

# Estimating Multi-Way Fixed Effect Models with **reghdfe**

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<http://scorreia.com/software/reghdfe/>

<https://github.com/sergiocorreia/reghdfe>

# Introduction

`reghdfe` implements the estimator from:

- Correia, S. (2016). Linear Models with High-Dimensional Fixed Effects: An Efficient and Feasible Estimator. [Working Paper](#)

Borrows heavily from previous contributions, many from the Stata camp (`reg2hdfe`, `a2reg`, `gpreg`)

Use it to control for unobservables that stay constant within an economic unit (workers, firms, exporters, importers, etc.)

Applications in many fields: accounting (DeHaan et al 2015), finance (Gormley et al 2015), labor (Guimarães et al 2015), trade (Mayer 2016), etc.

# Estimator

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## Linear Fixed Effect Models — Problem

We want to compute the least squares estimates  $\hat{\beta}$  of

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{D}\boldsymbol{\alpha} + \boldsymbol{\varepsilon}$$

- $\mathbf{D} = [\mathbf{D}_1 \ \mathbf{D}_2 \ \cdots \ \mathbf{D}_F]$  consists of  $F$  indicator matrices
- If  $F = 1$ , this collapses to a standard fixed effect regression (`xtreg`, `areg`)
- Can't use dummies because  $[\mathbf{D}_2 \ \cdots \ \mathbf{D}_F]$  is too large

# Linear Fixed Effect Models — Solution Strategy

Steps:

1. Compute the residuals of  $\mathbf{y}$  and  $\mathbf{X}$  against  $\mathbf{D}$ :

$$\tilde{\mathbf{y}} = \mathbf{M}_D \mathbf{y}$$

$$\tilde{\mathbf{X}} = \mathbf{M}_D \mathbf{X}$$

2. Apply the Frisch–Waugh–Lovell Theorem:

$$\hat{\boldsymbol{\beta}} = (\tilde{\mathbf{X}}' \tilde{\mathbf{X}})^{-1} \tilde{\mathbf{X}}' \tilde{\mathbf{y}}$$

Thus, we can just focus on one variable at a time:  $\tilde{\mathbf{y}}$

## Linear Fixed Effect Models – Solution Strategy

To obtain  $\hat{\mathbf{y}} = \mathbf{M}_D \mathbf{y}$ , find an  $\hat{\boldsymbol{\alpha}}$  that satisfies the normal equations

$$\mathbf{D}'\mathbf{e} = 0 \quad , \quad \mathbf{e} \stackrel{\text{def}}{=} \mathbf{y} - \mathbf{D}\hat{\boldsymbol{\alpha}}$$

In plain English:

*For every level  $g$  of every fixed effect  $f$  the mean of the residuals must be zero:*

$$\bar{e}_i = 0 \quad , \quad i \in \mathcal{J}(f, g)$$

*Note: We don't care if  $\hat{\boldsymbol{\alpha}}$  is unique*

# Outline of the Algorithm

1. Divide and conquer: apply FWL to work on one variable at a time
2. Apply Method of Alternating Projections (MAP)
3. Accelerate MAP with conjugate gradient
4. Insights from graph theory: exactly the same problem as solving a Graph Laplacian

## MAP - Definition

$$\lim_{n \rightarrow \infty} \|(\mathbf{M}_1 \cdot \mathbf{M}_2 \dots \mathbf{M}_F)^n \mathbf{y} - \mathbf{M}_{12\dots F} \mathbf{y}\| = 0$$

Suggests iteration:

$$\mathbf{y}_{k+1} = \underbrace{(\mathbf{M}_1 \cdot \mathbf{M}_2 \dots \mathbf{M}_F)}_{\text{Linear Transform } \mathbf{T}} \mathbf{y}_k$$



## MAP - Example (1/2)

```
sysuse auto, clear
```

```
// Benchmark
```

```
areg price gear length i.trunk, absorb(turn)
```

## MAP - Example (2/2)

```
foreach var in price gear length { // FWL Step
  forval i = 1/10 { // MAP Step
    foreach fe in turn trunk {
      qui areg 'var', absorb('fe')
      predict double resid, resid
      drop 'var'
      rename resid 'var'
    }
  }
}
regress price gear length, dof(38) nocons
```

# MAP - Problem #1

Bauschke et al (2003):

*[...] The main practical drawback of the MAP appears to be that it is often slowly convergent [...] Franchetti and Light and Bauschke, Borwein, and Lewis have given examples showing that the convergence [...] can be arbitrarily slow!*

**It can be very, very slow!**

(In particular when the underlying fixed effects are *poorly connected*)

## MAP - Problem #1

	y	id1	id2
1	1	0	0
2	0	0	1
3	0	1	1
4	0	1	2
5	0	2	2
6	0	2	3
7	0	3	3
8	0	3	4
9	0	4	4
10	0	4	5

Figure 1: This dataset will turn your PC into a heater in the winter

Guimarães & Portugal (2010) and Gaure (2013) apply accelerations that are related to steepest descent

$$\mathbf{y}_{k+1} = t \underbrace{(\mathbf{M}_1 \cdot \mathbf{M}_2 \dots \mathbf{M}_F)}_{\text{Linear Transform } \mathbf{T}} \mathbf{y}_k + (1 - t)\mathbf{y}_k$$

Often improve speeds significantly, but ...

## MAP - Problem #2

Bauschke et al (2003):

*[...] perhaps surprisingly, we show that the acceleration scheme may actually be slower than the MAP [...]!*

Hernández-Ramos et al (2011):

*[...] the steepest descent method is known for its slowness in the presence of ill-conditioned problems [...]*

## MAP - Solution #2

- Why apply steepest descent and not conjugate gradient?
- Because CG requires a symmetric transform and  $T \stackrel{\text{def}}{=} \mathbf{M}_1 \cdot \mathbf{M}_2 \dots \mathbf{M}_F$  is not symmetric
- Solution: follow Hernández-Ramos et al (2011) and make it symmetric:

$$T^{\text{Sym}} \stackrel{\text{def}}{=} \mathbf{M}_1 \cdot \mathbf{M}_2 \dots \mathbf{M}_F \dots \mathbf{M}_2 \cdot \mathbf{M}_1$$

$$T^{\text{Cim}} \stackrel{\text{def}}{=} (\mathbf{M}_1 \cdot \mathbf{M}_2 \dots \mathbf{M}_F) / F$$

- Theoretical advantages (monotonic convergence) and practical ones (as fast as other methods for easy problems, significantly faster for ill-defined ones)

Not fast enough for some applications, can we speed it even more? Yes!

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## Link with Graph Theory

- Let's rewrite the two-way fixed effect model as a graph:
- If CEO  $j$  has only worked at firm  $k$ :

$$\sum_{i \in j} y_i - n_j \hat{\alpha}_j - n_j \hat{\gamma}_k = 0$$

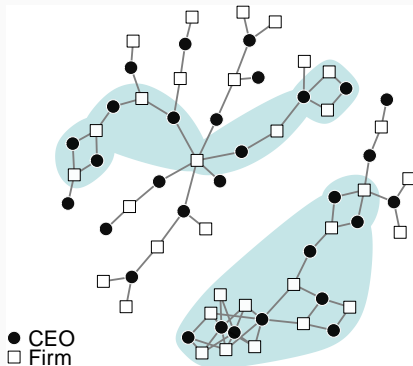


Figure 2: Graph of CEO–Firm Connections

## Link with Graph Theory

- Solving a two-way fixed effects problem is *exactly* the same problem as solving  $\mathbf{Lx} = \mathbf{b}$  where  $\mathbf{L}$  is a Laplacian matrix
- Spielman & Teng (2004), Kelner et al (2013):
  - Laplacian systems can now be solved in nearly-linear time, instead of in  $O(n^{2.36})$ !
  - This is a fundamental breakthrough in graph theory and numerical optimization, and we can apply it to solve our model
- Can also apply other insights from graph theory (e.g. graph condition number)

# Link with Graph Theory

However:

- Solver has a very complex implementation
- Suffers from cache locality problems (Hoske et al 2015, Boman et al 2016)
- What's the point of an  $O(n)$  solver if Stata requires multiple sorts?  $O(n \log n)$
- Solution: use a better sorting algorithm (see [ftools](#) package)

# Implementation

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# reghdfe

```
sysuse auto  
ssc install reghdfe  
reghdfe price weight, absorb(turn trunk foreign)
```

```
. reghdfe price weight, absorb(turn trunk foreign)
```

```
(dropped 9 singleton observations)
```

```
(converged in 13 iterations)
```

```
HDFE Linear regression
Absorbing 3 HDFE groups
```

```
Number of obs =      65
F( 1, 38) =      25.43
Prob > F =      0.0000
R-squared =      0.6563
Adj R-squared =     0.4211
Within R-sq. =     0.4009
Root MSE =     2203.9341
```

price	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]
weight	<b>4.978642</b>	<b>.9872606</b>	<b>5.04</b>	<b>0.000</b>	<b>2.980037 6.977246</b>
Absorbed	F(25, 38) =		<b>1.879</b>	<b>0.037</b>	(Joint test)

```
Absorbed degrees of freedom:
```

Absorbed FE	Num. Coefs. =	Categories -	Redundant
turn	13	13	0
trunk	12	13	1
foreign	1	2	1 ?

```
? = number of redundant parameters may be higher
```

Figure 3: reghdfe screenshot

## Design Principles: Simplicity

```
a2reg price gear, individual(turn) unit(foreign)
      indeffect(FE1) uniteffect(FE2)
```

```
reg2hdfe price gear, id1(turn) id2(trunk) fe1(FE1)
      fe2(FE2) uniteffect(FE2)
```

```
gpreg price gear, ivar(turn) jvar(trunk) ife(FE1)
      jfe(FE2)
```

```
felstdvregdm price gear, ivar(turn) jvar(trunk)
      peff(FE1) feff(FE2)
```

These are wonderful packages, but can we do better? (See [The Zen of Python](#), [Python for Humans](#), etc.)

## Design Principles: Simplicity

reghdfe price gear, a(turn trunk, save)



## Design Principles: Powerful Under the Hood

IV Regressions:

```
reghdfe price (gear=length), a(turn trunk)
```

Multi-way clustering:

```
reghdfe price gear, a(turn trunk)  
vce(cluster turn foreign)
```

Additional VCE methods:

```
reghdfe price gear, a(turn t) vce(cluster  
turn t, bw(2) kernel(parzen))
```

## Design Principles: Powerful Under the Hood

Supports most standard Stata features:

```
reghdfe L.price i.foreign [aw=length],  
a(turn trunk)
```

Heterogeneous slopes:

```
reghdfe price weight, a(turn##c.gear)
```

```
reghdfe price weight, a(turn##c.(gear  
length) trunk)
```

## Design Principles: Powerful Under the Hood

Save users' time:

```
reghdfe price gear, absorb(turn#trunk)
cluster(turn#foreign)
```

Also: implemented in heavily optimized Mata code (`reghdfe` is faster than `areg` and `xtreg` even for one set of fixed effects!)

## Design Principles: Don't Reinvent the Wheel

Most features come from the Stata community: see `reghdfe`, `version`

- `ivreg2` or `ivregress` for IV/GMM models
- `avar` for VCE estimation
- `tuples` for MWC
- `group3hdfc` to compute degrees-of-freedom
- Learned *a lot* from `reg2hdfc`, `a2reg`, etc.
- Supports `esttab: viewsource estfe.ado`

# Design Principles: Don't Let Users Shoot Themselves in the Foot

Same principle behind `use ...`, `clear`

Warn about several gotchas:

- Drop `singleton groups`, which might affect VCE estimates
- Compute `conservative` degrees-of-freedom
- Present alternatives to overall `R2`, which might be `misleading`

# Improvements and Extensions (1)

- Fixed effects are not identified; researchers are using it incorrectly; alternatives?
- Can we provide better VCE estimates? (e.g. Cattaneo et al 2016)
- What if every obs. has a varying number of fixed effects? (board of directors)

## Improvements and Extensions (2)

- `lsmr` estimator from Matthieu Gomez
- `ftools` allows significant speedups in Stata with large datasets (based on optimizations by Python's Pandas)
- Publicize collected benchmark datasets

## Also see

- [Detailed manual](#)
- [Github bug tracker](#)



Thank you!

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