-h_{i, t+1}\right| \leq\left(\sup _{t}\left|u_{t+1}\right|\right)\left(\sup _{t}\left|q_{i, t+1}\left(\ddot{\beta}_{i, t}\right)\left(\dot{\beta}_{i, t}-\beta_{i}^{*}\right)\right|\right) \\
& \leq k\left(\sup _{t}\left|u_{t+1}\right|\right)\left(\sup _{t}\left|q_{i, t+1}\right|\right)\left(\sup _{t}\left|\dot{\beta}_{i, t}-\beta_{i}^{*}\right|\right)+ \\
& \quad k\left(\sup _{t}\left|u_{t+1}\right|\right)\left(\sup _{t}\left|q_{i, t+1}\left(\ddot{\beta}_{i, t}\right)-q_{i, t+1}\right|\right)\left(\sup _{t}\left|\dot{\beta}_{i, t}-\beta_{i}^{*}\right|\right)
\end{aligned}
$$

That $\sup _{t}\left|u_{t+1}\right|$ and $\sup _{t}\left|q_{i, t+1}\right|$ are $O_{p}(1)$ follows from Assumption 3. That $\sup _{t}\left|\dot{\beta}_{i, t}-\beta_{i}^{*}\right|$ is $o_{p}(1)$ follows from Lemma A1 since $\sup _{t}\left|\dot{\beta}_{i, t}-\beta_{i}^{*}\right| \leq \sup _{t}\left|\hat{\beta}_{i, t}-\beta_{i}^{*}\right|=o_{p}(1)$. The result then follows from Assumption 2 and Lemma A1 since they imply that $\sup _{t}\left|q_{i, t+1}\left(\ddot{\beta}_{i, t}\right)-q_{i, t+1}\right| \leq$ $\left(\sup _{\mathrm{t}}\left|\mathrm{m}_{\mathrm{t}}\right|\right)\left(\sup _{\mathrm{t}}\left|\ddot{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right|\right)^{\varphi} \leq\left(\sup _{\mathrm{t}}\left|\mathrm{m}_{\mathrm{t}}\right|\right)\left(\sup _{\mathrm{t}}\left|\hat{\beta}_{\mathrm{i}, \mathrm{t}}-\beta_{\mathrm{i}}^{*}\right|\right)^{\varphi}=\mathrm{O}_{\mathrm{p}}(1) \mathrm{o}_{\mathrm{p}}(1)$.

Lemma A14: $\sum_{t}\left(u_{1, t+1}^{2}\left(\hat{\beta}_{1, t}\right)-u_{1, t+1}\left(\hat{\beta}_{1, t}\right) u_{2, t+1}\left(\hat{\beta}_{2, \mathrm{t}}\right)\right)^{2} \rightarrow_{\mathrm{d}} \sigma^{4} \chi_{2}$.

Proof of Lemma A14: If we take first order Taylor expansions of both $u_{1, t+1}\left(\hat{\beta}_{1, t}\right)$ and $\mathrm{u}_{2, \mathrm{t}+1}\left(\hat{\beta}_{2, \mathrm{t}}\right)$ around $\beta_{1}^{*}$ and $\beta_{2}^{*}$ respectively, we have

$$
\begin{aligned}
& \sum_{\mathrm{t}}\left(\mathrm{u}_{1, \mathrm{t}+1}^{2}\left(\hat{\beta}_{1, \mathrm{t}}\right)-\mathrm{u}_{1, \mathrm{t}+1}\left(\hat{\beta}_{1, \mathrm{t}}\right) \mathrm{u}_{2, \mathrm{t}+1}\left(\hat{\beta}_{2, \mathrm{t}}\right)\right)^{2}= \\
& \quad\left[-2 \sum_{\mathrm{t}} \mathrm{u}_{\mathrm{t}+1}\left\{\nabla \dot{\mathrm{~g}}_{1, \mathrm{t}+1}\right\}^{3}+4 \sum_{\mathrm{t}} \mathrm{u}_{\mathrm{t}+1}\left\{\nabla \dot{\mathrm{~g}}_{1, \mathrm{t}+1}\right\}^{2}\left\{\nabla \dot{\mathrm{~g}}_{2, \mathrm{t}+1}\right\}-2 \sum_{\mathrm{t}} \mathrm{u}_{\mathrm{t}+1}\left\{\nabla \dot{\mathrm{~g}}_{1, \mathrm{t}+1}\right\}\left\{\nabla \dot{\mathrm{g}}_{2, \mathrm{t}+1}\right\}^{2}\right. \\
& \left.\quad+\sum_{\mathrm{t}}\left\{\nabla \dot{\mathrm{~g}}_{1, \mathrm{t}+1}\right\}^{4}-2 \sum_{\mathrm{t}}\left\{\nabla \dot{\mathrm{~g}}_{1, \mathrm{t}+1}\right\}^{3}\left\{\nabla \dot{\mathrm{~g}}_{2, \mathrm{t}+1}\right\}+2 \sum_{\mathrm{t}}\left\{\nabla \dot{\mathrm{~g}}_{1, \mathrm{t}+1}\right\}^{2}\left\{\nabla \dot{\mathrm{~g}}_{2, \mathrm{t}+1}\right\}^{2}\right] \\
& \quad+\left[\sum_{\mathrm{t}} \mathrm{u}_{\mathrm{t}+1}^{2}\left\{\nabla \dot{\mathrm{~g}}_{1, \mathrm{t}+1}\right\}^{2}-2 \sum_{\mathrm{t}} \mathrm{u}_{\mathrm{t}+1}^{2}\left\{\nabla \dot{\mathrm{~g}}_{1, \mathrm{t}+1}\right\}\left\{\nabla \dot{\mathrm{g}}_{2, \mathrm{t}+1}\right\}+\sum_{\mathrm{t}} \mathrm{u}_{\mathrm{t}+1}^{2}\left\{\nabla \dot{\mathrm{~g}}_{2, \mathrm{t}+1}\right\}^{2}\right] \\
& \quad \begin{array}{l}
\equiv \mathrm{r}_{1, \mathrm{~T}}+\mathrm{r}_{2, \mathrm{~T}} .
\end{array}
\end{aligned}
$$

That $\mathrm{r}_{2, \mathrm{~T}}=\sigma^{4} \sum_{\mathrm{t}}\left\{\tilde{\mathrm{H}}(\mathrm{t}) \tilde{\mathrm{h}}_{\mathrm{t}+1}\right\}^{2} \rightarrow_{\mathrm{d}} \sigma^{4} \chi_{2}$ follows from Lemmas A6-A8 and A13. The remainder of the proof then consists of showing that each of the six terms in $r_{1, T}$ are $o_{p}(1)$. We will do so for the first, the remaining terms follow from similar arguments. Taking absolute values we know that $\left|\sum_{\mathrm{t}} \mathrm{u}_{\mathrm{t}+1}\left\{\nabla \dot{\mathrm{~g}}_{1, \mathrm{t}+1}\right\}^{3}\right| \leq\left(\sup _{\mathrm{t}}\left|\mathrm{T}^{1 / 3} \nabla \dot{\mathrm{~g}}_{1, \mathrm{t}+1}\right|\right)^{3}\left(\sup _{\mathrm{t}}\left|\mathrm{u}_{\mathrm{t}+1}\right|\right)$. That $\sup _{\mathrm{t}}\left|\mathrm{T}^{1 / 3} \nabla \dot{\mathrm{~g}}_{1, \mathrm{t}+1}\right|$ is $\mathrm{o}_{\mathrm{p}}(1)$ follows from Lemma A12; that $\sup _{\mathrm{t}}\left|\mathrm{u}_{\mathrm{t}+1}\right|$ is $\mathrm{O}_{\mathrm{p}}(1)$ follows from Assumption 3.

Proof of Theorem 3.4: (HLN) Given Lemma A14 and Theorem 3.5, the result follows from Theorem 2.1 of Hansen (1992) and the Continuous Mapping Theorem.

Proof of Theorem 3.5: (CM) If we take first order Taylor expansions of both $u_{1, t+1}\left(\hat{\beta}_{1, t}\right)$ and $\mathrm{u}_{2, \mathrm{t}+1}\left(\hat{\beta}_{2, \mathrm{t}}\right)$ around $\beta_{1}^{*}$ and $\beta_{2}^{*}$ respectively, we have

$$
\begin{align*}
& \sum_{t} u_{1, t+1}^{2}\left(\hat{\beta}_{1, t}\right)-u_{1, t+1}\left(\hat{\beta}_{1, \mathrm{t}}\right) \mathbf{u}_{2, \mathrm{t}+1}\left(\hat{\beta}_{2, \mathrm{t}}\right)=  \tag{1}\\
& \sum_{t}\left\{-u_{t+1} g_{1, \beta, t+1}^{\prime}\left(\dot{\beta}_{1, t}\right) B_{1}(t) J H(t)+u_{t+1} g_{2, \beta, t+1}^{\prime}\left(\dot{\beta}_{2, t}\right) B(t) H(t)\right\}- \\
& \sum_{\mathrm{t}}\left\{-\mathrm{H}(\mathrm{t})^{\prime} \mathrm{J}^{\prime} \mathrm{B}_{1}(\mathrm{t}) \mathrm{g}_{1, \beta, \mathrm{t}+1}\left(\dot{\beta}_{1, \mathrm{t}}\right) \mathrm{g}_{1, \beta, \mathrm{t}+1}^{\prime}\left(\dot{\beta}_{1, \mathrm{t}}\right) \mathrm{B}_{1}(\mathrm{t}) \mathrm{JH}(\mathrm{t})+\right. \\
& \left.\mathrm{H}(\mathrm{t})^{\prime} \mathrm{J}^{\prime} \mathrm{B}_{1}(\mathrm{t}) \mathrm{g}_{1, \beta, \mathrm{t}+1}\left(\dot{\beta}_{1, \mathrm{t}}\right) \mathrm{g}_{2, \beta, \mathrm{t}+1}^{\prime}\left(\dot{\beta}_{2, \mathrm{t}}\right) \mathrm{B}(\mathrm{t}) \mathrm{H}(\mathrm{t})\right\}
\end{align*}
$$

for $\dot{\beta}_{\mathrm{i}, \mathrm{t}}$ on the line between $\hat{\beta}_{\mathrm{i}, \mathrm{t}}$ and $\beta_{\mathrm{i}}^{*}$ respectively. By Lemmas A2 and A9 we know that the first bracketed term on the r.h.s. of (1) equals $\sigma^{2} \sum_{\mathrm{t}} \tilde{H}^{\prime}(\mathrm{t}) \tilde{h}_{\mathrm{t}+1}+\mathrm{o}_{\mathrm{p}}(1)$. By Lemma A10 we know both

$$
\sum_{t}-H(t)^{\prime} J^{\prime} B_{1}(t) g_{1, \beta, t+1}\left(\dot{\beta}_{1, t}\right) g_{1, \beta, t+1}^{\prime}\left(\dot{\beta}_{1, t}\right) B_{1}(t) J H(t)=\sum_{t}-H(t)^{\prime} J^{\prime} B_{1} J H(t)+o_{p}(1)
$$

and

$$
\begin{aligned}
& \sum_{\mathrm{t}} \mathrm{H}(\mathrm{t})^{\prime} J^{\prime} \mathrm{B}_{1}(\mathrm{t}) \mathrm{g}_{1, \beta, \mathrm{p}, \mathrm{t}}\left(\dot{\beta}_{1, \mathrm{t}}\right) \mathrm{g}_{2, \beta, \mathrm{t}+1}^{\prime}\left(\dot{\beta}_{2, \mathrm{t}}\right) \mathrm{B}(\mathrm{t}) \mathrm{H}(\mathrm{t})= \\
& \sum_{\mathrm{t}} \mathrm{H}(\mathrm{t})^{\prime} \mathrm{J}^{\prime} \mathrm{B}_{1} \mathrm{E}\left(\mathrm{~g}_{1, \beta, \mathrm{t}+1} \mathrm{~g}_{2, \beta, \mathrm{t}+1}^{\prime}\right) \mathrm{BH}(\mathrm{t})+\mathrm{o}_{\mathrm{p}}(1) .
\end{aligned}
$$

But $E\left(g_{1, \beta, t+1} g_{2, \beta, t+1}^{\prime}\right)=\operatorname{JE}\left(g_{2, \beta, t+1} g_{2, \beta, t+1}^{\prime}\right)=\mathrm{JB}^{-1}$. Hence the last bracketed term on the r.h.s. of (9) is $o_{p}(1)$. The result then follows from Lemma A4.

Proof of Theorem 3.6: (Eric) Given Theorem 3.5, the Continuous Mapping Theorem and Theorem 2.1 of Hansen (1992) it suffices to show $\mathrm{a}_{1, \mathrm{~T}} \mathrm{a}_{2, \mathrm{~T}}-\mathrm{a}_{0, \mathrm{~T}}^{2} \rightarrow_{\mathrm{d}} \sigma^{4} \chi_{2}$ for $\chi_{2}$ defined in Lemma A5. That $\mathrm{a}_{2, \mathrm{~T}} \rightarrow_{\mathrm{p}} \sigma^{2}$ follows from Theorem 4.1 of West (1996). To show that $\mathrm{Pa}_{0, \mathrm{~T}}^{2}=$ $\mathrm{o}_{\mathrm{p}}(1)$ note that Theorem 2.6 implies that $\mathrm{Pa}_{0, \mathrm{~T}}=\mathrm{O}_{\mathrm{p}}(1)$. The result follows since by Lemma A11, $\mathrm{Pa}_{1, \mathrm{~T}} \rightarrow_{\mathrm{d}} \sigma^{2} \chi_{2}$.

| Table 1 <br> Empirical Size <br> Artificial VAR(1) <br> Recursive Forecasts <br> Nominal Size $=10 \%$ |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $R=100$ |  |  |  |  |  |  |
|  | $P=10$ | $P=20$ | $P=40$ | $P=60$ | $P=100$ | $P=200$ |
| Tests Compared Against Valid Asymptotic Critical Values |  |  |  |  |  |  |
| OOS F | . 113 | . 107 | . 100 | . 105 | . 106 | . 099 |
| DM | . 163 | . 135 | . 120 | . 110 | . 107 | . 099 |
| CM | . 118 | . 110 | . 103 | . 106 | . 105 | . 100 |
| HLN | . 162 | . 140 | . 121 | . 113 | . 111 | . 104 |
| ERIC | . 170 | . 142 | . 120 | . 113 | . 111 | . 104 |
| CH | . 200 | . 155 | . 132 | . 122 | . 116 | . 110 |
| GC, OOS | . 135 | . 116 | . 110 | . 108 | . 106 | . 103 |
| GC, in-smpl. | . 103 | . 104 | . 103 | . 105 | . 104 | . 104 |
| Tests Compared Against Invalid Asymptotic Critical Values |  |  |  |  |  |  |
| DM | . 075 | . 055 | . 038 | . 029 | . 019 | . 010 |
| HLN | . 095 | . 083 | . 074 | . 069 | . 064 | . 057 |
| ERIC | . 135 | . 101 | . 080 | . 073 | . 066 | . 058 |
| $R=200$ |  |  |  |  |  |  |
|  | $P=20$ | $P=40$ | $P=80$ | $P=120$ | $P=200$ | $P=400$ |
| Tests Compared Against Valid Asymptotic Critical Values |  |  |  |  |  |  |
| OOS F | 0.107 | . 104 | . 096 | . 104 | . 102 | . 097 |
| DM | 0.137 | . 122 | . 110 | . 105 | . 103 | . 097 |
| CM | 0.111 | . 106 | . 099 | . 106 | . 101 | . 098 |
| HLN | 0.136 | . 125 | . 109 | . 109 | . 105 | . 100 |
| ERIC | 0.140 | . 126 | . 109 | . 109 | . 104 | . 100 |
| CH | 0.152 | . 126 | . 113 | . 109 | . 105 | . 105 |
| GC, OOS | 0.116 | . 110 | . 103 | . 104 | . 102 | . 101 |
| GC, in-smpl. | 0.102 | . 099 | . 102 | . 102 | . 102 | . 102 |
| Tests Compared Against Invalid Asymptotic Critical Values |  |  |  |  |  |  |
| DM | 0.067 | . 049 | . 034 | . 027 | . 018 | . 010 |
| HLN | 0.087 | . 076 | . 067 | . 066 | . 060 | . 056 |
| ERIC | 0.105 | . 084 | . 070 | . 068 | . 060 | . 056 |

Notes:

1. The DGP is

$$
\binom{y_{t}}{x_{t}}=\left(\begin{array}{cc}
.3 & 0 \\
0 & .5
\end{array}\right)\binom{y_{t-1}}{x_{t-1}}+\binom{e_{y, t}}{e_{x, t}},
$$

where the error terms are independent standard normal variables and, in these size experiments, $b=0$. In each simulation, 1-step ahead forecasts of $y$ are formed from an estimated AR model for $y$ and an estimated VAR in $y$ and $x$. 2. In each simulation, the lag lengths of the estimated models are set at one, the order of the DGP.
3. $R$ and $P$ refer to the number of in-sample observations and post-sample predictions, respectively.
4. Section 2 in the text defines the test statistics. The statistics included in the above set of asymptotically valid tests are compared to the correct asymptotic distributions, described in Section 2. The statistics in the set of asymptotically invalid tests are compared to the distributions that would be appropriate if the forecasting models were non-nested but are inappropriate for nested models.
5 . The number of simulations is 50,000 .

| $\operatorname{VAR}(2)$ in | Unemploy asts $10 \%$ 46 |
| :---: | :---: |
| $\begin{array}{r} \text { Tests } \\ \text { Asy } \\ \hline \end{array}$ | nst Valid Values |
| OOS F | . 108 |
| DM | . 116 |
| CM | . 108 |
| HLN | . 118 |
| ERIC | . 120 |
| CH | . 139 |
| GC, OOS | . 104 |
| GC, in-smpl. | . 101 |
| Tests Compared Against Invalid Asymptotic Critical Values |  |
|  |  |
| DM | . 032 |
| HLN | . 081 |
| ERIC | . 089 |

Notes:

1. The DGP is

$$
\begin{gathered}
\Delta \text { Infl }_{t}=-.024-.288 \Delta \text { Infl }_{t-1}-.237 \Delta \text { Infl }_{t-2}+u_{t} \\
\Delta \text { Unemp }_{t}=-.009+.057 \Delta \text { Infl }_{t-1}+.015 \Delta \text { Infl }_{t-2}+.703 \Delta \text { Unemp }_{t-1}-.182 \Delta \text { Unemp }_{t-2}+v_{t} \\
\operatorname{Var}\left(u_{t}\right)=2.795,, \operatorname{Var}\left(v_{t}\right)=.107, \operatorname{Cov}\left(u_{t}, v_{t}\right)=-.084 .
\end{gathered}
$$

In each simulation, 1-step ahead forecasts of the change in inflation are formed from an estimated AR model for the change in inflation and an estimated VAR in the changes in inflation and unemployment.
2. In each simulation, the lag lengths of the estimated models are set at two, the order of the DGP.
3. $R$ and $P$ refer to the number of in-sample observations and post-sample predictions, respectively.
4. Section 2 in the text defines the test statistics. The statistics included in the above set of asymptotically valid tests are compared to the correct asymptotic distributions, described in Section 2. The statistics in the set of asymptotically invalid tests are compared to the distributions that would be appropriate if the forecasting models were non-nested but are inappropriate for nested models.
5. The number of simulations is 50,000 .

| Table 3 <br> Size-Adjusted Power <br> Artificial VAR(1), $b=.1$ <br> Recursive Forecasts <br> $10 \%$ Signif. Empirical Critical Values |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $R=100$ |  |  |  |  |  |  |
|  | $P=10$ | $P=20$ | $P=40$ | $P=60$ | $P=100$ | $P=200$ |
| OOS F | . 212 | . 238 | . 280 | . 313 | . 382 | . 538 |
| DM | . 135 | . 176 | . 225 | . 257 | . 338 | . 509 |
| CM | . 230 | . 272 | . 324 | . 367 | . 455 | . 613 |
| HLN | . 149 | . 202 | . 266 | . 308 | . 405 | . 594 |
| ERIC | . 158 | . 201 | . 266 | . 308 | . 405 | . 595 |
| CH | . 111 | . 117 | . 124 | . 142 | . 157 | . 182 |
| GC, OOS | . 109 | . 138 | . 181 | . 208 | . 292 | . 482 |
| GC, in-smpl. | . 308 | . 312 | . 309 | . 301 | . 304 | . 297 |
| $R=200$ |  |  |  |  |  |  |
|  | $P=20$ | $P=40$ | $P=80$ | $P=120$ | $P=200$ | $P=400$ |
| OOS F | . 299 | . 345 | . 416 | . 486 | . 593 | . 757 |
| DM | . 181 | . 234 | . 315 | . 390 | . 526 | . 723 |
| CM | . 338 | . 413 | . 512 | . 584 | . 705 | . 854 |
| HLN | . 212 | . 287 | . 404 | . 493 | . 640 | . 829 |
| ERIC | . 215 | . 290 | . 404 | . 493 | . 639 | . 829 |
| CH | . 108 | . 116 | . 136 | . 144 | . 181 | . 227 |
| GC, OOS | . 141 | . 172 | . 260 | . 340 | . 501 | . 732 |
| GC, in-smpl. | . 476 | . 489 | . 482 | . 484 | . 488 | . 493 |

Notes:

1. The DGP is

$$
\binom{y_{t}}{x_{t}}=\left(\begin{array}{cc}
.3 & b \\
0 & .5
\end{array}\right)\binom{y_{t-1}}{x_{t-1}}+\binom{e_{y, t}}{e_{x, t}},
$$

where the error terms are independent standard normal variables and, in these power experiments, $b=.1$. In each simulation, 1 -step ahead forecasts of $y$ are formed from an estimated AR model for $y$ and an estimated VAR in $y$ and $x$. 2. In each simulation, the lag lengths of the estimated models are set at one, the order of the DGP.
3. $R$ and $P$ refer to the number of in-sample observations and post-sample predictions, respectively.
4. Section 2 in the text defines the test statistics.

5 . The number of simulations is 5,000 .

| Table 4 <br> Size-Adjusted Power Artificial VAR(1), $b=.2$ <br> Recursive Forecasts <br> $10 \%$ Signif. Empirical Critical Values |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $R=100$ |  |  |  |  |  |  |
|  | $P=10$ | $P=20$ | $P=40$ | $P=60$ | $P=100$ | $P=200$ |
| OOS F | . 405 | . 484 | . 581 | . 667 | . 780 | . 929 |
| DM | . 205 | . 293 | . 430 | . 523 | . 689 | . 897 |
| CM | . 486 | . 598 | . 728 | . 815 | . 910 | . 983 |
| HLN | . 260 | . 388 | . 577 | . 695 | . 855 | . 977 |
| ERIC | . 276 | . 395 | . 579 | . 699 | . 856 | . 977 |
| CH | . 140 | . 182 | . 240 | . 301 | . 401 | . 572 |
| GC, OOS | . 146 | . 227 | . 375 | . 508 | . 715 | . 938 |
| GC, in-smpl. | . 713 | . 712 | . 721 | . 714 | . 723 | . 719 |
| $R=200$ |  |  |  |  |  |  |
|  | $P=20$ | $P=40$ | $P=80$ | $P=120$ | $P=200$ | $P=400$ |
| OOS F | . 558 | . 644 | . 766 | . 853 | . 932 | . 990 |
| DM | . 277 | . 408 | . 597 | . 718 | . 867 | . 984 |
| CM | . 692 | . 820 | . 925 | . 970 | . 994 | 1.000 |
| HLN | . 393 | . 588 | . 803 | . 914 | . 981 | 1.000 |
| ERIC | . 408 | . 594 | . 805 | . 917 | . 981 | 1.000 |
| CH | . 155 | . 206 | . 315 | . 394 | . 555 | . 770 |
| GC, OOS | . 226 | . 375 | . 627 | . 792 | . 937 | . 998 |
| GC, in-smpl. | . 937 | . 938 | . 936 | . 938 | . 938 | . 940 |

Notes:

1. The DGP is

$$
\binom{y_{t}}{x_{t}}=\left(\begin{array}{cc}
.3 & b \\
0 & .5
\end{array}\right)\binom{y_{t-1}}{x_{t-1}}+\binom{e_{y, t}}{e_{x, t}},
$$

where the error terms are independent standard normal variables and, in these power experiments, $b=.2$. In each simulation, 1 -step ahead forecasts of $y$ are formed from an estimated AR model for $y$ and an estimated VAR in $y$ and $x$. 2. In each simulation, the lag lengths of the estimated models are set at one, the order of the DGP.
3. $R$ and $P$ refer to the number of in-sample observations and post-sample predictions, respectively.
4. Section 2 in the text defines the test statistics.
5. The number of simulations is 5,000 .

| Table 5 <br> Size-Adjusted Power <br> Artificial VAR(1), $b=.4$ <br> Recursive Forecasts <br> $10 \%$ Signif. Empirical Critical Values |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $R=100$ |  |  |  |  |  |  |
|  | $P=10$ | $P=20$ | $P=40$ | $P=60$ | $P=100$ | $P=200$ |
| OOS F | . 658 | . 767 | . 889 | . 943 | . 988 | . 999 |
| DM | . 317 | . 488 | . 715 | . 856 | . 968 | . 999 |
| CM | . 832 | . 930 | . 988 | . 999 | 1.000 | 1.000 |
| HLN | . 482 | . 738 | . 940 | . 988 | . 999 | 1.000 |
| ERIC | . 523 | . 754 | . 942 | . 988 | . 999 | 1.000 |
| CH | . 266 | . 400 | . 635 | . 776 | . 911 | . 991 |
| GC, OOS | . 282 | . 525 | . 820 | . 945 | . 995 | 1.000 |
| GC, in-smpl. | . 995 | . 995 | . 995 | . 996 | . 996 | . 997 |
| $R=200$ |  |  |  |  |  |  |
|  | $P=20$ | $P=40$ | $P=80$ | $P=120$ | $P=200$ | $P=400$ |
| OOS F | . 786 | . 902 | . 969 | . 992 | . 999 | 1.000 |
| DM | . 465 | . 684 | . 896 | . 970 | . 999 | 1.000 |
| CM | . 952 | . 994 | 1.000 | 1.000 | 1.000 | 1.000 |
| HLN | . 745 | . 939 | . 997 | 1.000 | 1.000 | 1.000 |
| ERIC | . 752 | . 943 | . 997 | 1.000 | 1.000 | 1.000 |
| CH | . 372 | . 590 | . 844 | . 936 | . 989 | 1.000 |
| GC, OOS | . 526 | . 831 | . 981 | . 999 | 1.000 | 1.000 |
| GC, in-smpl. | 1.000 | 1.000 | 1.000 | 1.000 | 1.000 | 1.000 |

Notes:

1. The DGP is

$$
\binom{y_{t}}{x_{t}}=\left(\begin{array}{cc}
.3 & b \\
0 & .5
\end{array}\right)\binom{y_{t-1}}{x_{t-1}}+\binom{e_{y, t}}{e_{x, t}},
$$

where the error terms are independent standard normal variables and, in these power experiments, $b=.4$. In each simulation, 1 -step ahead forecasts of $y$ are formed from an estimated AR model for $y$ and an estimated VAR in $y$ and $x$. 2. In each simulation, the lag lengths of the estimated models are set at one, the order of the DGP.
3. $R$ and $P$ refer to the number of in-sample observations and post-sample predictions, respectively.
4. Section 2 in the text defines the test statistics.
5. The number of simulations is 5,000 .


Notes:

1. The DGP is

$$
\begin{gathered}
\Delta \text { Infl }_{t}=-.033-.391 \Delta \text { Infl }_{t-1}-.266 \Delta \text { Infl }_{t-2}-1.207 \Delta \text { Unemp }_{t-1}-.137 \Delta \text { Unemp }_{t-2}+u_{t} \\
\Delta \text { Unemp }_{t}=-.009+.057 \Delta \text { Infl }_{t-1}+.015 \Delta \text { Infl }_{t-2}+.703 \Delta \text { Unemp }_{t-1}-.182 \Delta \text { Unemp }_{t-2}+v_{t} \\
\operatorname{Var}\left(u_{t}\right)=2.519,, \operatorname{Var}\left(v_{t}\right)=.107, \operatorname{Cov}\left(u_{t}, v_{t}\right)=-.084
\end{gathered}
$$

In each simulation, 1-step ahead forecasts of the change in inflation are formed from an estimated AR model for the change in inflation and an estimated VAR in the changes in inflation and unemployment.
2. In each simulation, the lag lengths of the estimated models are set at two, the order of the DGP.
3. $R$ and $P$ refer to the number of in-sample observations and post-sample predictions, respectively.
4. Section 2 in the text defines the test statistics.

5 . The number of simulations is 5,000 .


Notes:

1. 1-step ahead forecasts of the change in inflation are formed from an estimated AR model for the change in inflation and an estimated VAR in the changes in inflation and unemployment.
2. The significance level of the tests is $10 \%$.
3. $R$ and $P$ refer to the number of in-sample observations and post-sample predictions, respectively.
4. Section 2 in the text defines the test statistics.
Table A1
Percentiles of the HLN and ERIC statistics: Recursive scheme

| $\underline{\mathrm{k}}_{2} \underline{1}$ |  | 0.1 | 0.2 | 0.4 | 0.6 | 0.8 | 1.0 | 1.2 | 1.4 | 1.6 | 1.8 | 2.0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | (0.99) | 2.102 | 2.030 | 1.997 | 2.006 | 2.054 | 2.052 | 2.036 | 2.033 | 2.030 | 2.077 | 2.082 |
|  | (0.95) | 1.422 | 1.360 | 1.338 | 1.399 | 1.350 | 1.331 | 1.350 | 1.360 | 1.332 | 1.329 | 1.322 |
|  | (0.90) | 1.056 | 1.002 | 1.005 | 0.995 | 0.968 | 0.955 | 0.942 | 0.939 | 0.959 | 0.956 | 0.939 |
| 2 | (0.99) | 2.187 | 2.214 | 2.073 | 2.089 | 2.178 | 2.195 | 2.169 | 2.151 | 2.164 | 2.135 | 2.115 |
|  | (0.95) | 1.505 | 1.467 | 1.445 | 1.441 | 1.413 | 1.413 | 1.425 | 1.439 | 1.427 | 1.440 | 1.443 |
|  | (0.90) | 1.166 | 1.101 | 1.086 | 1.096 | 1.077 | 1.066 | 1.060 | 1.044 | 1.049 | 1.053 | 1.035 |
| 3 | (0.99) | 2.155 | 2.144 | 2.203 | 2.180 | 2.146 | 2.143 | 2.151 | 2.127 | 2.099 | 2.148 | 2.134 |
|  | (0.95) | 1.574 | 1.525 | 1.529 | 1.496 | 1.462 | 1.476 | 1.491 | 1.475 | 1.478 | 1.501 | 1.473 |
|  | (0.90) | 1.227 | 1.138 | 1.105 | 1.136 | 1.118 | 1.113 | 1.124 | 1.111 | 1.098 | 1.094 | 1.114 |
| 4 | (0.99) | 2.230 | 2.200 | 2.273 | 2.232 | 2.158 | 2.137 | 2.181 | 2.195 | 2.158 | 2.178 | 2.183 |
|  | (0.95) | 1.594 | 1.596 | 1.552 | 1.532 | 1.469 | 1.463 | 1.482 | 1.472 | 1.483 | 1.473 | 1.481 |
|  | (0.90) | 1.219 | 1.175 | 1.192 | 1.177 | 1.136 | 1.132 | 1.111 | 1.099 | 1.104 | 1.112 | 1.111 |
| 5 | (0.99) | 2.233 | 2.215 | 2.245 | 2.162 | 2.102 | 2.172 | 2.163 | 2.204 | 2.168 | 2.136 | 2.179 |
|  | (0.95) | 1.567 | 1.583 | 1.544 | 1.557 | 1.470 | 1.460 | 1.474 | 1.475 | 1.464 | 1.459 | 1.472 |
|  | (0.90) | 1.205 | 1.192 | 1.170 | 1.172 | 1.117 | 1.092 | 1.116 | 1.092 | 1.084 | 1.102 | 1.100 |
| 6 | (0.99) | 2.265 | 2.240 | 2.216 | 2.188 | 2.190 | 2.212 | 2.218 | 2.198 | 2.182 | 2.182 | 2.207 |
|  | (0.95) | 1.576 | 1.548 | 1.536 | 1.546 | 1.498 | 1.491 | 1.477 | 1.509 | 1.507 | 1.496 | 1.478 |
|  | (0.90) | 1.222 | 1.187 | 1.162 | 1.169 | 1.125 | 1.109 | 1.125 | 1.140 | 1.132 | 1.126 | 1.137 |
| 7 | (0.99) | 2.267 | 2.281 | 2.200 | 2.138 | 2.152 | 2.184 | 2.216 | 2.212 | 2.143 | 2.168 | 2.206 |
|  | (0.95) | 1.630 | 1.577 | 1.574 | 1.551 | 1.543 | 1.492 | 1.525 | 1.527 | 1.500 | 1.514 | 1.498 |
|  | (0.90) | 1.223 | 1.178 | 1.180 | 1.195 | 1.164 | 1.142 | 1.168 | 1.169 | 1.165 | 1.137 | 1.134 |
| 8 | (0.99) | 2.253 | 2.284 | 2.231 | 2.210 | 2.106 | 2.156 | 2.199 | 2.195 | 2.181 | 2.182 | 2.225 |
|  | (0.95) | 1.653 | 1.566 | 1.592 | 1.548 | 1.513 | 1.519 | 1.554 | 1.534 | 1.522 | 1.534 | 1.530 |
|  | (0.90) | 1.211 | 1.195 | 1.205 | 1.193 | 1.181 | 1.159 | 1.187 | 1.169 | 1.169 | 1.152 | 1.151 |
| 9 | (0.99) | 2.243 | 2.296 | 2.194 | 2.248 | 2.142 | 2.224 | 2.202 | 2.223 | 2.227 | 2.243 | 2.212 |
|  | (0.95) | 1.613 | 1.595 | 1.557 | 1.532 | 1.561 | 1.530 | 1.543 | 1.546 | 1.539 | 1.549 | 1.544 |
|  | (0.90) | 1.213 | 1.223 | 1.203 | 1.208 | 1.187 | 1.166 | 1.181 | 1.190 | 1.179 | 1.172 | 1.168 |
| 10 | (0.99) | 2.274 | 2.231 | 2.220 | 2.223 | 2.143 | 2.146 | 2.197 | 2.232 | 2.233 | 2.251 | 2.243 |
|  | (0.95) | 1.602 | 1.609 | 1.556 | 1.510 | 1.546 | 1.496 | 1.514 | 1.519 | 1.539 | 1.531 | 1.518 |
|  | (0.90) | 1.244 | 1.226 | 1.208 | 1.194 | 1.176 | 1.175 | 1.177 | 1.178 | 1.162 | 1.175 | 1.170 |

Table A2

| $\begin{aligned} & 0 \\ & \mathrm{i} \end{aligned}$ |  |  | $\begin{aligned} & \text { N } \\ & \underset{\sim}{\sim} \underset{\sim}{\sim} \\ & 0 \end{aligned}$ | $\begin{aligned} & n g= \\ & \cdots \underset{\sim}{n}= \end{aligned}$ | $\begin{aligned} & \hat{6} \underset{\sim}{n} \\ & \underset{\sim}{\sim} \underset{\sim}{=} \end{aligned}$ | $\begin{aligned} & m \underset{\sim}{n} \\ & \underset{\sim}{n} \underset{\sim}{?} \end{aligned}$ | $\begin{aligned} & \pm \\ & \infty \\ & \text { ? } \\ & \hline 1 \end{aligned}$ | $\begin{aligned} & \mathfrak{\sim}-\infty \\ & \underset{\sim}{\sim} \stackrel{\infty}{\square} \end{aligned}$ | $\begin{aligned} & \sigma \odot \infty \\ & \cdots \stackrel{\infty}{=} \\ & \cdots= \end{aligned}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\stackrel{\infty}{-}$ |  |  |  | $\begin{aligned} & n+\infty \\ & \underset{\sim}{\sim} \underset{\sim}{+} \\ & \hline \end{aligned}$ | $\begin{aligned} & \underset{\sim}{\circ} \circ \\ & \underset{\sim}{\circ} \stackrel{O}{-}= \end{aligned}$ | $$ |  | $\underset{\sim}{\infty} \underset{\sim}{n} \underset{\sim}{-}$ | $\begin{aligned} & \text { N } \\ & \text { N } \\ & \text { N } \\ & \text { N } \\ & = \end{aligned}$ |  |
| $0$ |  |  |  |  | $\begin{array}{ll} \infty \\ \underset{\sim}{\infty} \underset{\sim}{\infty} \\ \underset{\sim}{\infty} \\ =1 \end{array}$ | $\begin{aligned} & \infty \\ & \underset{\sim}{=} \stackrel{n}{n} \\ & \hdashline \end{aligned}$ | $\begin{aligned} & 0 \stackrel{\infty}{\sim} \underset{\sim}{n} \\ & \underset{\sim}{\sim} \stackrel{n}{=} \end{aligned}$ | $\begin{aligned} & \text { à } \\ & \text { Nin } \\ & \text { Ni } \end{aligned}$ | $\begin{array}{lll} n \\ \text { No } \\ \text { N } & \\ \text { N } & = \end{array}$ | $\begin{array}{lll} \text { a } & 0 \\ & 0 \\ \cdots & = \\ \cdots \end{array}$ |
| $\stackrel{-}{-}$ |  |  | $\begin{aligned} & \pm \stackrel{i}{O} \\ & \underset{\sim}{\sim} \underset{\sim}{-} \end{aligned}$ |  | $\begin{aligned} & \infty \\ & \underset{N}{\infty} \stackrel{\sim}{\sim} \\ & \cdots \end{aligned}$ |  |  |  |  |  |
| $\stackrel{\square}{-}$ |  |  | $\begin{aligned} & \hat{\alpha} \stackrel{0}{\mathrm{~N}} \underset{\sim}{\infty} \\ & \underset{\sim}{\mathrm{~N}} \underset{-}{2} \end{aligned}$ | $\begin{array}{ll} 0 & 0 \\ \text { N } \\ \text { N } \\ \text { N } \\ \text { N } \end{array}$ | $\begin{array}{lll} 0 \\ \text { N } & 0 \\ \text { N } \\ \text { N } & = \end{array}$ | $\begin{aligned} & 0 \infty \\ & \underset{N}{N} \underset{\sim}{\infty}= \\ & \cdots \end{aligned}$ |  | $\begin{aligned} & n \\ & \cdots \\ & \cdots \\ & \cdots \\ & \cdots \end{aligned}$ | $\begin{aligned} & \bar{i} \vec{\infty} \\ & \underset{\sim}{n} \because \\ & \cdots \end{aligned}$ | $\begin{array}{lll} m & \underset{n}{n} \\ \underset{n}{n} & = \\ \underset{\sim}{n} & \end{array}$ |
| $\bigcirc$ |  |  | $\begin{aligned} & \infty \\ & \underset{N}{*} \underset{\sim}{\mathcal{F}} \underset{\sim}{\infty} \\ & \end{aligned}$ |  | $\begin{aligned} & \hat{n} \circ \stackrel{0}{\infty} \underset{\sim}{\square} \\ & \stackrel{y}{-} \end{aligned}$ | $\frac{20}{2} \stackrel{0}{\square}$ |  |  | $\begin{aligned} & \vec{\sigma} \underset{\sim}{n} \\ & \cdots \stackrel{n}{\sim} \end{aligned}$ | $\cdots \stackrel{\infty}{\text { n }}$－ |
| $\bigcirc$ | $\begin{aligned} & 0 \\ & 0 \\ & 0 \\ & \cdots \\ & \cdots \end{aligned}$ |  | $\begin{aligned} & \hat{o} \underset{\sim}{f} \infty \\ & \underset{\sim}{i} \underset{-}{\infty} \end{aligned}$ |  | $\begin{aligned} & \infty \\ & \frac{\infty}{i} \\ & i \end{aligned}$ |  | $\begin{aligned} & n \underset{N}{N} \underset{\sim}{n}= \\ & \cdots \end{aligned}$ | $\begin{aligned} & \infty \underset{\sim}{\infty} \\ & \underset{\sim}{n} \underset{\sim}{n} \underset{\sim}{n} \end{aligned}$ | $$ | $\begin{array}{lll} \bar{N} & n & 0 \\ \underset{N}{n} & n & \ddots \\ & -1 & -1 \end{array}$ |
| $\stackrel{\square}{6}$ |  | $\begin{aligned} & \bar{\infty} \underset{\sim}{c} \\ & \underset{\sim}{\infty} \underset{-}{\infty} \end{aligned}$ |  |  |  |  | $\frac{\infty}{\sim} \stackrel{\infty}{\square}$ | $\begin{array}{lll} \text { N } & \infty \\ \text { N } & \stackrel{n}{n} \\ \text { N } & = \end{array}$ | ¢ ¢ ¢ ¢ ¢ |  |
| $\stackrel{+}{\circ}$ | $\underset{\sim}{i} \stackrel{\infty}{\top} \underset{\sim}{0}$ | $\begin{aligned} & \hat{a} 9 \\ & 0 \\ & i=0 \\ & i \end{aligned}$ |  |  |  | $\begin{aligned} & 0 \\ & \frac{0}{n} \frac{m}{n} \\ & = \end{aligned}$ |  |  |  |  |
| $\stackrel{3}{O}$ | $$ |  | $\cdots \stackrel{\infty}{\infty} \stackrel{\square}{\square}$ | $\begin{aligned} & \pm \\ & \infty \\ & \cdots \stackrel{\infty}{\sim} \stackrel{\infty}{\square} \\ & = \end{aligned}$ | $\begin{aligned} & \infty \stackrel{N}{\infty} \underset{\sim}{n} \\ & \cdots \stackrel{y}{n} \end{aligned}$ |  |  |  | $\stackrel{N}{N} \underset{\sim}{c} \underset{\sim}{N}$ |  |
| $\overline{0}$ |  | $\begin{array}{lll} \underset{i}{\infty} & 0 \\ \text { N. } & \stackrel{n}{n} \\ \underset{\sim}{n} & \end{array}$ | $\begin{aligned} & m n \underset{\sim}{n} \\ & \underset{\sim}{n} \underset{\sim}{n} \end{aligned}$ |  | $\begin{aligned} & n 8 \stackrel{N}{x}= \\ & \cdots i= \end{aligned}$ |  | $\begin{array}{lll} \infty & \pm & \infty \\ N & \infty & \underset{N}{n} \\ & \square \end{array}$ |  | $\begin{array}{lll} N & 0 \\ \text { N } & \text { N } \\ \text { N } \\ \text { N } \end{array}$ |  |
|  |  |  |  | $\begin{aligned} & \hat{2} \hat{\theta} \\ & \hat{\sigma} \hat{\varrho} \hat{心} \end{aligned}$ |  | $\begin{aligned} & \hat{2} \hat{\sigma} \\ & \hat{\sigma} \hat{\sigma} \hat{e} \end{aligned}$ | $\begin{aligned} & \hat{2} \hat{2} \\ & \hat{\sigma} \hat{\varrho} \hat{心} \end{aligned}$ | $\begin{aligned} & \hat{2} \hat{2} \\ & \hat{\sigma} \hat{\sigma} \dot{\theta} \end{aligned}$ |  |  |
|  |  | N | $m$ | $\checkmark$ | $n$ | $\sigma$ | $\checkmark$ | $\infty$ | $\bigcirc$ | $\bigcirc$ |

Table A3
Percentiles of the HLN and ERIC statistics: Fixed scheme


|  |  |  | $\begin{array}{ll} n & t \\ o \\ \infty & 0 \\ n & n \\ n & n \end{array}$ |  |  |  |  |  |  | $\infty \cdots \infty$ N のด ？ のい |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\infty$ |  | $\begin{aligned} & \underset{\sim}{\infty} \underset{\sim}{\infty} \\ & \dot{\gamma} \underset{\sim}{\infty} \end{aligned}$ |  | $\begin{array}{lll} \bar{N} & \text { No } \\ \text { No No } \\ \text { Ni } \end{array}$ |  | $\begin{array}{ll} \vec{N} \\ \underset{\sim}{N} \\ \text { n } \end{array}$ |  | $\begin{array}{lll} \infty & \cdots \\ \infty & n \\ \infty & \underset{\sim}{\infty} \\ \infty & n & m \end{array}$ |  |  |
| $\underset{-}{\bullet}$ | $\begin{aligned} & \text { N } \\ & \text { No } \\ & \text { N } \\ & \text { rion } \\ & \hline \end{aligned}$ |  |  | $\begin{array}{lcc} N & 0 & N \\ 0 & \hat{N} & \stackrel{n}{n} \\ 0 & \text { m } & n \end{array}$ |  |  |  |  |  | $\begin{array}{ccc} N & N & n \\ \infty & \underset{\sim}{n} & 0 \\ \infty & n & -\dot{r} \end{array}$ |
| $\text { }+$ |  |  | $\begin{aligned} & \underset{N}{N} \underset{\sim}{\infty} \\ & \text { in m } \end{aligned}$ | $\begin{aligned} & 0 \text { on } \\ & \text { ò } \\ & \text { in m } \\ & \text { in } \end{aligned}$ | $\begin{array}{lll} n & \infty & 0 \\ n & 0 \\ & \dot{0} \\ \text { in } \end{array}$ |  |  |  |  |  |
| N |  |  | $\begin{array}{lll} 6 & \hat{c} \\ \text { oh } \\ \text { jo } \\ \text { in } \end{array}$ | $\begin{aligned} & n \\ & \underset{m}{m} \\ & \stackrel{m}{n} \stackrel{n}{n} \end{aligned}$ |  | $\bigcirc 6$ No $\dot{\circ} \dot{\sim}$ |  |  | $\begin{array}{lll} -\infty & \infty & 0 \\ \delta & \infty & n \\ r & \dot{\sim} & n \end{array}$ |  |
| P! |  | $\begin{aligned} & N \underset{\sim}{N} \underset{\sim}{\top} \\ & \underset{\sim}{*} \end{aligned}$ |  |  | $\begin{array}{lcc} n & \infty \\ n & + \\ n & + \\ i n & \cdots \end{array}$ |  |  | $$ | $\begin{aligned} & \hat{n} \\ & \hat{n} \stackrel{\lambda}{n} \\ & 0 \\ & 0 \end{aligned}$ | $\pm$ y in ¢ |
| ${ }_{0}^{\infty}$ |  | $\begin{aligned} & \stackrel{m}{6} \\ & \cdots \\ & \cdots \cdots \\ & \cdots \end{aligned}$ |  |  | $\begin{aligned} & \infty N \\ & \underset{\sim}{\infty} \underset{\sim}{\top} \text { N } \end{aligned}$ | $\begin{aligned} & 0 \\ & 0 \\ & \underset{\sim}{6} \text { N } \\ & \text { n m N } \end{aligned}$ | $\begin{aligned} & m \\ & \infty \\ & \infty \\ & \text { in } \\ & \text { in in } \end{aligned}$ |  |  |  |
| $0$ |  | $\begin{gathered} N \\ \underset{\sim}{N} \underset{\sim}{N} \\ \underset{\sim}{n} \\ \hline \end{gathered}$ |  |  |  |  | $\begin{array}{lll} \infty & \infty & \infty \\ \infty & \infty \\ & \stackrel{1}{n} \\ \dot{\sim} & \cdots \end{array}$ | $\begin{aligned} & \text { No } \\ & \text { N } \\ & \text { nt } \\ & \text { in } \\ & \text { rin } \end{aligned}$ | $$ | $\begin{array}{lll} n & \grave{N} \\ \infty & \underset{N}{\infty} & \infty \\ i n & \dot{n} & \mathrm{~N} \end{array}$ |
| $\stackrel{+}{0}$ |  | $\begin{aligned} & \pm \infty \\ & \vdots \stackrel{\infty}{0} \\ & \text { i } \end{aligned}$ |  | $\begin{array}{lll} \underset{o}{\infty} & \infty \\ + \\ \cdots & n \\ \cdots & n \end{array}$ | $\begin{aligned} & \bar{n} \stackrel{a}{+} \\ & \underset{\sim}{n} \\ & \dot{m} \sim \end{aligned}$ |  |  |  |  | $\begin{array}{lll} \infty & \infty & n \\ \stackrel{n}{n} & \underset{\sim}{n} & \underset{寸}{\forall} \\ \dot{\sim} & \cdots & n \end{array}$ |
| $\bigcirc$ |  | $$ |  | $$ | $$ |  |  | $\begin{aligned} & 8 \underset{\sim}{n} \\ & \cdots \stackrel{n}{n} \end{aligned}$ | $\begin{aligned} & =80 \\ & \text { n } \\ & \text { n } \\ & \text { n } \end{aligned}$ |  |
| $\square$. |  |  | $\begin{aligned} & \text { Nे } \\ & \text { in } \\ & \text { in } \\ & \text { - } \\ & 0 \\ & 0 \end{aligned}$ |  | $$ |  | $\begin{array}{ll} \text { ơ } \\ \text { N } \\ \text { N } \\ \text { N } \\ \hline \end{array}$ |  | $\begin{array}{ll} m \\ \underset{\sim}{*} \stackrel{\infty}{n} \\ \cdots \end{array}$ |  |
|  |  | $\begin{aligned} & \overparen{2} \overparen{\sigma} \\ & \hat{\sigma} \hat{\sigma} \\ & i \end{aligned}$ |  | $\begin{aligned} & \overparen{2} \overparen{2} \\ & \hat{\sigma} \hat{\sigma} \hat{\sigma} \end{aligned}$ | $\begin{aligned} & \hat{2} \hat{2} \\ & \hat{2} \hat{\theta} \hat{e} \end{aligned}$ |  | $\begin{aligned} & \hat{2} \hat{O} \\ & \hat{\sigma} \hat{\theta} \\ & \hat{e} \hat{e} \end{aligned}$ | $\begin{aligned} & \hat{2} \hat{2} \\ & \hat{\sigma} \hat{\theta} \hat{e} \end{aligned}$ |  |  |
| 5 | － | N | $n$ | ＊ | $\cdots$ | $\bigcirc$ | $\bigcirc$ | $\infty$ | a | ㅇ， |

Percentiles of the CM statistic: Rolling scheme

|  | $\underbrace{}_{\substack{0,9 \\ 0.959 \\ 0.35 \\ 0.35}}$ |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| (os) |  |  | $\begin{gathered} 2090 \\ 1.1000 \\ 1.090 \end{gathered}$ |  |  | $\begin{gathered} 4,90 \\ 1,204 \\ 1,042 \end{gathered}$ |  |  |  | $\underset{\substack{6,38 \\ 2.398 \\ 2941}}{\substack{40 \\ \hline}}$ |  |
| (as) |  | $\underset{\substack{2,27 \\ 1.094 \\ 0,94}}{\substack{20 \\ \hline}}$ |  | $\begin{gathered} 4,28 \\ \substack{420 \\ 1,064} \end{gathered}$ |  |  | $\begin{gathered} 6,045 \\ 20454 \\ 24045 \end{gathered}$ |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| $\stackrel{(1020)}{(0,0)}$ | $\begin{aligned} & 1,291 \\ & 0.851 \\ & 0.81 \end{aligned}$ | $\underset{\substack{288 \\ 128 \\ 120}}{\substack{28 \\ \hline}}$ |  |  |  |  |  |  |  | $\underset{\substack{8,58 \\ 58,8 \times 5}}{\substack{8,5}}$ | (163 |
|  |  |  |  |  |  |  |  |  | $\underset{\substack{8,788 \\ 8.808}}{\substack{811}}$ |  |  |
| (1090) |  |  |  |  |  |  | $\underset{\substack{8,38 \\ 3,380}}{\substack{8,50}}$ |  |  |  | $\underset{\substack{10.35 \\ \text { and } \\ 4.951}}{\text { a }}$ |
|  |  |  | $\begin{gathered} 4.951 \\ 2 \times 2516 \end{gathered}$ |  |  |  | $\begin{gathered} 8,920 \\ \hline 8.044 \\ 4.044 \end{gathered}$ |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  | $\begin{gathered} 1.154 \\ 5,149 \\ \hline, 49 \end{gathered}$ |  |
| (om) |  |  |  |  | (inc |  | $\underbrace{\substack{150}}_{\substack{9,50 \\ 4.580}}$ |  | $\underbrace{\substack{18}}_{\substack { 10,98 \\ \begin{subarray}{c}{927{ 1 0 , 9 8 \\ \begin{subarray} { c } { 9 2 7 } }\end{subarray}}$ | , | ${ }^{12048}$ |

Table A6
Percentiles of the CM statistic: Fixed scheme



[^0]:    *Clark: Economic Research Dept., Federal Reserve Bank of Kansas City, Kansas City, MO 64198, tclark @frbkc.org. McCracken: Dept. of Economics, Louisiana State University, 2107 CEBA Building, Baton Rouge, LA 70803, mmccrac@unix1.sncc.lsu.edu. The research assistance of Hilary Croke and the helpful comments of Lutz Kilian and Ken West are gratefully acknowledged. The views expressed herein are solely those of the authors and do not necessarily reflect the views of the Federal Reserve Bank of Kansas City or the Federal Reserve System.

[^1]:    ${ }^{1}$ Diebold and Mariano (1995) also suggest using out-of-sample forecast tests to examine Granger causality.

[^2]:    ${ }^{2}$ Most of the other available tests of forecast accuracy or encompassing - such as the Mizrach (1992) and Granger and Newbold (1977) tests of equal accuracy - are also asymptotically invalid when applied to nested forecasts.

[^3]:    ${ }^{3}$ Computing the tests as Wald statistics and comparing them against the chi-square distribution would make the tests robust to non-normally distributed data. However, using the Wald statistics produces results very similar to those

[^4]:    ${ }^{4}$ Condition efficiency in turn draws from the forecast combination literature, started by Bates and Granger (1969). The regression (5) can be used to determine the optimal combining weight. The linear combination of forecasts 1

[^5]:    ${ }^{5}$ As presented in Ericsson (1992) and used by others, the test often is expressed as a regression of the error from model 1 on the difference in forecasts rather than forecast errors. But that regression is equivalent to (6), with the appropriate sign change.

[^6]:    ${ }^{6}$ There is a parallel to this in McCracken (1999). There it is shown that the DM statistic has the same limiting distribution as the regression-based test for equal MSE by Granger and Newbold (1977).
    ${ }^{7}$ For the basic models considered below a modified CH test, that takes the form of the covariance between the LHS and RHS of (8) divided by an estimate of the standard error of the covariance, has modestly better size properties but

[^7]:    regression test.
    ${ }^{8}$ Using Kilian's (1998) bootstrap method to adjust the coefficients of the models produces essentially the same Monte Carlo results.

[^8]:    ${ }^{9}$ For the empirical model, using bootstrap methods to generate artificial data produces results much like those reported for Monte Carlo-generated data.
    ${ }^{10}$ In the case of the simple $\operatorname{VAR}(1)$ model, when $b$ is non-zero, the true VAR implies that the true univariate model for $y_{t}$ is an $\operatorname{ARMA}(2,1)$. For the models considered here, however, inverting the MA component to rewrite the $\operatorname{ARMA}(2,1)$ in AR form yields very small coefficients on lags greater than 1 , so the true (infinite order) AR model is very close to an $\operatorname{AR}(1)$. Accordingly, in the Monte Carlos the selected AR lag length is 1 in about 75 percent of the power simulations.
    ${ }^{11}$ In computing power when the lags are data-determined, the test statistic in simulation $i$, for which the selected lag is j , is compared against the distribution of test statistics from the set of simulations under the null in which the lag was selected to be j . For example, if lag j was selected in J of the 50,000 size simulations of a given experiment, empirical critical values for lag j were calculated from just those J simulated test statistics. In a corresponding power experiment, for those simulations in which the lag was selected to be j , the test statistics were compared against these critical values. Since longer lags tend to be somewhat infrequently rejected, 50,000 simulations were used in the size experiments to ensure the accuracy of the results with data-determined lags.

[^9]:    ${ }^{12}$ While results for rolling forecasts are very similar to those for recursive forecasts, results for fixed forecasts do differ slightly. For example, with fixed forecasts, the size distortions of the asymptotically valid DM test are smaller, while the size distortions of the CM test are a bit bigger.

[^10]:    ${ }^{13}$ Increasing P, however, does not necessarily make the empirical distribution of the test statistic quickly approach a normal distribution. CH test rejections occur more frequently in the left tail than in the right tail. When a nominal size $\alpha \%$ is used, right tail rejections occur in less than $\alpha / 2 \%$ of the simulations. As P rises, right tail rejections occur even less frequently and account for most of the observed improvement in the empirical size of the CH test.

[^11]:    ${ }^{14}$ However, if the lags of the AR and VAR models are set at the order minimizing the Akaike criterion for the insample AR model, the in-sample GC test is essentially correctly sized, just as when the lag is set at the true order.

[^12]:    ${ }^{15}$ For those tests subject to small size distortions, particularly the OOS F and CM tests, power based on asymptotic critical values is very similar to the reported size-adjusted power.

[^13]:    ${ }^{16}$ The forecasts are slightly biased. However, demeaning the errors prior to calculating the test statistics has little effect on the results.

[^14]:    ${ }^{17}$ The models do, however, pass the Nyblom (1989) test for stability and Chow tests for a shift in the parameter estimates between 1958:Q3-87:Q1 and 1987:Q2-97:Q3. Following Diebold and Chen (1996), the stability test results are based on bootstrap critical values.

