Competing Norms of Cooperation^{**}

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Abstract

A key question concerning social norms is whether norms that are bad for its members can survive. This paper argues that when identical workers have the outside option to join a competing rm with a di®erent norm, good norms can exist only in the presence of bad norms. With non contractible e®ort, agents cannot credibly commit to cooperation when all outside options are equally good. This is proposed as a rationale for endogenous strati⁻cation of coexisting norms and corporate cultures. The framework naturally gives rise to authority relations within rms: seniors earn higher wages than entering juniors. However, authority is limited and does not eradicate the strati⁻cation of norms.

Keywords. Social Norms. Matching. Authority. Trust. Inequality.

1 Introduction

Social norms play an important role in economics and social sciences.¹ Peer groups, Ma⁻a gangs, fraternities, religions, ⁻rms,... have all very di[®]erent rules of behavior to which members voluntarily adhere. A fraternity member who does not agree with the terms on how to ⁻nance the services provided, is free to leave and join another association. Even members of religious groups are reported to change membership (turnover in cults is extremely high; 40% of all Protestants leave to another faith). Firms have workers coming and going. Some ⁻rms are known to have a strong corporate culture with high employee cooperation, others have a weak culture. This paper is an attempt to model norms of cooperation, while individuals can choose which norm to belong to. A

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¹Knack and Keefer (1997) show that the average of a country's norms (measured as trust or social capital) signi⁻cantly increases its per capita growth rate in cross country comparisons.

member's willingness to adhere to the norm is determined by the outside option of joining other norms available in the economy. In understanding norms as a social phenomenon, attention is naturally drawn towards the di®erence in characteristics and behavior between norms. The theory of conventions (see for example Young (1993)) explains norms as a device for the coordination of actions in a setting where there is no interaction between members of separate societies (familiar examples include driving left or right on the road, standing up or sitting down through the entire game in a sports stadium). An equally signi⁻cant issue, hitherto ignored by economists, is what the e®ect is of competition between norms. Social Norms are as much a societal feature with interaction between norms through mobility of its members. Can social norms that are bad for its members survive? In the presence of unlimited entry, and free mobility, will social norms tend to become uniform because citizens will choose the successful norms only?

In this paper, a social norm is referred to as a set of common characteristics, behavior, beliefs,... that apply to a subgroup of society, in our case the \neg rm. Each individual \neg rm has a social norm associated with it. We believe that applying our theory to the case where the subgroup is a \neg rm, is justi \neg ed for two reasons: 1. Empirical evidence suggests that norms within a \neg rm are strongly related to productivity;² 2. Firms operate in an environment where there is su±cient mobility of its members. By choosing the \neg rm as our focus of attention, we concentrate on the interplay between private incentives and group incentives within the social norm.³ That does not imply that the individual \neg rm's norm stands alone, independent of other \neg rms' norms in the economy. Competing norms can only exist if it is an equilibrium in the social norm is the result of a (voluntary) implicit contract.

Consider the basic components of the competing norms model in more detail. 1. Each rm is characterized by a social norm: one rm, one norm. 2. The norm of a rm is determined by the contribution of e®ort of each of its members. The stage game builds on Holmsträm's (1982) analysis of moral hazard in teams. Firms have a production technology where a rxed number of employees jointly provide e®ort. E®ort is not contractible, but after production is realized, output is observed. The immediate private bene t is determined by a budget balancing sharing rule. 3. The model is dynamic. Because all workers are non-myopic and forward looking, in their actions they trade o® current gains and losses with the discounted future changes in value. 4. Matching is endogenous. After realization of the output, a worker will either remain in the rm or leave the

²Kotter and Heskett (1992) and Cappelli and Neumark (1999) ⁻nd strong evidence of heterogeneity of norms (corporate culture) between ⁻rms. In addition, both studies show a signi⁻cant relation between productivity and a measure for the quality of the norm.

³The value of a rm's social norm can be referred to as its aggregate social capital (as introduced by Loury (1977), and Coleman (1990)). However, it will be the individual (or behavioral) social capital that determines costs and bene ts of membership, and whether an individual member in the group is willing to comply with the rm's norm or not. This distinction between an individual based as opposed to a group based de nition of norms, is drawn from Loury (1977) and Glaeser, Laibson, Scheinkman and Soutter (1999). We also adopt their view that a rm's norm is only as good as the aggregate of it's members' individual social capital.

⁻rm after which she is randomly matched to a new ⁻rm. Endogenous separation can occur for two reasons: either because she decides to leave the ⁻rm or because of punishment: she is made redundant. In addition, there is an exogenous separation probability. Any separated employee randomly draws a new ⁻rm. There is no friction in this model as matching is instantaneous (the Poisson arrival rate of a match is in⁻nity) and employees prefer any match for one period than receiving zero utility from remaining unmatched.

In the model described above, a worker joining a rm with a norm of cooperation gets a higher level of utility by cooperating than she would get in a rm with a norm of non-cooperation. However, given her belief that all other employees in that rm will cooperate, she can get even higher utility by free riding through less e®ort. In the static game this is a dominant strategy. In the dynamic game, whether this is a optimal strategy or not depends on her expectations about her future utility. Suppose we have an equilibrium where all rms have a norm of cooperation. Free riding implies she will be made redundant at the end of the period. When separated, she is instantaneously matched to a new rm, drawn from the distribution of rms. Given the belief that all rms have norms of cooperation, with probability one she will be matched to a rm with a norm of cooperation. Her future value after separation is not lower by being rematched. This implies that free riding, which yields a higher °ow utility, is a dominant strategy. An equilibrium where all rms cooperate does not exist because it is not individually incentive compatible.

When a fraction of ⁻rms do and the complementary fraction do not cooperate, then the option value of defecting when matched to a cooperating rm depends on the expected value of being rematched. If there are su±cient ⁻rms with a norm for non-cooperation, then the expected value of rematching is proportionally lower than the option value of cooperating and remaining in the good norm ⁻rm. If the immediate gain from free riding is not larger than the expected discounted future loss, it is a dominant strategy for an employee matched to a high norm ⁻rm to cooperate and not separate. Consider the equilibrium where each employee adheres to this strategy when matched to a ⁻rm with a norm of cooperation, and free rides with immediate separation in all other ⁻rms. We want to verify for deviations by all employees. First, given this belief, a strategy of cooperation without separation when matched to a cooperative norm is incentive compatible. No employee in a cooperating rm can gain from deviating. Second, when matched to a rm with a norm for non-cooperation, the best response when all free ride is to free ride. Providing e®ort above the static Nash level would yield less utility (by de-nition of the Nash equilibrium). In addition, separation is a dominant strategy as the expected value of rematching is higher than the value of remaining in a low cooperation ⁻rm: there is a fraction of high cooperation norms around that yield a higher utility than the low norms. Since no employee gains from deviating, this belief is con⁻rmed by the equilibrium actions.

This is the main result of the competing norms model. A norm of cooperation can exist only if there is a su \pm cient number of \neg rms with a norm of non-cooperation. Though cooperation implies a positive externality within the \neg rm, it also has a negative external e[®]ect on all other \neg rms through

the improved outside option of the workers in all other ⁻rms.⁴ Despite the fact that all agents are identical, norms are heterogeneous and as a result there is a wage di®erential across ⁻rms. The wage gap results in a higher degree of turnover in low e®ort ⁻rms. Employees in the low norm ⁻rm separate as quickly as possible in order to try and match a high norm ⁻rm. Note also that the wage di®erential occurs for identical workers, while at the same time it is necessary to sustain incentive compatibility and hence equilibrium.

A result new to the literature follows from extending the model to allow for a market for authority. With exogenous sharing rules, new entrants in a "rm with a norm of cooperation receive a strictly higher option value than in a low norm "rm. Senior incumbents can extract some of the rents by setting the sharing rule such that the junior entrant is still willing to enter. This type of "backloading" or "performance bonds" have in the past been proposed as a solution to these dynamic incentives problems: a market for junior job openings determines the wage-tenure schedule and makes entrants indi®erent between good and bad "rms.⁵ The contribution here is to show that such a market for authority does not necessarily result in the indi®erence between the option value of entering a good and that of a bad "rm. It is shown that limited authority arises because lowering the share violates the incentive compatibility constraint of the new entrant, and no "rm "nds it optimal to do so. This is the case when exogenous separation is relatively low compared to the discount rate. The result is that even in the presence of a market of authority, junior workers are not indi®erent between the option value of good and bad "rms, and that strati"cation of "rm norms persists.

These results are compatible with empirical <code>-ndings</code> of heterogeneity in incomes amongst observationally equivalent workers. Krueger and Summers (1988) <code>-nd</code> evidence against explanations based on unmeasured di[®]erences in ability across industries. This suggests that competing norms may help explain endogenous heterogeneity. In addition, their analysis shows that turnover and wages for observationally identical workers are negatively related, and that the wage structure is highly correlated with job tenure. Both these facts <code>-t</code> the competing norms model: bad norm <code>-rms</code> pay low wages and have high turnover, and wage-tenure schedules for identical workers arise naturally in good norm <code>-rms</code>.

This paper is related to a large literature in economics on social norms. The theory of conventions (Young (1993)) proposes an explanation for the existence of social norms that is based on coordination. When there are multiple Nash equilibria, a convention (e.g. driving on the left) coordinates

⁴Eeckhout and Jovanovic (1998) show that inequality necessarily arises in a dynamic framework, when an economy-wide production externality involves higher moments of the distribution of types. This is the case in our model: low norm ⁻rms induce a positive externality while high norm ⁻rms have a negative external e[®]ect. Note that this is not the case for example in standard endogenous growth models where only the mean of the distribution of types enters the externality. In such a framework, inequality has no real e[®]ect.

⁵Because of this indi[®]erence, no worker is better o[®] than any other (irrespective of the ⁻rm in which she works), but that does not imply the bad norm ⁻rms are eradicated.

beliefs and actions, just like a focal point. The extensive literature following this interpretation has a long standing tradition dating back to Arrow's (1973) application to discrimination.⁶ Competing norms di[®]er from conventions in three substantial aspects. First, conventions derive behavior that applies to an economy as a whole rather than to a subgroup of the economy. Roughly speaking, a norm relates to a convention as culture relates to society.⁷ Second, mobility between di[®]erent conventions is not modeled. Third, the theory of conventions is about homogeneous (because coordinated) behavior within an economy. In contrast, the competing norms model provides a rationale for observed heterogeneity and strati⁻cation within the same economy.

Surprisingly, not much theoretical work has been done on competing norms. The line of research that provides most of the fundamental building blocks of our model is the work on the theory of repeated games. The main result in this literature⁸ is formulated as the folk theorem: any individually rational payo[®] can be sustained in a subgame perfect equilibrium for high enough discount factors. Not only has this been shown to hold for a -xed set of players, but also for randomly matched players as long as there is some aggregate information available.⁹ Most relevant to our model is the work on the folk theorem with endogenous matching and without information °ows. Ghosh and Ray (1996) and Kranton (1996) make important contributions by showing that in such an environment, cooperation can exist where the behavior is characterized by a gradually increasing degree of cooperation. Greif (1993) ⁻nds evidence for this practice and for endogenous matching in early trade relations in the Magreb. Ghosh and Ray use exogenous heterogeneity to model the economy: some traders are irrational and are never willing to cooperate. Through gradually increasing degrees of cooperation, rational players can learn the type of their partner. This work shows that the strategy described above, when commonly adopted by all agents in the economy (i.e. a convention), yields cooperation. Neither of these papers on endogenous matching takes up the main concern here - whether bad norms of low cooperation can exist in the presence of norms of high cooperation.

The paper is organized as follows. In the following section, the competing norms model is presented. Given exogenous sharing rules, in section 3 the model is solved and the main result, strati⁻cation of

⁶Conventions have also provided an explanation for history and belief dependent equilibria in several dynamic settings: customs in the marriage market (Cole, Mailath and Postlewaite (1992)), training and turnover di[®]erentials (Acemoglu and Pischke (1998)), corruption (Tirole (1996)) and corporate culture (Kreps (1990) and Carillo and Gromb (1999)).

⁷" [...] society provides the larger reference groups and culture the local reference groups with respect to which norms [...] operate. Culture is local and allows for strong bonds to a small number of persons. Society is global and allows for weaker ties to a larger number of persons.", Elster (1989), p. 250.

⁸See Fudenberg and Maskin (1986) for most of the results in the case of repeated interaction between the same players.

⁹Rosenthal (1979) shows that cooperation can be sustained through the evolution of reputation. Okuno-Fujiwara and Postlewaite (1990) derive a similar result where the information available is much less speci⁻c and is transmitted as an economy wide social norm. Random matching can also result in cooperation without such information as long as the populations is small enough: Kandori (1992) and Ellison (1994) show this using contagion strategies, i.e. punishments that unravel and spread through the whole population fast enough so as to impose su±cient punishment.

norms, is derived. This is illustrated with an example and further discussed with some comparative statics results. In section 4, the market for authority is introduced. Though wage-tenure schedules arise naturally, authority is limited and does not eradicate strati⁻cation. The robustness of the model to the introduction of capital, general monitoring technologies, general sharing rules and renegotiation is discussed in section 5. In section 6, the implications for the model from extensions to include heterogeneous agents and complementary inputs in production are considered. Finally, some concluding remarks are made.

2 The Competing Norms Model

In this section, the basic model is presented. We describe the incentives employees face when joining a rm with a certain social norm, and de ne equilibrium.

Workers, Firms and the Stage Game. The economy is populated with an in-nite number of identical workers. The set of workers W has measure 1 and each worker is interpreted as an in-nitesimally small subset of W. Production occurs in rms of a red and nite number of m > 2 worker. Index workers within a rm by i = 1; ...; m. The set of all rms is given by N and has measure $\frac{1}{m}$: A generic rm is referred to as n 2 N. For the purpose of the characterization below, consider the partition fC; Dg of N, where c 2 C is a rm with a norm of cooperation and d 2 D is a rm with a norm of non-cooperation.

We want to capture the notion of joint production. The stage game is therefore as Holmsträm's (1982) moral hazard in teams model. Total output y produced in a \mbox{rm} is a function of all individuals' e®ort. Let e_i be worker i's level of e®ort and let e = (e₁; ...; e_m) be the vector of all e®ort levels in a \mbox{rm} n: The \mbox{rm} 's total output produced y = Q(e) is deterministic and symmetric in e_i: Workers receive a share s_i(Q); 8i of total output. The utility cost of e®ort to each individual is C(e_i), with C convex. The utility of agent i is given by

$$u_i = s_i (Q(e))_i C(e_i)$$
 (1)

Given the sharing rule, agents choose their level of e^{is} ort e_i ; they produce, and in function of the vector e; output Q is realized. E^{is} ort is not contractible, which gives rise to the moral hazard problem. Ex ante shares rules are binding because they are contracted, and ex post output is perfectly observed.

In a competitive environment, <code>rms'</code> pro<code>ts</code> are zero. Given a technology without physical capital, it follows that the total wage bill is equal to total production. We have chosen this simple production function to economize on notation. In section 5, the model is shown to be robust to the introduction of a production function with physical capital in addition to e[®]ort. Throughout the paper, the following assumption is maintained: the sharing rule $f_{s_i}(Q)g$ satis⁻es Balanced Budget: $P_{i=1}^m s_i(Q) = Q$:

Holmsträm (1982) shows that the solution to the static game with budget balancing sharing rules is ine±cient. Given the vector of e[®]ort choices by all other workers e_{i} ; 8_i i(6 i) 2 n, the best response correspondence of worker i satis⁻es arg max_{ei} fs_i (Q(e_i; e_i))_i C(e_i)g: The Nash equilibrium e[®]ort e^a_i; with corresponding utility u^a satisfying (1), solves for the ⁻xed point e^a_i = arg max_{ei} s_i Q(e_i; e^a_i) i C(e_i); 8i: Pareto optimal e[®]ort e^o_i yield utility u^o; and satis⁻es e^o_i = arg max_{ei} Q(e_i; e^o_i) C(e_i).

Theorem 1 (Holmsträm) There do not exist sharing rules $f_{s_i}(Q)g$ which satisfy $\mathbf{P}_i s_i(Q) = Q$, and which yield e_i^o as a Nash equilibrium in the non cooperative game with payo®s u_i^o :

Would all workers cooperate and provide optimal e^{\circledast} ort levels e° , then an individual best response is to deviate and provide e^{\circledast} ort $e^{d} \in e^{\circ}$ such that $e^{d} = \arg \max_{e_{i}} s_{i} Q(e_{i}; e^{\circ}_{i})_{i} C(e_{i})$; which yield u^{d} .¹⁰ As a corollary to the theorem it follows that for a given sharing rule, equilibrium e^{\circledast} ort $e^{\alpha} < e^{\circ}$ is suboptimal and that $u^{d} > u^{\circ} > u^{\alpha}$. The theorem holds for a general production function and for general sharing rules.

The ine±ciency result crucially hinges on the assumption of budget balancing sharing rules. A large part of the literature has given attention to studying incentives in environments where this assumption can be relaxed, for example involving an independent principal (see Holmsträm (1982)). Perhaps of equal importance is the interaction between joint production and mobility across ¬rms. Our analysis is an attempt to complement the incentives approach.¹¹ The objective here is to ¬nd solutions for the moral hazard problem even in environments where the budget is balanced. This is the case for example where it is not possible to involve a completely independent principal. Any dependent principal needs to be considered as one of the employees, which brings us back to the ine±ciency. In the case of partners in a law ¬rm for example, partners are both the owners and employees.

Matching and Monitoring. Consider now the repeated game, where utility that is delayed for one unit of time is discounted at the common rate 1 + r. Time is continuous, and the ⁻rms of m workers are formed for one period. Periods of di®erent ⁻rms overlap. At the end of the period, output Q is realized and shared according to the sharing rule $fs_i(Q)g$; contracted upon ex ante. At the end of the stage game, each employee decides whether to stay in the current ⁻rm or to separate. When separated, a random match with a new ⁻rm is formed immediately.¹² This captures the notion of competing norms. Any employee can opportunistically execute her outside option by going to a another ⁻rm.

¹⁰Formally, $u_i^d = s_i^i Q(e_i^d; e_i^o)_i^{(c)} C(e_i^d)$.

¹¹A similarly complementary approach has been taken by Meyer (1994) in studying learning in task assignment of team members.

¹²There is no friction and no agents is ever unmatched. Remaining unmatched with zero utility is an option, but never individually rational.

The decision to separate is bilateral. This is the punishment device that employees in a ⁻rm have over their colleagues. Underlying the punishment is the monitoring technology. After observation of Q; monitoring implies that the ⁻rm has some information about each individual employee's e[®]ort contribution. We assume that with probability 1; the ⁻rm knows which of the employees has provided e[®]ort below the optimal level.¹³ In addition to endogenous separation - either from punishment or opportunism -, there is an exogenous probability [®] with which partners separate. The parameter [®] is the arrival rate of a Poisson process.

Social Norms and Equilibrium. Loosely speaking, a social norm is a totality of common characteristics, behavior patterns, beliefs,... that applies to each ⁻rm individually. More precisely, the social norm consists of the strategy or the behavior rule that workers follow within the ⁻rm. It is a full contingent plan of action: for a given history, in each period workers choose e[®]ort and, after realization of Q; they decide whether or not to terminate the partnership. Of course, we will not be looking for just any set of strategies that constitute a ⁻rm's norm, but those that are an equilibrium, both within the ⁻rm and in an economy as a whole. We return to equilibrium in more detail below.

The interest here is in equilibria where a norm of cooperation within some rms can be maintained, despite the non-cooperative outcome in the static game. As is the case in the folk theorem, a norm is an implicit dynamic agreement between the workers in a rm. Of course, because agents have the option to separate, matching is endogenous and the standard folk theorem for in nitely repeated games between a given set of agents (see for example Fudenberg and Maskin (1986)) does not apply. In deriving equilibrium, we will be looking for those strategies that can support social norms of cooperation in the presence of endogenous matching.

Two remarks are worth noting at this point. First, in concentrating on equilibria that are supported by strategies speci⁻c to each ⁻rm's norm, the focus is on pure strategy equilibria. Nothing prevents workers from playing a mixed strategy, and such equilibria may exist. We consider it part of the contribution that the results on the coexistence of di®erent (good and bad) norms do not rely on mixed strategies. Second, the main objective of this paper is to derive those competing norms that exhibit the highest degree of cooperation. As is the case with the standard folk theorem, any individually rational payo[®] can be sustained in a subgame perfect equilibrium.

Whenever a worker is matched to a new rm, she forms a belief about the norm in that rm. Given the norm, i.e. belief about the strategy of all other m_i 1 workers, an optimal strategy must be a best response. In addition, equilibrium requires that adhering to the norm is individually incentive compatible. An equilibrium is then described by a rule, such that given the best response of all other workers in the economy, each player chooses $e^{\text{@}}$ ort to maximize expected discounted

¹³The assumption of this particular monitoring technology is without loss of generality. In section 5 the more general case is solved where with probability $^-$ < 1; a worker's e[®]ort is monitored ex post. Note that in matches with 2 workers only, $^-$ is always equal to 1: after realization of Q; a worker who knows her own e[®]ort can deduce the other employee's e[®]ort with probability 1.

utility. Suppose that all other workers cooperate, cooperation is a best response only if the payo[®] is higher from cooperating, and remaining matched to the ⁻rm with a norm of cooperation. It is precisely the separation that will determine the equilibrium in the economy as a whole. A norm of cooperation is not merely the choice of e[®]ort, but also the decision not to separate. A worker's best response will depend on her belief whether her colleagues will cooperate and decide not to separate. The incentive compatibility constraint will ultimately tie down the economy's equilibrium. This is precisely the role of di[®]erent types of norms. Since free riding in a cooperating ⁻rm has a higher immediate payo[®], the distribution of ⁻rms, in particular the ones with a bad norm, will constitute a su±ciently high threat through separation so as to satisfy the incentive compatibility constraint. Equilibrium is then determined by all individuals' best replies within a ⁻rm's norm, given they are incentive compatible (i.e. given the distribution of norms in the economy). The incentive compatibility constraint ties down the equilibrium distribution of norms.

Two more remarks are worth noting. First, all matches must be individually rational. For symmetric exogenous sharing rules, this is always satis⁻ed as matches are formed instantaneously and being matched has a higher value than being unmatched. The issue does have immediate relevance in the case of endogenous sharing rules. We will take up the issue in section 4. Second, the assumption of having more than two workers in a ⁻rm (m > 2) is not without consequences. In matches of two, punishment is costly: the punisher is separated as well as the punished. This gives rise to problems of renegotiation proofness.¹⁴ In the case of m > 2; the issue does not arise as the ⁻rm's norm does not disappear. By assuming that only one worker at the time gets separated exogenously and by considering non-cooperative equilibrium (i.e. unilateral deviations only), the non-separated workers remain matched and keep adhering to the norm with one newly matched worker.

3 The Main Result: Strati⁻cation

The model is rst solved for exogenously given symmetric sharing rules (see for example Farrell and Scotchmer (1988)). This assumption implies $s_i(Q) = s_j(Q) = s_j(2) = s_j$

¹⁴The issue of renegotiation proofness is discussed in more detail in section 5.

is given by15

$$rV^{o} = u^{o} + {}^{\textcircled{R}} \left[\mathsf{E}V_{j} \; V^{o} \right] \tag{2}$$

The °ow utility a worker gets is u° and after each period, she only gets separated from the \neg rm due to exogenous break up. This happens with probability ®: In the case of separation, the expected utility when rematched is EV. Below, we will derive EV explicitly. Whether or not cooperation is an equilibrium depends on the option value of defecting instead of cooperating in this high norm \neg rm. This is given by V^d

$$rV^{d} = u^{d} + \stackrel{\mathbf{n}}{\mathbf{E}}V_{j}V^{d}$$
(3)

Defecting yields a higher utility $u^d > u^o$ but implies that at the end of the period, the worker will get separated. Output is then observed to be below the optimal level $Q < Q(e^o)$; and the monitoring technology identi⁻es the defector with probability one.

In contrast, when matched to a rm with a norm of non-cooperation, a worker's best response is to choose e[®]ort such that it maximizes the one period utility and to separate at the end of the period. The option value is then equal to the °ow value of one period of non-cooperation plus the discounted expected value of a future match:

$$rV^{\alpha} = u^{\alpha} + [EV_{j} V^{\alpha}]$$
(4)

Note that it is $su\pm cient$ to observe whether the other workers in the $\neg rm$ have been matched together before to distinguish whether the norm is in C or in D. Because exogenous separation is assumed to happen one at the time, a worker matched to all newly matched colleagues deduces that the norm is D. This works like a public randomization device in matches between two players (see for example Fudenberg and Maskin (1986)).

The crucial variable here is the expected value of a future match EV: It is the belief any worker has about the whole population of workers' behavior. A rst preliminary result is that a strategy where none of the workers cooperates is an equilibrium.

Proposition 1 (No Cooperation) Non Cooperative behavior, $e = e^{\alpha}$ in all \neg rms in N is an equilibrium

Proof. If there is no cooperation in none of the \neg rms, then the option value in all \neg rms is V^{*}: Since all \neg rms are identical, the expected value of a future match is EV = V^{*}. As a result, the worker chooses e_i to maximize $rV^* = max_{e_i} s_i Q(e_i; e_i^*)_i c(e_i)$, the solution of which by de nition of the static Nash equilibrium is $e_i = e_i^*$. Because workers in all \neg rms are indi®erent between rematching and remain matched to the current partner (EV = V^{*}), an equilibrium may involve any separation strategy, i.e. with any probability 2 [0; 1].

$$(1 + rt)V^{o} = u^{o}t + (1 i^{B}t)V^{o} + {}^{B}tEV$$

which implies equation (2).

¹⁵For a time interval [0; t], the expected value V ° satis⁻es

Now suppose a newly matched worker believes that her new rm has a norm of cooperation. Her best response depends on the incentives for deviating. This is given by the incentive compatibility constraint (IC)

$$V^{\circ}$$
 , V^{d} (5)

This is a necessary condition for a worker to be induced to cooperate in a high norm rm, rather than free ride on the other members and rematch in the next period. From equations (2) and (3), this condition can be written as

$$u^{o} , \frac{^{\otimes} + r}{1 + r}u^{d} + \frac{r(1 i)^{\otimes}}{1 + r}EV$$
(6)

the °ow utility from cooperating must be large enough to make cooperating incentive compatible. It is therefore a function of u^d ; the utility of deviating, and of EV; the expected value of rematching. The value of rematching is determined by the distribution of norms in the economy, and it is easy to see that, in order to induce the worker to cooperate rather than free ride, the utility from cooperating must be larger the larger the expected outside option EV:

The outside option will pinn down the equilibrium distribution of \neg rm norms in the economy. Let F (n) be the cumulative density function of all norms in the economy. Since we are constructing equilibrium where the norm is either one of two types: the norm c 2 C with the optimal level of e®ort and no endogenous separation or the norm d 2 D the static Nash equilibrium level of e®ort followed by immediate separation. Let F (c) = f and F (d) = 1 i f: Then in each period of time, the total mass of separated workers is proportional to 1 i f + ®f; all the bad norm workers rematch each period and only the exogenously separated good norm workers do so. As a result, the fraction of newly matched workers that will be matched to a \neg rm with a norm of cooperation is

$$p = \frac{^{\textcircled{\mbox{$\mathbb{R}}$}}f}{1 \ i \ f + ^{\textcircled{\mbox{$\mathbb{R}}$}}f}$$
(7)

This now determines the expected outside option from rematching: $EV = pV^{\circ} + (1_i p)V^{*}$: The expected value from a match is the weighted sum of the values of each type of rm. We can now state the main result.

Theorem 2 (Strati⁻cation) There exists a pair (\mathbf{r} ; $^{\textcircled{m}}$) such that for any r 2 (0; \mathbf{r}] and for any $^{\textcircled{m}}$ 2 (0; $^{\textcircled{m}}$]; an equilibrium exists where a fraction f of ⁻rms c 2 C ½ N have a norm for cooperation, with $^{\textcircled{m}}$

$$f = 1_{i} \frac{u^{d}_{i} u^{o} (r + 1)}{u^{o} (r + 1)_{i} r u^{d}_{i} u^{\alpha}} \frac{@}{1_{i} @} < 1$$
(8)

Proof. Consider the following strategy: a worker chooses: 1. $e = e^{\alpha}$ if the the other workers in her $\bar{r}m$ were matched together in the last period and remains matched if Q $_{\circ}$ Q°; and 2.

 $e = e^{\alpha}$ and separation otherwise. Given this strategy, substitutin the expected value of a match $EV = pV^{\circ} + (1 \text{ j } p)V^{\alpha}$ in equations (2), (3), (4) implies

$$rV^{\circ} = u^{\circ} + \circledast (1 i p) [V^{*} i V^{\circ}]$$

$$rV^{d} = u^{d} + (1 i p) V^{*} i V^{d}$$

$$rV^{*} = u^{*} + p[V^{\circ} i V^{*}]$$

We can now calculate the incentive compatibility constraint (5) which implies

where

$$P = \frac{r + p + (k)(1 + p)}{r + 1}$$
 (10)

It su±ces to demonstrate the existence of a non negative pair (\mathbf{r} ; \mathfrak{E}) such that condition (9) is satis⁻ed and such that no worker in a non cooperating ⁻rm wants to deviate, i.e. $e_i^{\pi} = \arg \max_{e_i} V^{\pi}$: To establish (9) we can choose an \mathbf{r} and \mathfrak{E} to satisfy (9) with equality. To see this is possible, note that $\lim_{r! 0} (\lim_{e_l 0} \circ) = 0$ and $\lim_{r! 1} (\lim_{e_l 1} \circ) = 1$; and that $\frac{d^{\circ}}{de} > 0$ and $\frac{d^{\circ}}{dr} > 0$; making use of equation (7). Since by de⁻nition, u° ; u^{π} , and u^{d} satisfy $u^{d} \downarrow u^{\circ} \downarrow u^{\pi}$, we choose (\mathbf{r} ; \mathfrak{E}) so that $u^{\circ} = \circ u^{d} + (1_{i} \circ) u^{\pi}$: Now, for a given (\mathbf{r} ; \mathfrak{E}) < (\mathbf{r} ; \mathfrak{E}); the IC constraint is satis⁻ed. Using (7) and (10) to substitute at the IC constraint (9), yields equation (8).

Equation (9) ensures that no worker in a \neg rm with a norm for cooperation wants to deviate. We now verify deviations by workers in low e[®]ort \neg rms. Suppose she chooses a level of e[®]ort e $\mathbf{6}$ e^{*}, then by de nition of Nash equilibrium, her utility u(e_i; e^{*}_i) < u^{*}: Given the separation strategy of her coworkers, she will be separated with probability 1; giving her the same expected continuation value. As a result, her option value from choosing e $\mathbf{6}$ e^{*} is lower than V ^{*}:

The fraction of \neg rms with a norm of cooperation f as derived in the theorem is the upper bound. It now follows immediately that an economy where all \neg rms have a norm for cooperation (i.e. f = 1) cannot be an equilibrium. The outside option after separation is no worse, which makes cooperation not credible. This is con \neg rmed by mere observation of equation (9). When f = 1; then $p = \circ = 1$: Since u^d is strictly larger than u^o; the IC constraint is always violated. The way the upper bound (8) is determined is precisely by solving for highest possible f such that the IC is binding. Note that though workers are identical, and even with mobility, wages (and for that matter option values) di®er between \neg rms. There is a gap between the utility derived from being in the high norm \neg rm compared to the utility in the low \neg rm. This gap is necessary to make cooperation incentive compatible.

An Example and Some Comparative Statics Results

We illustrate the result with a simple example. Let m = 3, $Q = {\mathsf{P}}_i e_i$ and $C(e) = \frac{e^2}{2}$: Output is shared equally $s(Q) = \frac{1}{3}Q$. We can calculate the Nash equilibrium $e^{\text{@}}$ ort and utility $e^{\alpha} = \frac{1}{3}$; $u^{\alpha} = \frac{5}{18}$ and the optimal $e^{\text{@}}$ ort and utility $e^{\circ} = 1$; $u^{\circ} = \frac{1}{2}$: Deviating when both other partners supply

optimal e[®]ort implies e^d = $\frac{1}{3}$; u^d = $\frac{13}{18}$: Suppose that the rate of discounting is r = 0:1 and that the exogenous separation rate [®] = 0:1: Then Theorem 2 allows us to calculate f; and from equation (8) it follows that f ¼ 0:86. Eighty six percent of the ⁻rms have a norm of cooperation, with the remaining fourteen percent having a norm of non cooperation.

Separation Rate. The exogenous rate of separation has two di[®]erent e[®]ects. It determines the fraction of high cooperation jobs that are opened each period of time, and as a result, the expected value of a new match EV: Second, it also determines the probability with which cooperative behavior will be "unjustly" punished. Both e[®]ects go the same way:

$$\frac{@f}{@@} = i \frac{u^{d} i u^{o} (r + 1)}{(r + 1)u^{o} i ru^{d} i u^{a}} \frac{1}{(1 i e^{B})^{2}} < 0$$

The higher the exogenous separation rate, the more attractive free riding becomes and as a result, the higher the fraction of ⁻rms with bad norms needs to be in order for cooperation to remain incentive compatible.

Discounting. An increase in the interest rate implies that the future is discounted more which makes workers more myopic. The more myopic workers are, the less they care about future low utility matches in their trade o[®] between current e[®]ort and future utility. It follows that a larger fraction of non cooperating ⁻rms is needed to enforce cooperation, i.e. to satisfy the IC constraint.

$$\frac{@f}{@r} = i \frac{u^{d} i u^{o} u^{d} i u^{a}}{[(r+1)u^{o} i ru^{d} i u^{a}]^{2}} \frac{@}{1i^{e}} < 0$$

In the limit of complete myopia, the future is not valued at all, so that all \neg rms are non-cooperative. As was shown in Theorem 2, there is however a upper limit r in order to assure existence.

Firm Size. The e[®]ect of larger teams implies that free riding becomes more interesting. Ceteris paribus, an increase in m results in a higher value u^d; while keeping u^o and u^a constant. This in turn brings about a larger fraction of norms of non cooperation. Free riding is more lucrative, hence punishment is required to be stronger (i.e. a larger probability of a bad match). Formally, we show this for a linear additively separable production function, for which $e^d = e^a$. Let $Q = \prod_{i=1}^{n} e_i$; then $u^d = \frac{1}{m} (m_i \ 1)e^o + e^d \ i \ C(e^d)$, and as a result, $\frac{@u^d}{@m} = \frac{e^o + e^d}{m^2} > 0$: Now, it immediately follows that

$$\frac{@f}{@m} = i \frac{@}{1i} \frac{@(r+1)}{@m} \frac{@u^{d}}{(r+1)u^{o}i} \frac{u^{u}}{ru^{d}i} \frac{u^{u}}{u^{u}} < 0$$

The larger the teams, the lower the fraction of cooperating ⁻rms.

Applying competing norms to the ⁻rm environment seems to make sense, given the observed mobility of employees between di[®]erent ⁻rms. The endogenous strati⁻cation may be more generally applied in other social environments. As alluded to in the introduction, religions in the US face

substantial mobility of its members. Iannaccone (1992, p.272) reports that "90% of cult converts drop out within a few years, and 40% of all Protestants change denomination at least once [...and that there is] considerable "internal" mobility across di®erent branches of Judaism and among Catholic parishes with very di®erent styles of worship". She considers religions as club goods where religion is an object of choice and with the degree of participation voluntarily accepted. A similar reasoning applies to secret societies. Though often referred to by both insiders and outsiders as one society, "the lodge" for example, there are many di®erent local branches competing for members. Finally, it has been argued by biologists that "social behavior" of some animals includes mobility between groups. Wolves living in packs for example, expel members who violate the rules. Expelled wolves usually try and join another pack. Some of the wolves also leave voluntarily in an attempt to be become the alpha wolf in another pack. This is related to the presence of internal authority, an issue to which we will turn in the next section.

In a more typical economic environment, we could think of competing norms as a version of Tiebout's theory of local public goods. In fact, the social capital associated to the norm can be interpreted as a local public good. By "voting with their feet" citizens move between di®erent neighborhoods and sort themselves into homogeneous neighborhoods. Heterogeneity between neighborhoods increases. This is often applied to the case of heterogeneous citizens "nancing a local public good (e.g. education). What the theory of competing norms shows, is that even with identical citizens and with su±cient mobility, neighborhoods will have di®erent degrees of contribution to the public good (and di®erential degrees of turnover).

4 The Market for Authority: Wage-Tenure Schedules

The strati⁻cation result derived in the previous section has one salient feature: the option value in a ⁻rm with a norm of cooperation is strictly higher than the option value when the norm is non cooperation: $V^{\circ} > V^{\pi}$: All workers strictly prefer joining a high norm ⁻rm. Deriving this result when sharing rules are exogenous yield involuntary strati⁻cation. Because the market for new job openings in the high norm ⁻rms is missing, unmatched workers cannot outbid each other. If the argument applies, such a market would lower the wage received upon entry in a ⁻rm c; up to the point where workers are indi[®]erent between entering a ⁻rm with a high norm or a low norm: $V^{\circ} = V^{\pi}$. This type of voluntary strati⁻cation implies that the compensation packages (often referred to as performance bonds) in high norm ⁻rms exhibit "backloading": wages increase with tenure which results in an authority relation between junior entrants and senior incumbents. In this section, the objective is to introduce such a market for authority. Though wage-tenure schedules arise naturally, it will be shown that authority is limited, and that involuntary strati⁻cation is robust to the introduction of the market for authority.

We distinguish between junior and senior workers, indexed by the subscript j and s respectively. Junior workers are new entrants to the ⁻rm. Seniors are all other incumbent workers. Being

junior lasts until a senior gets separated (or until the junior gets separated herself). In every rm, there is one junior and m_i 1 identical seniors.¹⁶ The model is as before, where output shares for juniors are $s_i(Q)$ and $s_s(Q)$ for seniors. As a result, the °ow utility to a any worker is $u_i = s_i(Q(e))_i C(e)$; 8i 2 fj; sg: For analytical tractability of some of the results, we make the following simplifying assumption: the technology is additively separable in e[®]ort ant the sharing rule is linear:

Assumption A:
$$Q(e) = {\bf P}_i e_i$$
 and $s_i (Q(e)) = s_i Q(e)$

For a given sharing rule fs_j ; s_sg ; we can now derive the equivalents to equations (2),(3),(4), taking into account that V_j^o is in general di[®]erent from V_s^o : In the ⁻rms of type d, all workers are newly matched and the surplus is split equally. The main di[®]erence in the option value is at the level of the junior worker. A junior worker now has the prospect of becoming senior¹⁷:

$$rV_{j}^{o} = u_{j}^{o} + {}^{\otimes} EV + (m_{i} 1) V_{s}^{o} i mV_{j}^{o}$$
(11)

$$rV_{s}^{0} = u_{s}^{0} + ^{\otimes} [EV_{j} V_{s}^{0}]$$
(12)

The fundamental di[®]erence here is that when joining a ⁻rm of type c; as a junior there is the prospect of becoming a senior. Once a senior has been separated exogenously, the junior gets promoted to senior and a new junior is hired. Because a senior in general receives a higher share from the output than a junior, here is a gap between the option value of a senior and that of a junior. Let $\[mbox{$\]}$ be de⁻ned as $\[mbox{$\]} = V_s^{\circ}_i V_j^{\circ}$; then equation (11) can be written as $rV_j^{\circ} = u_j^{\circ} + \[mbox{$\]} EV_i V_j^{\circ} + (m_i \] 1) \[mbox{$\]} :$ Substituting out EV in equations (11) and (12), it is easy to show that for any given sharing rule fs_j ; s_sg ; $\[mbox{$\]}$ is given by

and that it is decreasing in s_i.

Lemma 1 For any given sharing rule fs_j ; s_sg ; C is decreasing in the junior's share: $\frac{@C}{@S_i} < 0$:

Proof. Since $e_j^o = e_s^o = e^o$; and $u_i^o = s_i(Q^o)_i c(e^o)$; the utility di[®]erence is equal to $u_s^o_i u_j^o = s_s(Q^o)_i s_j(Q^o)$: Under budget balancing, $s_j(Q) + (m_i 1)s_s(Q) = Q$ which implies $u_s^o_i u_j^o = c_s^o_i u_j^o_i u_j^o_i = c_s^o_i u_j^o_i u_j^o_i = c_s^o_i u_j^o_i u_j^o_i = c_s^o_i u_j^o_i = c_s^o_i u_j^o_i u_j^o_i = c_s^o_i u_j^o_i = c_s^o_i u_j^o_i u_j^o_i = c_s^o_i u_j$

¹⁷For a time interval [0; t] the equation (11) is derived from

$$(1 + rt) V_j^{o} = u_j^{o}t + {}^{\otimes}tEV + (1_i {}^{\otimes}t)^{E}(m_i {}^{1}) {}^{\otimes}tV_s^{o} + (1_i {}^{(m_i {}^{1})} {}^{\otimes}t) V_j^{o}^{m}$$

¹⁶There is no reason to assume that ex ante bargaining between all parties will treat all senior incumbents equally. What is captured here is that all m_i 1 incumbents bargain jointly with the new entrant. This reduces the split of the surplus to a two party bargaining problem, which is better documented in the literature than multi agent bargaining problems. For a given bargaining solution, the model could be extended to the case of a complete seniority schedule.

 $\frac{Q^{o_{i}} m_{s_{j}}(Q^{o})}{m_{i}}$: Taking the derivative of (13) with respect to s_{j} :

$$\frac{@\& \ }{@s_{j}(Q)} = \frac{i \ m}{(r + m^{\textcircled{e}})(m \ i \ 1)} < 0$$

This completes the proof. ■

It immediately follows from observation of equation (13) that for $s_j = s_s$; there is no di[®]erence in the option value of juniors and seniors: $\mathfrak{C} = 0$ and that for any $s_s > s_j$; \mathfrak{C} is strictly positive. In order to be able to derive the incentive compatibility condition, we need the option value of a deviator:

$$rV_{i}^{d} = u_{i}^{d} + EV_{i}^{d} V_{i}^{d}; 8i \ 2 \ fj; sg$$
 (14)

As before, the utility of a non cooperative partnership will be determined by the static Nash equilibrium payo[®] u^{*} and the expected continuation payo[®] $EV : rV^{*} = u^{*} + [EV_{i} V^{*}]$: Incentive compatibility requires that no agent has an incentive to deviate in a cooperating $\bar{r}m$

$$V_i^{o} \downarrow V_i^{d}$$
; 8i 2 fj; sg (15)

Incentive compatibility ensures a worker will not deviate once a job has been accepted. With authority, the rm in addition has to ensure that these rules are individually rational for the junior worker. Workers may decide to reject o[®]ers which give a very low current option value. A junior worker will accept an o[®]er of a match to a cooperating rm, as long as the option value of that match is at least as high as the option value of sampling a rm with a norm d. As a result, individual rationality IR requires

$$V_j^{o} \downarrow V^{a}$$
 (16)

Note that this does not imply that the °ow utility from a match with a cooperating $\mbox{rm should}$ be at least as high as the utility from a match with a non-cooperating $\mbox{rm:} u_j^o \mbox{\tt 4} u^{\mbox{\tt m}}$. In fact, when the IR constraint is satisfied, utility u_j^o may even be negative. The following lemma derives the lower bound on s_j :

Lemma 2 There is a lower bound \underline{s}_i on the sharing rule, satisfying

$$\underline{s}_{j} \overset{3}{Q^{d}}_{i} c(e_{j}^{d}) = u^{\alpha}$$
(17)

Proof. In appendix

At $s_j = \underline{s}_j$, $V_j^o = V^{\alpha}$ and any worker is indi[®]erent between joining ⁻rm with a norm of type c or a ⁻rm with a norm of type d: Given this sharing rule, there is no longer any involuntary strati⁻cation, in the sense that workers are indi[®]erent and hence equally well o[®] in both types of ⁻rms. That does however not rule out the existence of the two types of di[®]erent norms. Proposition 2 establishes the existence of equilibrium and derives the distribution of ⁻rms in the presence of authority. This Proposition is the equivalent of Theorem 2, where $s_j = s_s$.

Proposition 2 Under assumption A; there exists a pair (**b**; **b**) such that for any r 2 (0; **b**] and for any **®** 2 (0; **b**]; and for a sharing rule fs_j ; s_sg_c ; 8c 2 C, where $s_j \ 2 \ [\underline{s}_j; s_s]$, an equilibrium exists where a fraction f of $\neg rms c \ 2 C \ \frac{1}{2} N$ have a norm of cooperation, with

$$f = 1_{i} \frac{u_{j}^{d}_{i} u_{j}^{o} (r + 1) + {}^{\otimes}(m_{i} 1) {}^{\oplus}(m_{i} 1) {}^{\oplus}}{u_{j}^{o} (r + 1)_{i} ru_{j}^{d}_{i} u_{j}^{\mu} + {}^{\otimes}(m_{i} 1)(1 + r) {}^{\oplus}\frac{}{1_{i} {}^{\otimes}}}$$
(18)

Proof. In appendix ■

The proposition states that equilibrium exhibiting authority relations within \neg rms with a norm of cooperation, exists. In fact, any type of authority is an equilibrium (i.e. the proposition holds for any feasible s_j) where all \neg rms in C adhere the same sharing rule. We have derived equilibrium when authority is assumed. We now turn to endogenous authority, i.e. \neg rms choose the sharing rule.

4.1 Limited Authority

Consider a \mbox{rm} with a norm of cooperation. Juniors are better o[®] in the high norm \mbox{rm} than in a low norm \mbox{rm} as long as the IR constraint (16) holds without equality. If a senior has the power to negotiate the contract prior to the production stage, then Lemma 3 shows that whatever the equilibrium in the economy, she increases her option value by decreasing s_j:

Lemma 3 The option value of a senior worker is increasing with decreasing s_i

$$\frac{@V_s^o}{@S_j} < 0$$

Proof. From equation (12) it follows that

$$V_s^{o} = \frac{1}{r + \mathbb{R}} f u_s^{o} + \mathbb{R} E V g$$

Derivation with respect to s_i,

which is negatives since budget balance implies that $\frac{@S_s}{@S_j} < 0$.

Consider this is a two player bargaining problem between all identical seniors (or one representative) and one junior. Given individual rationality and the fact that matching is frictionless (rematching happens instantaneously in case the bargain breaks down), the junior is willing to accept any sharing rule s_j such that $V_j^{\circ} \, V^{\pi}$. A junior will not reject an o[®]er with a lower s_j (even if that yields a current °ow value $u_j^{\circ} = s_j (Q^{\circ})_j$ c(e°) that is smaller than u^{π} or even negative) since the option value in the high norm is above the option value in the low norm. An

equilibrium with endogenous sharing rules is now as before, with the additional requirement that the budget balancing sharing rule fs_j ; s_sg_c ; 8c 2 C for each \neg rm is optimally chosen to maximize V_s^o , given the choice of an optimal sharing rules by all other \neg rms fs_j ; $s_sg_i c$; 8_i c(\ominus c) 2 C. At \neg rst sight, it looks like seniors will want to choose s_j as low as possible ($s_j = \underline{s}_j$), from Lemma 3. However, Proposition 3 establishes that there is a limit to the authority senior incumbents can exercise. It establishes conditions under which incumbents do not want to lower the share s_j : The reason is that when lowering s_j the IC_j constraint is violated, so the \neg rm \neg nds it optimal to set $s_j = fs_jg_{ic}$:

Proposition 3 (Limited Authority) Under assumption A; there exists a pair $(r^{\alpha}; \mathbb{R}^{\alpha})$ and an **b** such that for any r 2 $[r^{\alpha}; \mathbf{b}]$ and for any \mathbb{R} 2 $(0; \mathbb{R}^{\alpha})$; an equilibrium exists where seniors in a ⁻rm c 2 C with a norm of cooperation, choose $fs_j; s_sg_c = fs_j; s_sg_{jc'}$ satisfying $s_j 2 [\underline{s}_j; s_s]$ and where the fraction f of ⁻rms in C is

$$f = 1_{i} \frac{u_{j}^{d}_{i} u_{j}^{o} (r + 1) + {}^{\otimes}(m_{i} 1) C}{u_{j}^{o} (r + 1)_{i} r u_{j}^{d}_{i} u_{j}^{a} + {}^{\otimes}(m_{i} 1)(1 + r) C} \frac{1}{1} {}^{\otimes}$$
(19)

Proof. We proceed to prove the proposition in two steps. First, in Lemma 4 we show that, for a given sharing rule of all other $\[rms fs_j; s_sg_{ic}, \[rm c's best response is fs_j; s_sg_c = fs_j; s_sg_{ic}: \]$ Then we apply Proposition 2 to show existence and derive f as in equation (19).

Lemma 4 (Best Response) Under assumption A; and provided IC_j is binding, there exists a pair $(r^{a}; \mathbb{B}^{a})$; such that for any r 2 $(r^{a}; 1]$ and for any \mathbb{B} 2 $(0; \mathbb{B}^{a})$; a \overline{rm} i's best response $fs_j; s_sg_c; sc 2 C$ satis $\overline{s} fs_j; s_sg_c = fs_j; s_sg_i_c$:

Proof. The constraint IC_j binding implies, from equation (15) that $V_j^o = V_j^d$: From equations (11) and (14) it follows that

$$V_{j}^{o} = \frac{1}{r+\mathbb{R}} u_{j}^{o} + \mathbb{R} [EV + (m_{i} 1) \mathbb{C}]^{o}$$
$$V_{j}^{d} = \frac{1}{r+1} u_{j}^{d} + EV$$

The problem of the senior is to choose s_j (and as a result s_s ; from budget balancing) in order to maximize V_s^o subject to IC_j

Since V_s^o is always increasing for decreasing s_j (from Lemma 3) it su±ces to verify whether for a lower s_j the IC_j constraint is still binding, i.e. whether

$$\frac{{}^{\varrho}\mathsf{V}_{j}^{\,\varrho}}{{}^{\varrho}\mathsf{S}_{j}} \cdot \frac{{}^{\varrho}\mathsf{V}_{j}^{\,d}}{{}^{\varrho}\mathsf{S}_{j}} \tag{20}$$

From assumption A this implies

$$\frac{Q^{o}}{r+\mathbb{R}} \stackrel{\mathbf{\tilde{A}}}{1}_{\mathbf{\tilde{I}}} \frac{m^{\mathbb{R}}}{(r+m^{\mathbb{R}})} \cdot \frac{Q^{d}}{1+r}$$
(21)

We now show that there exists a pair $(r^{\alpha}; \mathbb{R}^{\alpha})$ for which equation (20) holds with equality. To see this, we consider two extreme points. At r = 0; equation (20) holds with strict inequality for any $\mathbb{R} > 0$, since $_{3}$

$$\lim_{r! 0} \frac{Q^{o}}{r + {}^{\textcircled{\tiny{B}}}} \mathbf{1}_{i} \frac{m^{\textcircled{\tiny{B}}}}{(r + m^{\textcircled{\tiny{B}}})} = 0$$

$$\lim_{r! 0} \frac{Q^d}{1+r} = Q^d > 0$$

At r = 1; the inequality is violated if

$$O^{0} \frac{1}{(1+)^{(1+m^{(0)})}} > \frac{O^{d}}{2}$$
 (22)

which is the case for all [®] 2 (0; ^{®^a}), where ^{®^a} solves equation (22) with equality (note that the left hand side is monotonically decreasing in [®] and goes to zero as [®] goes to in⁻nity). It now follows that, provided [®] < ^{®^a} there exists an r^{^a} such that equation (21) holds with equality, since 8r 2 (0; 1); $\frac{d}{dr} \frac{{}^{e}V_{j}^{o}}{{}^{e}s_{j}} = Q^{o} \frac{1_{i} r}{(1+{}^{e})(1+m{}^{e})} > 0$ and $\frac{d}{dr} \frac{{}^{e}V_{j}^{d}}{{}^{e}s_{j}} < 0$:

For any pair (r; [®]) such that r 2 (r^x; 1] and [®] 2 (0; ^{®^x}); the IC_j constraint satis⁻es

$$\frac{{}^{@}V_{j}^{o}}{{}^{@}S_{j}} > \frac{{}^{@}V_{j}^{d}}{{}^{@}S_{j}}$$
(23)

A decrease in s_j implies a higher marginal e^{\otimes} ect on V_j° than on V_j^{d} : Given that IC_j is binding for the strategy fs_j ; s_sg_{ic} by all other norms ic 2 C, it follows that $V_j^{\circ} = V_j^{d}$; for fs_j ; $s_sg_c = fs_j$; s_sg_{ic} . Equation (23) implies that $V_j^{\circ} < V_j^{d}$ for $fs_jg_c < fs_jg_{ic}$ implying that the best response is fs_j ; $s_sg_c = fs_j$; s_sg_{ic} : This completes the proof of the Lemma.

The proof of Proposition 3 is now nearly complete. We only need to show that there is an $r^* < b$; so that Proposition 2 applies. For any **b**; there exists an [®] low enough such that this is satis⁻ed. To see this, consider equation (21). It follows that r^* is decreasing in decreasing [®]

$$\frac{dr^{\pi}}{d^{\textcircled{R}}} = \frac{Q^{o}r^{\pi}}{Q^{o}(1 \ i \ r^{\pi}) + Q^{d}\frac{(r^{\pi} + \textcircled{R})(r^{\pi} + m^{\textcircled{R}})}{(1 + r^{\pi})^{2}}} > 0$$

and with $^{\ensuremath{\mathbb{R}}}$ going to zero, $r^{\ensuremath{\mathbb{R}}}$ becomes negative since $Q^{\ensuremath{o}} > Q^{\ensuremath{d}}$

$$\lim_{\substack{\circledast i \ 0}} r^{\alpha} = \frac{i \ Q^{o}}{Q^{o} \ i \ Q^{d}} < 0$$

As a result, there is always an $r^* < b$: This completes the proof of Proposition 3.

The intuition is that even though the seniors' value is increasing for a decreasing s_j ; the incentive compatibility constraint of the juniors is a®ected by the change in s_j : What the proposition shows is the conditions under which a decrease in s_j violates the IC_j constraint. For su±ciently high r and su±ciently low ®; a decrease in s_j decreases V_j^o marginally more than a decrease in V_j^d ; which violates the IC constraint. Consider $V_j^o = V_j^d$ binding, then a decrease in s_j decreases both V_j^o and V_j^d : Since V_j^o depends on both r and ®; and V_j^d only on r; both values have a di®erent marginal e®ect for di®erent pairs (r; ®).

This clearly limits a \neg rm to extract authority rents from newly entering juniors. The best one individual \neg rm can do is extract as much as the other \neg rms. Of course, there is a continuum of equilibria in this economy: if all other \neg rms extract more from the juniors (i.e. have a low s_j) then an individual \neg rm can extract that much as well. The equilibrium level of s_j does a®ect the equilibrium distribution, and hence e±ciency. In general, the e®ect of s_j on f is ambiguous.

4.2 An Example With Authority

Consider the same example as above, where each time, two senior incumbents hire one junior. Note that assumption A is satis⁻ed. The sharing rule satis⁻es budget balancing: $s_j + 2s_s = 1$; and utility is given by $u_i = s_i Q_i \frac{e_i^2}{2}$; 8i 2 fj; sg. Optimal $e^{\text{@}}$ ort is unchanged $e^{\circ} = 1$ and adjusting for the shares, optimal utility $u_i^{\circ} = s_i 3_i \frac{1}{2}$: $E^{\text{@}}$ ort for deviating is determined by the ⁻rst order condition, where $C^{0}(e) = e$ implies $s_i = e_i$. It follows that

$$u_i^d = s_i(2 + s_i)_i \frac{s_i^2}{2} = 2s_i + \frac{s_i^2}{2}$$
; 8i 2 fj; sg

Making use of budget balancing $s_i + 2s_s = 1$; it follows that

$$u_{j}^{d} = 2s_{j} + \frac{s_{j}^{2}}{2}$$
$$u_{s}^{d} = 1_{j} s_{j} + \frac{(1_{j} s_{j})^{2}}{8}$$

As before, in <code>-rms</code> with a norm of non-cooperation, output is shared equally: $e^{\pi} = \frac{1}{3}$ and $u^{\pi} = \frac{5}{18}$: From equation (13) it follows that $\mathfrak{C} = \frac{3}{2} \frac{1_{i} 3s_{j}}{r+3^{\circ}}$: Note that for $s_{j} = s_{s} = \frac{1}{3}$; we have the case of symmetric exogenous sharing rules, and $\mathfrak{C} = 0$: From the individual rationality condition (16), $u_{j}^{d} = u^{\pi}$ it follows that $2s_{j} + \frac{s_{j}^{2}}{2} = \frac{5}{18}$; which is satis⁻ed for $\underline{s}_{j} = 0$:13: Note that $u^{\circ} = s_{j}3_{j} \frac{1}{2}$ is negative for any $s_{j} < \frac{1}{6}$ ¼ 0:17 (at $s_{j} = \underline{s}_{j}$; $u_{j}^{\circ} = i$ 0:097).

We ⁻rst verify the conditions of Proposition 2:

1. The junior's IC is binding

implies

$$\frac{3}{2}\frac{1}{r+3^{(0)}} \frac{1}{3} \frac{9}{1} \frac{1}{8}\frac{26s_{j}}{r+1} \frac{3s_{j}^{2}}{1}$$

which is satis⁻ed for all the examples we give below. Hence f is derived from (18)

$$f = 1_{i} \frac{2s_{j} + \frac{s_{j}^{2}}{2}i}{3s_{j}i} \frac{1}{2}(1+r)_{i} r(2s_{j} + \frac{s_{j}^{2}}{2})_{i} \frac{5}{18} + \frac{8}{3}\frac{3(1_{i}3s_{j})}{r+3^{(8)}}(1+r)}{\frac{8}{1}i} \frac{(24)}{1}$$

2. Limited authority (L.A.), from equation (23)

$$3 \frac{r}{(r+e)(r+3e)} > \frac{2+s_j}{1+r}$$

It is easy to verify that this condition holds for r = @ = 0:1. And though it does not hold for r = @ = 0:2 over the whole range of s_j (in particular near $s_j = \frac{1}{3}$); it does hold over the whole range for r = 0:3 and @ = 0:1. This implies that when it holds, authority is limited to what the market o@ers. Firms cannot o@er an s_j that is lower than the rest of the -rms. If they would, that would violate the juniors' IC constraint. When this condition is not satis ed, -rms can exercise unlimited authority by o@ering the lowest share possible.

We now plot the distribution f in function of s_j from equation (24) for di[®]erent combinations of r and [®]: The junior's share is bounded from above by $\frac{1}{3}$ and from below by $\underline{s}_j = 0.13$. The solid line gives equation (24).

The share f in function of s_j (r = $^{(R)}$ = 0:1)

Below an illustration of the di[®]erent types of equilibrium distributions. In the ⁻rst panel, f is bounded from below for any feasible s_j . The minimum level of inequality is at $s_j = \underline{s}_j$; where

f = 0.42: For r and [®] even lower (equal to 0.01), the minimum level of inequality increases f = 0.89. As [®] and r go to zero, all ⁻rms in the limit have a norm of cooperation. On the other hand, as r and [®] increase, the equilibrium with heterogeneity in norms eventually does not exist, as in the example for $r = ^{\mathbb{R}} = 0.4$; and all ⁻rms have a norm of non-cooperation.

In the <code>-rst</code> and the second panel, (as is the case in <code>-gure 1</code>), authority is limited (L.A.). If all <code>-rms</code> choose pay a share s_j ; then the best response for a <code>-rm</code> that employs a new entrant is to o[®]er a share s_j : Then, even though there is a market for authority, and <code>-rms</code> can choose what share to o[®]er to newly entering juniors, no <code>-rm</code> will o[®]er a share di[®]erent than any other <code>-rm</code>. If it would do so, that would violate the junior's incentive compatibility constraint. As a result, all possible combinations of f within the feasible range are possible (f 2 [:42; :94] in the <code>-rst</code> example and f 2 [0; :79] in the second).

L.A. f 2 [:42;:94] (r = $^{(e)}$ = 0:05) L.A. f 2 [0;:79] (r = 0:3; $^{(e)}$ = 0:1)

$$A f = (r \ 0; ; ^{(R)} \ 0;)$$
 U. $f \ 0; 9 (= 0.01 ^{(R)} = :1)$

The third number of the operation of the term operation operati

only equilibrium is one with unlimited authority but where a fraction of roughly half of the ⁻rms has a norm for cooperation.

Note that in general, it is ambiguous whether f is increasing in $s_{\rm j}$ or not. To see this, consider the binding IC constraint

$$u_j^{o} + {}^{\mathbb{R}}(m_j 1) \oplus u_j^{d \circ} + u^{\alpha}(1_j \circ)$$

Then from the implicit function theorem

$$\frac{d\mathbf{f}}{ds_{j}} = i \frac{\frac{du_{j}^{o}}{ds_{j}}i \circ \frac{du_{j}^{d}}{ds_{j}} + {}^{\textcircled{\text{e}}}(\underbrace{\mathbf{m}}_{i} 1)\frac{d\mathbf{c}}{ds_{j}}}{i \quad u_{j}^{d}i \quad u^{\alpha} \quad \frac{d^{\circ}}{d\mathbf{f}}}$$

the sign of which only depends on the sign of the numerator as u_j^d , u^{α} and $\frac{d^{\circ}}{df} > 0$. Though in the numerator $\frac{du_j^{\circ}}{ds_j} + \circledast(m_i - 1)\frac{d\mathfrak{C}}{ds_j} > 0$; it may not be larger than $\circ \frac{du_j^d}{ds_j}$:

5 Robustness

In this section, we verify whether the results derived are robust to changes in the assumptions. We consider the introduction of capital in production, a general monitoring technology, non-linear sharing rules, and deviations by coalitions.

5.1 Production with Capital

Consider the model from section 3, with capital, competing for labor. The output production function is Cobb-Douglas with capital in addition to additively separable e[®]ort

$$y = f(e;k) = {}^{3}X e_{i}k^{a}$$

This represents a situation as before: the \mbox{rm} can announce wages depending on the whole bundle e of e®ort choices. Firms and workers simultaneously choose capital and e®ort, respectively. Given an e®ort bundle e, a \mbox{rm} hires capital k at a capital rental rate R in order to maximize pro \mbox{rs} $\mbox{}^{4} = y_{i} \mbox{mw}(e)_{i} \mbox{kR}$, where mw(e) is the total wage bill that is paid by the \mbox{rm} , which is shared according to the sharing rule fs_ig. This implies the \mbox{rst} order condition

$$ak^{a_i 1} e_i = R$$

The equilibrium level of capital k

$$k = \frac{\mu_{aQ}}{R} \P_{\frac{1}{1_i a}}$$

The ⁻rst order condition for labor is

$$\frac{dw(e)}{de_i} = \frac{dy}{de_i} = \frac{d^{\mathbf{P}}e_i}{de_i}k^a$$

he nceaei th waefretr $e^{(m)}$ rt se ua to he nceaei th ad it on I pod ct on f o tp t. sb fo e, e I ok or qu li ri wihe ua $e^{(m)}$ rt up ly yalw rk rs it in ne rm Th nt e⁻ st rd r c nd ti n f r e = e 8 i s

$$\frac{d}{de}$$
 (e k^a

sig(in eQ me

$$k = \frac{am}{R} \P_{\frac{1}{1}}$$

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$$\frac{z}{R} = \frac{am}{R} \frac{\P_{\overline{\tau_i}}}{dK} d\frac{F}{dK} = \overline{K}$$

hihg ve R = $\frac{R}{m}$ (me $\frac{1}{1a}$ d (e wer F() i th cu ul tied st ib ti no al wo kes, it mo th mi ea h m. ec nn ws bs it te

$$\frac{W()}{d} = \frac{\mu}{me} \frac{me^{\frac{a}{ia}}}{me}$$

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$$(e = (i a \frac{\mu_a}{R} e^{\frac{1}{1_i}} e^{\frac{1}{1_i}} K$$

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$$(e = (i a)^{3} X i^{a}$$

I this stting calit lipr potinato he [®]otlve in hermind sales lt aptayild th saler tunial ⁻r s, rr spictive ft en rm Calit ld es ot ar a high rr tuni th ⁻r s with no mo cope at on Thug this is point th as umitino a C bb Dogls fincio al or , r ce te pilc lwrk y C pp II an Nemak (99) s pp rt this a supton Capeli nd eu ar re or evide ce ha "high er or an e" or prictice in rese ab rip od ctivity. It es me im , t es wokp accids r is la or os an emilo ee omien at on while ee in thire ur on apta cost nt "High er or an e" or prictice ar god fire plyes a d hirm or ur emilo er. T ey on lu e t at high rms (.e. thica it l') c mp tinty nes.

5.2 A General Monitoring Technology

The assumption in the model is that at the end of production, when Q is observed, the \neg rm observes the identity of the deviating individual with probability 1. Suppose now that deviators in m-worker teams can be detected with probability \neg (m), where $\neg^{0} \cdot 0$ and \neg (2) = 1: The value function for a deviator then becomes

$$rV^{d} = u^{d} + (^{((e))} + ^{-} (1_{i} ^{((e))}))^{h} EV_{i} V^{d}$$
(25)

As in Theorem 2 we can derive for the generalized problem the incentive compatibility condition V° , V° ; which implies a modi⁻ed version of (9)

$$u^{o} \downarrow {}^{\circ 0} u^{d} + (1 i {}^{\circ 0}) u^{\alpha}$$
(26)

where

$${}^{\circ 0} = \frac{r + p + {}^{\otimes} (1_{i} p)}{r + {}^{\otimes} + {}^{-} (1_{i} {}^{\otimes}) + p[1_{i} {}^{\otimes} {}^{-} (1_{i} {}^{\otimes})]}$$
(27)

Calculating the proportion of cooperating ⁻rms gives

$$f(\bar{}) = 1_{i} \frac{u^{d}_{i} u^{\alpha} (r+1)}{u^{0} (r+\bar{})_{i} ru^{d}_{i} \bar{}^{-} u^{\alpha}} \frac{e}{1_{i}}$$
(28)

And it is straightforward to get

$$\frac{@f(\bar{\ })}{@\bar{\ }} = \frac{(u^{o}_{i} u^{u})^{u} u^{d}_{i} u^{u}}{[u^{o}(r + \bar{\ })_{i} ru^{d}_{i} - u^{u}]^{2}} \frac{@}{1_{i} @} > 0$$

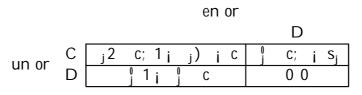
The higher the probability of detecting a free rider, the higher the proportion of cooperating rms. Punishment is harsher as more agents who free ride will be caught. As a result, even with less low norm rms, the IC constraint is satis⁻ed.

Earlier, we found that the e[®]ect of larger ⁻rms, i.e. larger m; decreases the proportion of cooperating ⁻rms: for a given sharing rule, the bene⁻ts from free riding are higher in a large ⁻rm, which requires more non-cooperating ⁻rms to punish deviators. Now, this direct e[®]ect still exists, but in addition, if larger ⁻rms have a lower probability of detecting deviators, ⁻⁰(m) < 0; the total e[®]ect on f is even larger through the indirect e[®]ect from m on ⁻

$$\frac{\mathrm{d}\mathbf{f}(\bar{})}{\mathrm{d}\mathbf{m}} = \frac{\mathscr{Q}\mathbf{f}(\bar{})}{\mathscr{Q}\mathbf{m}} + \frac{\mathscr{Q}\mathbf{f}(\bar{})}{\mathscr{Q}\bar{}} \frac{\mathrm{d}\bar{}}{\mathrm{d}\mathbf{m}} < 0$$

.3 on li ea Sh ri g R le

We on trct si pl⁻e ve sin o ou mo el wh re he taic ec sin i re re en ed y t e fllwig 2 la er or al or ga e:



w er ea hpayrc ne thrd ciet plyC cope at on rD deecio. Tej nirp yo is he rs of he wo al es ne chox nd he enor ay [®] i th se on. Tep yo saed temied s f II ws Th jont ur lu if ot plyC sQ = 2 If ot plyD it sQ = 0 nd ftey la ad [®]e en statgy t i Q^d 1: ot Is rp us s s ard a codigt shrigrle j a d s = 1 s_s Th coto e[®] rt sc he cope at ng nd whnd fe tig. oh ve hi st lied er io ⁻t ol st **Å** (182, a su ec si th negh or oo of bu st ic ly male. N te ha th shrigr le sn n-in ar si ge er Is **6** $\frac{1}{9}$ By et in s⁰ < s; tes nirc np niht e d vi tigj nirp op rt on II hade fo ex mpe. et $j = \frac{1}{2}$ ad s_j = $\frac{1}{4}$; he ba an ed ud et mpie th t 1 s⁰ = $\frac{3}{2}$: D vi tigh sb co ee en or at ratie frtes nir.

ti im ed at ly ler fom hi ex mpet at heei no jt at il ac iee st es (te H Im trom 192) es lt. Teq es io is ha ths wll mpy fr ted na ic am. W th reor loka th in en iv co paibliyc ns rant of un or an se ios. he e a e d ri ed n te a pe di un er he ro fo Pr poiton. E ua ios (0) nd 31 ar gi en y

W at roostin 2 taes stat or $u \pm ietl lo rad$ IC is lwys in in . W th on liea shrigr le an fo su cintylws_j, he tiit frmd vitinu_j b co es olwt at C_j sn tbndng Ho evr, it bu ge baan in , t is mpie th tu_s poprton II in rese. A a r sut, he elvatcns rant ha is in in is C_s It an es ow th tfrf 1; hi costait i no bi dig (ot th tt ei di id alyr tinait costait I im list at loer $\frac{1}{j}$ mpie a hghr I we bond_j a dhnc as aler et ffasbl) im lyng ha th stat ct in prsst evn w th on liea shrigr le. T is om sn ta as rp is as he aton le or he ne cinc in he ep at dg me si en ic I th on in he taic am. I th st ti ga e, ti sh wn ha th in \pm cen yr sut des ot ep nd n lne riyo shrigr le, b to th as um ti no ab la ce bu ge.

54 Dvitins ycaltins

quli ri m d ri ed er is on co pe at ve in he en et at nl de ia io s b on in iv du l a th ti e a e c ns de ed Th re re wo el va t i su s t at ay e c ns de ed On is en go ia io proofness when one individual has deviated. The second is deviations by coalitions of all m members of a ⁻rm with a norm of non-cooperation.

Renegotiation proofness is certainly a serious problem when m = 2: Punishment of the co-worker who deviates also implies self punishment. "Firing" your partner implies that you are unmatched yourself and that you will be randomly assigned a new partner afterwards. If you were cooperating, punishing your partner implies that you get expected value EV which is lower than V^o: As a result, both parties would gain from renegotiating the "threatened" separation through any split of the ensuing surplus. In our model, m > 2 and by the assumption that only one worker is exogenously separated from the -rm with a norm of cooperation, incumbents never get a lower option value V^o by punishing a deviating co-worker. For them the continuation payo® of punishment is not dominated, and hence satis the criterion for renegotiation proofness in Farrell and Maskin (1989).

Allowing for deviations by coalitions of workers certainly does change the equilibrium. In particular, a ⁻rm with a low norm of cooperation would always gain by starting to cooperate. Because the ⁻rm has zero mass in the economy, it is a dominant strategy for all ⁻rms to cooperate. However, cooperation in all ⁻rms would not be an equilibrium since individual workers in a ⁻rm now gain from deviation: the outside option is equally good as all ⁻rms are cooperating, so non-cooperation is a dominant strategy. It follows that equilibrium does not exist. Note also that a mixed strategy by coalitions would be problematic. Given a mixed strategy by all other ⁻rms, one ⁻rm's best response is to cooperate with probability one. Being of zero mass, this does not change the incentive compatibility constraint of one individual worker. This is a dominant strategy as the payo[®] from cooperating is higher than not cooperating. The result is that an equilibrium that allows for deviations by coalitions of workers does not exist, neither in pure nor in mixed strategies. This is of course not a new discovery, because there is no general existence proof for equilibrium of large sequential games of incomplete information.

6 Extensions

We consider two extensions to the model of section 3.

6.1 Worker Heterogeneity

Consider two types μ of workers, h and I and such that, in addition to e[®]ort, the worker types are inputs in production. A worker's type μ is observable. Let ⁻rms consist of m = 2 workers. For sorting to matter, let worker types be complementary inputs: $Q = \{\mu \mu P_i e_i : \text{There is now a productivity gain from matches that are positively assorted, as for a given level of e[®]ort, Q(h; h) + Q(I; I) > 2Q(h; I). In the earlier sections, rematching is assumed to be frictionless.¹⁸ That implies$

¹⁸Eeckhout (1999) derives an equilibrium with endogenous class formation, provided there are frictions in the matching process.

ht n hg tp cn las eet lw yead erw prnr nise es nte hg tp. e o mdf te oesihladeaetmk oerwrmh pooumthd e pro. eas te au ont en mthd o noes om lzd o eo i awy past re ai machd, ve if ha in lu es eg ti el sote machs (; l:

Nw, ®otcoieb hihtpe in lues he on idraio of ba" (; I machs, nadio to he osibliy o beng nah;) m tc wiha or fo no-c op raio. Alh gh yp swll mm ditey w nt o spa at fr m a at h w th lo ty e i pl in thre s n co pe at on n m xe mach s. he i[®] re ce et ee h a d l an he ce he ar in l p od ct vi y o e[®] rt n d®e en machsino crcilide er inng qulirim. it a h gh i[®] re ce al hi h t pe wilb in ucdt cope at as heei su cint unsh en in he hrat fb in machdt at pe : S there are eight so e_{\pm} in the eigenvalue of the eig on id rnwtelwtpe. Tey tilned u± ie tm tc es it an rm or on co pe at on in rdrt crdily us ai cope at on no hes. ow ve, ter is ls a pss biit of eig rematched to an exogenously separated high type worker. The larger the di®erence between low and high types, the higher the bene⁻t to a low type and the higher here incentive to try a rematch each time. This will induce her not to cooperate even if she is matched to another low type, as she wants to try her luck by possibly rematching a high type. While increasing dispersion in the types provides incentives for the high types to cooperate, it provides incentives for the low types not to cooperate. The result is that the initial dispersion is exacerbated in the payo[®]s through e®ort choice.

6.2 Complementary Inputs

When inputs are complementary, multiple static Nash equilibria can exist. The marginal productivity of a worker's e®ort increases as e®ort by other workers in the ⁻rm increases. As a result, multiple ⁻xed points to the static game can exist.¹⁹ Suppose there are two pure strategy Nash equilibria with utilities associated $\underline{u}^{\pi} < \overline{u}^{\pi}$ such that $\underline{u}^{\pi} < \overline{u}^{\pi} < u^{o} < u^{d}$. Let the corresponding option values be \underline{V}^{π} and \overline{V}^{π} be de⁻ned as above. To derive the equilibrium distribution of ⁻rm norms in this economy, consider the following expected valuation of being rematched: $EV = p_1V^o + p_2\underline{V}^{\pi} + p_3\overline{V}^{\pi}$ where p_1 is the probability of matching to ⁻rm with a norm for cooperation and $p_1 + p_2 + p_3 = 1$:

An equilibrium distribution will now depend on what the level of e^{e} ort is in the ⁻rms without a norm for cooperation. The condition (5) will now write $u^{\circ} \, _{_{1}} u^{d} + \, _{_{2}} \underline{u}^{_{1}} + \, _{_{3}} \overline{u}^{_{1}}$: If $p_{2} = 0$ (and hence $^{\circ}_{_{2}} = 0$); the fraction of cooperating ⁻rms f where the IC constraint is binding will

¹⁹Consider an example with m = 3; but where the production function is now multiplicative (i.e. $e^{\text{@ort}}$ is a complementary input) Q = 3; $i_i e_i$ and cost of $e^{\text{@ort}}$ is $c(e_i) = \frac{e_i^4}{4}$; which implies $c^0 = e_i^3$. When output is equally shared, there are two pure strategy Nash equilibria: $\overline{e}^{\pi} = 1$ and $\underline{e}^{\pi} = 0$. Then either $\overline{u}^{\pi} = \frac{1}{2}$ or $\underline{u}^{\pi} = 0$: The Pareto optimal level of $e^{\text{@ort}}$ is $e^0 = 3$; implying that $u^0 = \frac{27}{4}$ ¼ 6:75. The utility from deviation is given by $u^d = 9e_i i \frac{e_i^4}{4}$; which solves $e^d = \frac{13}{9} \frac{9}{4}$ 2:08 and yields $u^d = \frac{3}{4}9^{\frac{4}{3}}$ ¼ 14:04:

be smaller than if $p_2 = 1$ i p_1 : In fact, as p_2 is increasing, f is decreasing. The value of being in a rm with a norm for non-cooperation \underline{e}^{π} is the lowest possible, which implies that punishment is su±ciently severe that a large number of rms with a norm for cooperation can be sustained. In principle, any distribution of between p_2 and p_3 can be envisaged, as long as it satis is the constraint.

Now consider the following case: let $\overline{V}^{\pi} > EV$: Then a worker in a ⁻rm with a norm for noncooperation (the higher one of the two), will not want to separate as the current value is higher than the expected value of rematching. However, even if these non-cooperating stay together, it will not be an equilibrium to start cooperating if the IC constraint is binding with equality. Hence there is an equilibrium with three types of norms: high turnover, low non-cooperative e[®]ort; low turnover, high non-cooperative e[®]ort; cooperation. We now derive distribution, always under the assumption that $\overline{V}^{\pi} > EV$:

7 Concluding Remarks

The theory of competing norms provides an explanation for the coexistence of heterogeneous norms and the endogenous strati⁻cation of corporate cultures. The crucial premise is that organizational forms are in competition through the labor market. The organizational characteristics are not explained by transaction cost di[®]erences between ⁻rms and markets (Coase (1937), Williamson (1975)), nor as a result of non contractible, unforeseen contingencies where ownership constitutes the residual claimant (Grossman and Hart (1986)). We o[®]er a complementary explanation in the line of Kreps (1990). The norm in our model is an implicit contract that is self enforcing. The market environment in which this norm operates determines the outside option for workers and is crucial for the feasibility of this implicit contract. No ⁻rm with a norm of cooperation can coexist unless there are su±cient bad norms. This is far from a theory of the ⁻rm (the boundaries of a ⁻rm here are exogenous). Rather, it is a theory of inequality of the ⁻rm.

Since there is a gap between the utility for an entrant in a bad norm compared to the utility for entry in a good norm, authority naturally arises by the incumbent high norm members. Wage payments that di®er between seniors and juniors are the result from this discrepancy between the utility derived in di®erent norms. As in Simon (1951), a new entrant is willing to enter into an authoritative employment contract as long as that contract is better than the employment contract in a bad norm. The important caveat of the competing norms model is that even authority is limited by the implicit contract. We show that the implicit contract restricts the rents that the authority of senior incumbents can extract. The nature of authority is determined/limited by the competitive environment through the implicit contract. Authority does not, in general, eradicate bad norms.

8 Appendix

Proof of Lemma 2

Given that the incentive compatibility constraint is binding, IR requires that $V_j^{o} = V_j^{d}$, V^{*} : From equations (14) and (4), IR then implies

$$\frac{u_j^d + EV}{1+r} , \frac{u^{\alpha} + EV}{1+r}$$

and hence $u_j^d \, u^{\alpha}$: Where the IR constraint is binding, $u_j^d = u^{\alpha}$ can be rewritten as $\underline{s_j}^{Qd} i C(e_j^d) = u^{\alpha}$; where $\underline{s_j}$ is the the minimal s_j : This is a lower bound because u_j^d is increasing in s_j :

Proof of Proposition 2

To prove this Proposition, we proceed by showing two Lemmata. In Lemma 5, for a given sharing rule fs_j ; s_sg , common to all ⁻rms, we derive the equivalent distribution function as in Theorem 2. In Lemma 6, assumption A allows us to determine that IC_j is binding, and we show exisitence.

Lemma 5 For any given sharing rule fs_j ; s_sg_c ; 8c 2 C the fraction f_1 of \neg rms with a norm for cooperation, is given by

$$f_{1} = 1_{i} \frac{u_{j}^{d} i_{j} u_{j}^{0} (r + 1) + {}^{\mathbb{B}}(m_{i} 1) C}{u_{j}^{0} (r + 1)_{i} r u_{j}^{d} i_{j} u_{j}^{\pi} + {}^{\mathbb{B}}(m_{i} 1)(1 + r) C} \frac{1}{1} {}^{\mathbb{B}}$$
(29)

provided $\frac{u_{si}^o u_j^o}{r+m^{\circledast}}$, $\frac{u_{si}^d u_j^d}{r+1}$ and provided equilibrium exists.

Proof. Consider the same strategies as in Theorem 2. Then the proportion p of cooperating rms is given by equation (7). The expected value of rematching is now $EV = pV_j^{o} + (1_i p)V^{a}$. Substituting EV in equations (11), (14) and (4), using (13) implies

$$rV_{j}^{o} = u_{j}^{o} + {}^{\textcircled{B}} \begin{pmatrix} \mathbf{n} & \mathbf{j} \\ \mathbf{n} & \mathbf{j} \end{pmatrix} V^{a} \mathbf{j} V_{j}^{o} + (\mathbf{n} & \mathbf{j}) \mathbf{j} \\ \mathbf{n} & \mathbf{n} \\ \mathbf$$

Satisfying the incentive compatibility constraint of the junior V_j^{o} , V_j^{d} , we get condition IC_j

$$u_{j}^{o} + {}^{\otimes}(m_{i} 1) {}^{\oplus} , u_{j}^{d}{}^{\circ} + u^{*}(1_{i} {}^{\circ})$$
 (30)

where $^{\circ}$ is as before and given by equation (10).

The value equations for the senior workers are similar: V_s^d for deviators and V^* non-cooperators: For cooperators, the option value is $rV_s^o = {}^{\circledast}[(1_i p)(V^*_i V_s^o)_i p C]$: We then get a similar condition IC_s for the senior workers derived from $V_s^o \downarrow V_s^d$

$$u_{s}^{o} + p(1_{i}) \ \mathbb{C} \ \mathbf{u}_{s}^{d \circ} + u^{\mathbf{x}} (1_{i}) \ (31)$$

Both IC_j and IC_s need be satis⁻ed. To determine which one of the two is binding, consider

Now given the de nition of $\mathbf{C} = \mathbf{V}_{s}^{o} \mathbf{i} \mathbf{V}_{i}^{o}$; we can write IC_s as

$$V_j^o + C_j V_j^d + \frac{u_s^d i u_j^d}{r+1}$$

since

$$V_{s}^{d} i V_{j}^{d} = \frac{U_{s}^{d} i U_{j}^{d}}{r+1} > 0$$

This implies that IC_j is binding $i^{\textcircled{m}} \Leftrightarrow \ \ \, \frac{u_{s\,i}^d \ \, u_j^d}{r+1}$ and IC_s if $\diamondsuit \cdot \ \ \frac{u_{s\,i}^d \ \, u_j^d}{r+1}$ (note that both are binding at $s_j = s_s$: then $\diamondsuit = 0$ and $u_s^d = u_j^d$). From the de⁻nition of \diamondsuit

$$IC_{j} \text{ binding }, \quad \frac{u_{s}^{o} i \quad u_{j}^{o}}{r+m^{\mathbb{R}}} \stackrel{u_{s}^{d} i \quad u_{j}^{d}}{r+1}$$
(32)

Assuming existence of a non degenerate distribution, we now proceed as in the proof of Theorem 2 by calculating the distribution. If (32) holds, from (30) (holding with equality), we can calculate f_1 which gives (18). This completes the proof.

In the following Lemma, we make use of assumption A in order to determine when IC_j is binding.

Lemma 6 Under assumption A; and for any sharing rule fs_j ; s_sg , with $s_j \ 2 \ [s_j; s_s]$, there exists a pair $(r_1; \mathbb{B}_1)$ such that for any $r \ 2 \ (0; \mathbf{p}]$; and for any $\mathbb{B} \ 2 \ (0; \mathbf{e}]$, IC_j is binding.

Proof. We show that $u_s^o i u_j^o u_s^d i u_{jh}^{d}$. The left hand side can be written as $s_s(Q^o) i s_j(Q^o)$: The right hand side is $s_s(Q_s^d) i s_j(Q_j^d) i c(e_s^d) i c(e_j^d)$: For any $s_j \cdot s_s$; and given A1 and A2 it follows that $e_j^d \cdot e_s^d$ (from $\frac{@u}{@e_i} = s_iQ_e i c^0(e_i) = 0$; and c convex the envelope theorem implies that $\frac{@e_i}{@s_i} < 0$) and as a result, $Q_s^d u_s^d Q_j^d$: Since $Q^o > Q^d$; it immediately follows that $u_s^o i u_j^o u_s^d i u_j^d$: For a _nite m; there always exists a pair (r; ®) small enough such that equation (32) is satis ed. To see this, for any r; let ® · $\frac{1}{m}$, which is su±cient. Then let (r_1 ; $@_1$) be chosen such that (32) holds with equality. From Lemma 5, it follows that the binding constraint is IC_j . ■

We can now \neg nalize the proof of Proposition 2 and derive the distribution f. As in theorem 2, there exists a pair (r; [®]) such that (30) holds with equality. To see this, note that $\lim_{r! \to 0} \lim_{s! \to 0} (m_i)$

1) $\mathbb{C} = \frac{m_i 1}{m} \frac{1}{s} u_s^0 i u_j^0$, so that in the limit, the left hand side of IC_j in equation (30) is equal to $u_j^0 + \frac{m_i 1}{m} u_s^0 i u_j^0 = \frac{1}{m} Q^0 i c(e^0) > u^{\alpha}$: Choose $(r_2; \mathbb{B}_2)$ to satisfy (30) with equality. Let $(\mathbf{b}; \mathfrak{B}) = \min f(r_1; \mathbb{B}_1); (r_2; \mathbb{B}_2)g$: Then, under assumption A; Lemma 6 holds, so that from Lemma 5, it follows that $f = f_1$

$$f = 1_{i} \frac{u_{j}^{d}_{j} u_{j}^{o}(r+1) + {}^{\otimes}(m_{i} 1)C}{u_{j}^{o}(r+1)_{i} ru_{j}^{d}_{i} u_{j}^{a} + {}^{\otimes}(m_{i} 1)(1+r)C} \frac{}{1_{i} {}^{\otimes}}$$

This completes the proof of Proposition 2. ■

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