# One-Sided Testing for ARCH Exect Using Wavelets

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## ABSTRACT

There has been an increasing interest in hypothesis testing with inequality restrictions. An important example in time series econometrics is hypotheses on autoregressive conditional heteroskedasticity (ARCH). We propose a one-sided test for ARCH using the wavelet method, a new analytic tool developed in the last decade or so. The test is based on a wavelet spectral density estimator at frequency zero of the square of estimated residuals from a regression model. The square of an ARCH process is positively correlated at all lags, resulting in a spectral mode at frequency zero. In particular, it has a spectral peak at frequency zero when there exists persistent ARCH, or when ARCH e<sup>a</sup>ect is small at each lag but carries over a long distributional lag. Because wavelets can e<sup>a</sup>ectively capture spectral peaks, we expect that the wavelet test is more powerful than the kernel counterpart when there exists persistent ARCH or when ARCH e<sup>a</sup>ect has a long distributional lag. This is con...rmed in a simulation study, which also compares a number of important one-sided and two-sided ARCH tests.

Key words: ARCH, one-sided hypothesis, time series, spectral analysis, wavelet

## 1. INTRODUCTION

Hypothesis testing with inequality restrictions has been important in econometrics and statistics (e.g., Andrews 1998, Bera et al. 1998, Gourieroux et al. 1982, King and Wu 1998, Self and Liang 1987, SenGupta and Vermeire 1986, Silvapulle and Silvapulle 1995, Wolak 1989, Wu and King 1994). An important example in time series econometrics is hypotheses on ARCH, where parameters of interest are zero if there is no ARCH and are nonnegative if ARCH exists.

Detection of ARCH is important from both theoretic and practical points of view. Neglecting ARCH may lead to arbitrarily large loss in asymptotic e¢ciency of parameter estimation (e.g., Engle, 1982); cause overrejection of conventional tests for serial correlation such as those of Box and Pierce (1970) and Ljung and Box (1978) (e.g., Taylor 1984, MilhÁj 1985, Diebold 1987); and result in overparameterization of ARMA models (e.g., Weiss 1984). Although the one-sided nature of ARCH has been long well-known, most ARCH tests are two-sided. Among them are Engle (1982), McLeod and Li (1983), Bera and Higgins (1992), Gregory (1989), Hong and Shehadeh (1999), Lee (1991), and Weiss (1986). Brock et al.'s (1991,1996) chaotic correlation dimension test for serial dependence also has excellent power against ARCH.

Exploration of the one-sided nature of ARCH is expected to increase power in small samples. Engle et al. (1985) suggest using the square root of the Lagrangian Multiplier (LM) test, with proper sign, to test ...rst order ARCH. This approach, however, could not be generalized to test higher order ARCH. Lee and King (1993,1994) are apparently the ...rst to develop one-sided tests for ARCH of general order q. They propose a locally most mean powerful score-based test for ARCH(q), using SenGupta and Vermeire's (1986) approach for one-sided multiparameter hypotheses. Demos and Sentana (1998) consider a convenient one-sided LM test for ARCH(q) in spirit similar to Kuhn-Tucker Multiplier tests (cf. Gourieroux et al. 1982). Lee and King (1993) and Demos and Sentana (1998) also consider one-sided tests for GARCH(1,1), which are numerically identical to their tests for ARCH(1) respectively. Andrews (1999) also considers one-sided tests (e.g., Engle 1982), indicating nontrivial gains of exploring the one-sided nature of ARCH.

Hong (1997) recently proposed a one-sided ARCH test by observing that the spectral density of the square of an estimated residual from a regression model is uniform when there is no ARCH and is always larger than the uniform one at frequency zero whenever

ARCH exists. Hong (1997) uses Parzen's (1957) kernel estimator to construct the test. The test is shown to perform well in comparison with some popular one-sided and twosided ARCH tests, and it requires no formulation of an alternative model (e.g., the orders of ARCH or GARCH processes).

It is well-known that in ...nite samples the kernel method tends to underestimate the spectral density at frequencies where there is a mode, no matter whether a ...nite sample optimal bandwidth is available (cf. Priestley 1981). The kernel method is not an ideal tool in capturing signi...cantly inhomogeneous spectral features. In the present context, the one-sided nature of ARCH implies that the square of a linear ARCH process is positively correlated at all lags, always resulting in a spectral mode at frequency zero. In particular, the spectral density of the squared process exhibits a peak at frequency zero when there exists persistent ARCH, or when ARCH exect carries over a long distributional lag, although it may be small at each individual lag. Examples are nearly integrated GARCH processes, and fractionally integrated GARCH processes (cf. Baillie 1986). In such situations, the kernel method cannot be expected to perform well.

The recent development of wavelet analysis provides a tool to construct a potentially more powerful one-sided test for ARCH. Wavelet analysis is a new analytic tool developed over the last decade or so. It is a spatially adaptive analytic tool that can e⊄ciently capture signi...cantly inhomogeneous features (e.g., Donoho and Johnstone 1994,1995a,1995b, Donoho et al. 1996, Gao 1993, Neumann 1996, Wang 1995). In this paper, we propose a one-sided test for ARCH using a wavelet spectral density at frequency zero of the square of estimated residuals from a regression model. Because of the nature of ARCH, the wavelet method is expected to be more powerful than the kernel method where there exists persistent ARCH. Besides the ARCH context, spectral peaks may arise due to strong dependence, seasonality, and business cycles. Therefore, our approach might have potential applications to testing a broad range of one-sided hypotheses. The present paper merely provides an example to illustrate how wavelets can be used to develop powerful econometric procedures.

Wavelets have been applied to time series analysis in several directions. Gao (1993) uses the wavelet method to estimate the spectral density of a stationary Gaussian time series. Neumann (1996) considers wavelet estimation of the spectral density of a stationary non-Gaussian process. Priestley (1996) explores potential applications of wavelet analysis to nonstationary time series evolutionary spectral analysis. See also Subba Rao. In

econometrics, Gilbert (1995) uses the wavelet method to estimate and test structural changes. Jensen (1996) uses wavelets to estimate a long memory model via maximum likelihood. There have been also some applications of wavelet methods to economic and ...nancial time series (e.g., Go¤e 1994, Ramsey 1998, Ramsey and Lampart 1998a,1998b, Ramsey and Zhang 1996,1997, Ramsey et al. 1995).

We ...rst describe the basic framework and hypotheses of interest in Section 2. Section 3 is an introduction to wavelet analysis and especially its application to spectral analysis. In Section 4, we propose a test based on a wavelet spectral density estimator, and derive its asymptotic distribution. An asymptotic local power analysis is given in Section 5. In Section 6, we adapt the proposed test to data-dependent choice of ...nest scale parameter—the smoothing parameter in the wavelet estimation. Section 7 presents a Monte Carlo comparison between the proposed wavelet test, three existing one-sided ARCH tests, and Engle's (1982) popular two-sided LM test. Section 8 concludes the paper. All proofs are collected in the appendix. Unless indicated, all convergencies are taken as the sample size n ! 1; A<sup>a</sup> denotes the complex conjugate of A; jjAjj = ftr(A<sup>0</sup>A)g<sup>1</sup>/<sub>2</sub> the Euclidean norm of A; C a generic bounded constant that may di¤er from place to place; and Z = f0; §1; §2; :::g the set of integers.

## 2. FRAMEWORK AND HYPOTHESES

Throughout, we consider the following data generating process: ASSUMPTION A.1:  $fY_tg$  is a stochastic time series process

$$Y_{t} = g(X_{t}; b_{0}) + "_{t}; "_{t} = *_{t}h_{t}^{\frac{1}{2}}; \qquad (2.1)$$

where  $X_t$  is a vector consisting of exogenous variables and lagged dependent variables,  $b_0$  is a ...nite-dimensional parameter vector, and  $h_t$  is a positive time-varying measurable function with respect to the information set  $I_{t_i 1}$  available at period  $t_i$  1: The innovation sequence  $f_{*t}g$  is independent and identically distributed (i.i.d.) with  $E(*_t) = 0$ ;  $E(*_t^2) = 1$ and  $E(*_t^8) < 1$ : Moreover,  $*_t$  is independent of  $X_s$  for all  $s \cdot t$ :

This is a setup often seen in the ARCH literature (e.g., Bollerslev et al. 1992). We make no distributional assumption on innovation  $*_t$  except the existence of an eighth moment. The process  $f''_tg$  is an adapted martingale dimerence sequence with respect to  $I_{t_i \ 1}$ ; namely  $E("_t j I_{t_i \ 1}) = 0$  almost surely. Its conditional variance,  $E("_t^2 j I_{t_i \ 1}) = h_t$ ; is

time-varying. Throughout, we consider a generalized linear ARCH process

$$h_{t} = -_{0} + \frac{X}{|t_{i}|^{2}}; \qquad (2.2)$$

where  $\bar{}_0 > 0$ ;  $\mathbf{P}_{I=1}^1 < 1$ ; and  $\bar{}_I \ge 0$  for all I  $\ge 1$  to ensure positivity of h<sub>t</sub> (cf. Nelson and Cao 1992, Drost and Nijman 1993). One example is Engle's (1982) ARCH(q) process

$$h_{t} = {}^{-}_{0} + \underbrace{\mathbf{X}}_{\substack{|=1\\ |=1}} {}^{-}_{1} {}^{"2}_{t_{i}} :$$
(2.3)

Another example is Bollerslev's (1987) GARCH(p; q)

$$h_{t} = {}^{\circ}_{0} + \frac{\mathbf{X}}{|_{l=1}} {}^{\otimes}_{|_{t_{i}}|_{l}} + \frac{\mathbf{X}}{|_{l=1}} {}^{\circ}_{|}h_{t_{i}}; \qquad (2.4)$$

whose  $coe Ccient \[-1]$ , which is a function of  $f^{(e)}_{1}$ ;  ${}^{\circ}_{1}g$ ; decays to zero exponentially as I ! 1: The class (2.2) also includes Baillie et al.'s (1996) fractionally integrated GARCH process. For this process,  $\[-1]_{i}$  decays to zero slowly.

Under (2.2), the null hypothesis of no ARCH can be stated as

$$H_0: \bar{j} = 0$$
 for all  $j = 1; 2; ...$ 

The alternative hypothesis that ARCH exists is

 $H_A$ :  $\bar{j}_i = 0$  for all j = 1; 2; ...; with at least one strict inequality.

The alternative  $H_A$  is one-sided. To test such a hypothesis, we take a frequency domain approach. Let f(!) be the standardized spectral density of  $"_t^2$ ; that is,

$$f(!) = (2\%)^{i} {}^{1} {}^{\%} {}_{j=i} {}^{1} {}^{\%} (j) e^{i i j !}; ! 2 [i \%; \%];$$
(2.5)

where  $\frac{1}{t}(j)$  is the autocorrelation function of  $f_t^2g$ : Because (2.2) implies that  $f_t^2g$  follows an AR(1) process:

$$"_{t}^{2} = -_{0} + \bigvee_{j=1}^{2} -_{j} "_{t_{i}j}^{2} + W_{t}; \qquad (2.6)$$

with  $E(w_t j I_{t_j 1}) = 0$  almost surely. Under  $H_0$ ,  $f''_t g = w_t$  is a white noise, we have  $f(0) = (24)^{j}$ . On the other hand, under  $H_A$ ; we have  $\frac{1}{2}(j) = 0$  for all  $j \ge Z$  and there exists at least one j such that  $\frac{1}{2}(j) > 0$ : It follows that  $f(0) > (24)^{j-1}$  under  $H_A$ :

This forms a basis for constructing a one-sided test for  $H_0$  vs.  $H_A$ : We can compare a consistent estimator for f(0) and  $(2^{4})^{i}$  and test if their di¤erence is signi...cantly larger than zero: Note that we do not specify any particular alternative model (e.g., the orders of GARCH(p; q)) under  $H_A$ ; the proposed test will be consistent (i.e., has asymptotic unit power) against the class of general linear ARCH processes, which include ARCH, GARCH and fractionally integrated GARCH with known or unknown orders.

Hong (1997) proposes a consistent one-sided ARCH test using a Parzen's (1957) kernel estimator for f (0): While the kernel estimator is consistent, it tends to underestimate f (0) when there is a spectral mode at frequency zero (e.g., Priestley 1981). This is indeed the case under  $H_A$ ; which implies that the autocorrelations of  $f_t^2$  are positive at all lags and consequently result in a spectral mode at frequency zero. In particular, when the  $\bar{j}$  are small but decay to zero slowly, there is a spectral peak at frequency zero. This is the case with highly persistent volatility clustering. For such cases, the kernel method may not be expected to be most powerful.

## 3. WAVELET METHOD

The recent development of wavelet analysis provides a potentially useful tool to test ARCH. Wavelet analysis is a new mathematical tool. It can exectively estimate inhomogeneous spectral density functions (e.g., Gao 1993, Neumann 1996). We now propose a wavelet estimator for f(0); the standardized spectral density at frequency zero of  $f''_t^2g$ , and use it to construct a one-sided test for ARCH.

Throughout, we use multiresolution analysis (MRA), introduced by Mallat (1989). MRA is a mathematical method to describe a square-integrable function  $g(c) 2 L_2(R)$  at dimerent scales. The key of MRA is the introduction of the mother wavelet function  $\tilde{A}$ :

ASSUMPTION A.2:  $\tilde{A} : \mathbb{R} \mid \mathbb{R}$  is an orthonormal mother wavelet such that  $\frac{R_1}{\prod_{i=1}^{k} \tilde{A}(x)dx = 0$ ;  $\frac{R_1}{\prod_{i=1}^{k} \tilde{A}^2(z)dz = 1$  and  $\frac{R}{\tilde{A}(x)\tilde{A}(x_i \mid k) = 0$  for all k 2 Z; k  $\in 0$ :

The orthonormality of  $\tilde{A}$  implies that the doubly in...nite sequence  $f\tilde{A}_{jk}g$  constitutes an orthonormal basis for  $L_2(R)$ , where

$$\tilde{A}_{jk}(x) = 2^{j=2}\tilde{A}(2^{j}x_{j} k); \qquad j; k \in \mathbb{Z}:$$
(3.1)

This sequence is obtained from a single mother wavelet  $\tilde{A}$  by dilations and translations. The integers j and k are called the dilation and translation parameters respectively. Intuitively, j localizes analysis in frequency and k localizes analysis in time (or space). This simultaneous time-frequency localization of information is the key feature of wavelet analysis, explaining why wavelets are attractive for function approximation. The dilation factor can di¤er from 2, but "2" ensures the L<sub>2</sub>-invariance that  $\begin{bmatrix} R_1 \\ i \\ 1 \end{bmatrix} \tilde{A}_{jk}(x)^2 dx = \begin{bmatrix} R_1 \\ i \\ 1 \end{bmatrix} \tilde{A}(x)^2 dx$ : Often  $\tilde{A}(x)$  is well-localized (i.e.,  $\tilde{A}(x) ! 0$  su¢ciently fast as x ! 1), so  $\tilde{A}_{jk}(x)$  is e¤ectively nonzero only around an interval of width 2<sup>i j</sup> centered at k=2<sup>j</sup>:

The mother wavelet à can have bounded support. An example is Haar wavelet:

$$\tilde{A}(x) = \begin{cases} \tilde{a} & \text{if } 0 < x \cdot \frac{1}{2}; \\ \tilde{b} & \text{if } i \frac{1}{2} \cdot x < 0; \\ 0 & \text{otherwise.} \end{cases}$$
(3.2)

Compact support ensures that  $\tilde{A}$  is well-localized in time domain. Daubechies (1992) shows that for any nonnegative integer D; there exists an orthonormal compact supported wavelet whose ...rst D moments vanish. The mother wavelet  $\tilde{A}$  can also have in...nite support, but it must decay to zero su¢ciently fast at in...nity. An example is the Littlewood -Paley wavelet  $\tilde{A}(\mathfrak{k})$ , which is de...ned via its Fourier transform

$$\hat{A}(z) \quad (2\%)^{i \frac{1}{2}} \quad \tilde{A}(x)e^{i izx}dx = (2\%)^{i \frac{1}{2}}1(jzj \cdot 2\%); \qquad z \ 2 \ R; \qquad (3.3)$$

where 1(¢) is the indicator function. Other wavelet examples include Franklin wavelet, Lemarie-Meyer wavelets, and spline wavelets. See (e.g.) Hernandez and Weiss (1996) for details.

For any  $g(x) \ge L_2(R)$ ; we have the wavelet representation

$$g(\mathbf{x}) = \sum_{j \geq \mathbf{Z}}^{\mathbf{X}} \sum_{k \geq \mathbf{Z}}^{\mathbf{R}} \tilde{A}_{jk}(\mathbf{x}); \qquad (3.4)$$

where the wavelet coe¢cient

$$^{\otimes}_{jk} = \sum_{\substack{i=1\\ j=1}}^{I} g(x)\tilde{A}_{jk}(x)dx:$$
(3.5)

Cf. Mallat (1989) and Daubechies (1992). The localization property of  $\tilde{A}$  ensures that  $^{(m)}_{jk}$  basically depends on the local property of g on an interval of width  $2^{i j}$  centered at  $k=2^{j}$ : This is fundamentally di¤erent from Fourier representation, where each Fourier coe¢cient depends on the global property of g: An essential feature of wavelet analysis is that wavelets, in an "automatic manner", evaluate high frequency components of g on small intervals, and low frequency components of g on large intervals. Consequently,

they can exectively represent signi...cantly inhomogeneous functions with a relatively small number of wavelet coe¢cients. Wavelet coe¢cients are large where g exhibits signi...cant inhomogeneity, and are small where g is smooth.

To represent the standardized spectral density f(!) of  $f''_t^2g$ ; which is 24-periodic and thus is not square-integrable on R; we need to periodize the wavelet basis  $f\tilde{A}_{jk}g$  via

$$a_{jk}(!) = (2\%)^{j\frac{1}{2}} \prod_{m=j=1}^{k} \tilde{A}_{jk}(\frac{!}{2\%} + m);$$
 (3.6)

which is 24-periodic. With such periodic orthonormal bases for  $L_2(I)$ , where  $I = [i \ 4; 4]$ ; we can represent f(!) via wavelet bases:

$$f(!) = \frac{1}{2\frac{1}{4}} + \frac{\mathbf{X} \mathbf{X}}{\sum_{j=0}^{8} k=1} e_{jk} e_{jk}(!); \qquad (3.7)$$

where the wavelet coe¢cient

$$^{\mathbb{B}}_{jk} = \int_{i^{\frac{1}{4}}}^{I} f(!)^{a}_{jk}(!) d! : \qquad (3.8)$$

See Lee and Hong (1998) and Hong and Lee (1999). Denote the Fourier transform of  $\tilde{A}(x)$  by  $Z_{1}$ 

$$\hat{A}(z) = (2\frac{1}{4})^{i\frac{1}{2}} \int_{i^{1}}^{z} \tilde{A}(x)e^{i^{i}zx}dx:$$
(3.9)

Assumption A.2 ensures that  $\hat{A}(z)$  exists and is continuous almost everywhere; with  $j\hat{A}(z)j \cdot C$ ;  $\hat{A}(j z) = \hat{A}^{(z)}; \hat{A}(0) = 0$  and  $\frac{R_1}{i + 1} j\hat{A}(z)j^2dz = 1$ : By Parseval's identity, we can equivalently express the wavelet coeC cient

where  $a_{jk}(I)$  is the Fourier transform of  $a_{jk}(I)$ ; that is,

$$\overset{\mathbf{A}}{}_{jk}(\mathbf{I}) = (2\frac{1}{2})^{i\frac{1}{2}} \overset{a}{}_{jk}(!)e^{i\frac{1}{2}} d! = e^{i\frac{2\frac{1}{2}}{2}\mathbf{I}k=2^{j}}(2\frac{1}{2}=2^{j})\hat{\mathbf{A}}(2\frac{1}{2}=2^{j}): \quad (3.11)$$

In (3.11) the second equality follows from (3.6) and a change of variable. Note that the translation parameter k is converted into a "modulation", i.e., the multiplication of an exponential. This is a natural consequence of the Fourier transform of convolution.

We impose an additional assumption on  $\tilde{A}$ :

ASSUMPTION A.3:  $j\hat{A}(z)j \cdot C \min f j z j^q$ ;  $(1 + j z j)^{i/2} g$  for some q > 0 and i > 1:

This requires that  $\hat{A}$  have some regularity (i.e. smoothness) at 0 and su $\oplus$ ciently fast decay at 1. The condition  $j\hat{A}(z)j \cdot Cjzj^q$  is exective as z ! 0; where q governs the degree of smoothness of  $\hat{A}(z)$  at zero. If  $\prod_{i=1}^{n} (1 + jxj^\circ)j\tilde{A}(x)jdx < 1$  for some  $\circ > 0$ ; then  $j\hat{A}(z)j \cdot Cjzj^q$  for  $q = min(\circ; 1)$ ; cf. Priestley 1996). When  $\tilde{A}$  has ...rst D vanishing moments (i.e.,  $\prod_{i=1}^{n} x^r \tilde{A}(x)dx = 0$  for  $r = 0; ...; D_i = 1$ ); we have  $j\hat{A}(z)j \cdot Cjzj^D$  as z ! 0: On the other hand,  $j\hat{A}(z)j \cdot C(1 + jzj)^{i-z}$  is exective as z ! = 1. It holds trivially for the so-called band-limited wavelets, whose  $\hat{A}$ 's have compact supports (cf. Hernandez and Weiss 1996).

Most commonly used wavelets satisfy Assumptions A.2-A.3. Examples include Daubechies' (1992) compactly supported wavelets of positive order, Franklin wavelet, Lemarie-Meyer wavelets, Littlewood-Paley (or Shannon) wavelets, and spline wavelets. See (e.g.) Hernandez and Weiss (1996) for more discussions. Assumption A.3 rules out Haar wavelet, however, because its  $\hat{A}(z) = i e^{iz=2} \sin^2(z=4)=(z=4)$  decays to zero at a rate of jzj<sup>i 1</sup> only.

To obtain a feasible wavelet estimator of f(0); we use the estimated regression residual

$$\mathbf{r}_{t} = \mathbf{Y}_{t} \mathbf{j} \mathbf{g}(\mathbf{X}_{t}; \mathbf{\hat{b}}); \tag{3.12}$$

where  $\hat{b}$  is a consistent estimator of  $b_0$ : We impose the following assumptions on the regression model  $g(X_t; b)$  and parameter estimator  $\hat{b}$ :

ASSUMPTION A.4: (i) For each b 2 B;  $g(\mathfrak{k}; \mathfrak{b})$  is a measurable function with respect to  $I_{t_{i} 1}$ ; (ii)  $g(X_t; \mathfrak{k})$  is twice continuously di¤erentiable with respect to b in an open convex neighborhood  $B_0$  of  $b_0$  almost surely, with  $\lim_{n!=1} \operatorname{fn}^{i} \prod_{t=1}^{n} \operatorname{E} \sup_{b \ge B_0} jj \frac{e}{eb} g(X_t; \mathfrak{b}) jj^4 g < 1$  and  $\lim_{n!=1} \operatorname{fn}^{i} \prod_{t=1}^{n} \operatorname{E} \sup_{b \ge B_0} jj \frac{e^2}{ebeb^0} g(X_t; \mathfrak{b}) jj^2 g < 1$ : ASSUMPTION A.5:  $n^{\frac{1}{2}}(\hat{b}_i \ b_0) = O_P(1)$ :

We permit but do not require that  $\hat{b}$  be the ordinary least square (OLS) or quasimaximum likelihood estimators (e.g., Lee and Hansen 1994, Lumsdaine 1996). Any  $p_{\overline{n}}$ consistent estimator of  $b_0$  su¢ces.

Now, de...ne the sample autocorrelation function of squared residuals  $f_t^{r_t^2}$ 

$$\Re(I) = \hat{R}(I) = \hat{R}(0);$$
(3.13)

where the sample autocovariance of  $f_t^{n_2}g$ 

$$\hat{R}(I) = n^{i} \prod_{t=j|j+1}^{N} {\binom{n^2}{t} = \frac{3}{4}^2} i 1) {\binom{n^2}{t_i} \frac{3}{j|j} = \frac{3}{4}^2} i 1); \qquad I \ 2 \ Z$$
(3.14)

with  $\Re^2 = n^{i-1} P_{\substack{n=1\\t=1}}^n R_t^2$ : A wavelet spectral estimator for f(0) can be given as

$$\mathbf{f}(0) = (2\%)^{i^{1}} + \frac{\mathbf{X} \mathbf{X}}{\sum_{j=0}^{a} \sum_{k=1}^{j k} (0)}; \qquad (3.15)$$

where the empirical wavelet coe¢cient

$${}^{\circledast}_{jk} = \sum_{i^{\frac{1}{4}}}^{Y_{4}} \hat{\Gamma}(!)^{a}_{jk}(!) d! = (2^{\frac{1}{4}})^{i^{\frac{1}{2}}} \sum_{l=1_{i}}^{\mathbb{X}^{1}} {}^{\frac{n}{2}}(l)^{\frac{n}{2}} (1);$$
 (3.16)

with  $\hat{\Gamma}(!) = (2\frac{1}{4}n)^{i} {}^{1}j \sum_{t=1}^{n} {}^{n}t^{2}e^{i!t}j^{2}$  the periodogram of  $f^{n}t^{2}g$ . There are two ways to compute  $\circledast_{jk}$ : For compactly supported wavelets  $\tilde{A}$ ;  $a_{jk}(!)$  in (3.6) is a sum of ...nite terms. The ...rst expression of  $\circledast_{jk}$  in (3.16) is e¢cient to compute. For the band-limited wavelets (whose  $\hat{A}$  has compact supports), the second expression of  $\circledast_{jk}$  in (3.16) is convenient to compute, as it is a sum of ...nite terms.

The integer J is called the …nest scale parameter. Given n, a large J will lead to a smaller bias but a larger variance for f(0): We need to choose J properly to balance the bias and variance. In subsequent sections, we will provide proper conditions on J to ensure that the proposed test statistic have a well-de…ned limit distribution.

## 4. TEST STATISTIC AND ITS DISTRIBUTION

To introduce our test statistic, we de...ne

$$z_{x}(z) = 2\frac{\pi}{\hat{A}^{*}(z)} \prod_{m=i=1}^{\infty} \hat{A}(z + 2\frac{\pi}{m}):$$
 (4.1)

Assumptions A.2-A.3 implies that (z) is continuous almost everywhere, with (0) = 0 and  $j_(z)j \cdot C$ . Note that the tail behavior of (z) is governed by  $\hat{A}(z)$ ; because  $P_{\substack{1 \\ m=j}}^{1} \hat{A}(z + 24m)$  is 24-periodic. For convenience, we impose a condition on (z):

ASSUMPTION A.6: : R ! R is square-integrable.

Most commonly used wavelets satisfy this assumption. Because  $\hat{A}^{\alpha}(z) = \hat{A}_{i}(z)$  given Assumption A.2, the condition that (z) is real-valued implies (i z) = (z):

The test statistic for  $H_0$  vs.  $H_A$  is de...ned as

$$S_{n}(J) \stackrel{f}{=} V_{n}^{i\frac{1}{2}}(J)n^{\frac{1}{2}} \stackrel{h}{=} f(0)_{i} (24)^{i\frac{1}{2}}; \qquad (4.2)$$

where

$$V_{n}(J) = \bigvee_{I=1}^{\infty} (1_{i} I = n) \bigvee_{j=0}^{\infty} (2\frac{1}{2}I = 2^{j})^{2}$$
(4.3)

The factor 1 i I=n is a ...nite sample correction; it could be replaced by unity.

The statistic  $S_n$  is applicable for both small J (i.e., J is ...xed) and large J (i.e., J  $J_n ! 1$  as n ! 1): For and only for large J; we could also use the statistic

$$S_n(J) = i_{n=2} V_0^{i_{\frac{1}{2}}} V_0^{i_{\frac{1}{2}}} f(0)_i (24)^{i_{\frac{1}{2}}};$$
 (4.4)

where

$$V_0 = \int_{0}^{24} j_i(z) j^2 dz$$
 (4.5)

and

$$i_{j}(z) = \bigwedge_{m=j=1}^{\mathbf{X}} \hat{A}(z + 2m\%):$$
(4.6)

This statistic has the same null asymptotic distribution as  $S_n(J)$  when J is large, because  $V_n(J)=2^J \mid V_0$  as  $J \mid 1$  (see Lemma A.2 in the appendix). It is simpler to compute than  $S_n(J)$ ; but may have less desirable sizes in ...nite samples, especially when J is small. Theorem 1: Suppose that Assumptions A.1-A.6 hold, and  $2^J=n \mid 0$  as  $n \mid 1$ : Then under  $H_0$ 

 $S_n(J)$ ! N(0; 1) in distribution.

Both small and large (i.e., ...xed and increasing) ...nest scales J are allowed here. The choice of J may have important impact on the behavior of  $S_n(J)$ : We will use a data-driven method to choose J in the simulation study below:

# 5. ASYMPTOTIC LOCAL POWER

We now study the asymptotic power of  $S_n(J)$  under the following class of generalized linear local alternatives

$$( \ M_{a}(a_{n}): h_{t} = \frac{3}{4}_{0}^{2} \ 1 + a_{n} \sum_{j=1}^{-1} ("_{t_{i} j i} 1);$$

where  $\bar{j}_{j=1}^{j=1}$ , 0;  $P_{j=1}^{1}\bar{j}_{j}^{j=1} < 1$  and  $a_{n}$  ! 0: Without loss of generality we further assume  $a_{n} P_{j=1}^{1}\bar{j}_{j}^{j=1} < 1$  for all n to ensure positivity of  $h_{t}$ : The class  $H_{a}(a_{n})$  describes all linear local ARCH alternatives, which include ARCH, GARCH and fractionally integrated GARCH of known or unknown orders.

Theorem 2: Suppose that Assumptions A.1-A.6 hold. (i) Let J 2 Z be ... xed. De... ne

$$\label{eq:started_st$$

Theorem 2(i) implies that with ... xed ... nest scale J;  $S_n(J)$  has nontrivial power against  $H_a(a_n)$  with parametric rate  $a_n = n^{\frac{1}{2}}$ , provided  $P_{l=1}^1 d_J(l)^{-1} \in 0$ . It has no power whenever  $\prod_{l=1}^{1} d_J(l) = 0$ ; which may occur for a ... xed J; because  $d_J(l)$  is a local average, depending on J and wavelet Ã: On the other hand, Theorem 2(ii) implies that with increasing ...nest scale J;  $S_n(J)$  has nontrivial power against all linear local ARCH processes asymptotically. This follows because the noncentrality parameter  $^{1} > 0$  whenever ARCH exists (i.e., at least one parameter  $\bar{i} > 0$ ): Hong's (1997) kernel test is also consistent for all linear local ARCH processes. The tests of Lee and King (1993) and Demos and Sentana (1998) are not designed to test all linear local ARCH alternatives, since they are interested in testing a parametric ARCH(q) for ...xed q. Lee and King (1993) and Demos and Sentana (1998) also consider one-sided tests for GARCH(1,1), which numerically coincide with their tests for ARCH(1) respectively. The extension to testing GARCH(p; q) for p; q > 1 is more di¢cult, because some of the parameters do not lie on the boundary of the parameter space (cf. Lee and King 1993, Demos and Sentana 1998). We note that Andrews (1999) recently also considered one-sided testing for GARCH(1,1) using a di¤erent approach.

The consistency of  $S_n(J)$  against all possible linear local ARCH alternatives is desirable when no prior information about the alternative is known. This is, however, achieved at the price that  $S_n(J)$  can detect  $H_a(a_n)$  with  $a_n = 2^{J=2}=n^{\frac{1}{2}}$  only. This rate is slower than the parametric rate  $n^{i-\frac{1}{2}}$ ; as is typical for nonparametric smoothed testing. However, it may not be taken too literally in practice. For example, if  $2^J \neq (\ln n)^2$ ; the rate of the local alternatives is  $n^{i-\frac{1}{2}} \ln(n)$ ; only slightly slower than  $n^{i-\frac{1}{2}}$ : Finally, we note that because of the one-sided nature of the tests, it is appropriate to use upper-tailed N (0; 1) critical values for  $S_n(J)$ : For example, the upper-tailed N (0; 1) critical value at the 5% level is 1.645.

## 6. ADAPTION TO DATA-DRIVEN FINEST SCALE

Theorem 2 shows that  $S_n(J)$  is consistent for all linear locally ARCH processes as J increases. In practice, the choice of J may have important impact on the power. Because usually no prior information on the alternative is available, it may be desirable if J can be determined by suitable data-driven methods. To allow for such a possibility, we give the conditions on the data-dependent ...nest scale  $\hat{J}$  (say) under which the randomness of  $\hat{J}$  has asymptotically negligible exect on the limit distribution of  $S_n(J)$ .

ASSUMPTION A.7:  $\int$  is a data-driven ...nest scale such that  $\int_{i}^{J} J = o_{P}(2^{i}^{J=2})$ ; where J is a nonstochastic integer.

For ...xed J; Assumption A.7 becomes  $\hat{J}_i = o_P(1)$ :

**Theorem 3:** Suppose that Assumptions A.1-A.7 hold, and  $2^{J}=n ! 0$ : Then under  $H_0$ ;  $S_n(\hat{J}) \in S_n(J) ! 0$  in probability, and  $S_n(\hat{J}) ! N(0; 1)$  in distribution.

So far there are very few data-driven methods to choose J available in the literature. To our knowledge, only Walter (1995) proposes a data-driven J; using a mean square error criterion. We will use it in our simulation study below.

# 7. MONTE CARLO EVIDENCE

We now investigate the ...nite sample performance of the wavelet-based test  $S_n(J)$ . We use Franklin wavelet and the second order spline ( $S_1$  and  $S_2$ ; respectively). Franklin wavelet is de...ned via its Fourier transform,

$$\mathbf{A}(z) = (2\%)^{i} \, {}^{1=2} e^{iz=2} \frac{\sin^4(z=4)}{(z=4)^2} \, \mathbf{\mu} \frac{1}{(1 \, i \, 2=3 \sin^2(z=2))(1 \, i \, 2=3 \sin^2(z=4))} \, {}^{\mathbf{\eta}_{1=2}} : \qquad (7.1)$$

For the second order spline wavelet, its Fourier transform

$$\mathbf{R}(z) = \mathbf{i} \ (2^{4})^{\mathbf{i}} \ {}^{1=2}\mathbf{i} e^{\mathbf{i} z=2} \frac{\sin^{6}(z=4)}{(z=4)^{3}} \frac{\mathbf{\mu}}{\mathbf{P}(z=4 + \frac{1}{4}=2)} \frac{\mathbf{P}(z=4 + \frac{1}{4}=2)}{\mathbf{P}(z=2)\mathbf{P}(z=4)}$$
(7.2)

where  $P(z) = \frac{1}{30}\cos^2(2z) + \frac{13}{30}\cos(2z) + \frac{8}{15}$ :

The choice of the ...nest scale parameter, J; may be important. We choose a datadriven J via Walter's (1994) algorithm, which makes use of the fact that the change in the integrated mean squared error (IMSE) from one scale to the next ...ner scale is proportional to the sum of squared empirical wavelet coe¢cients. The change in IMSE from J<sub>i</sub> 1 to J is proportional to  $P_{k=1}^{2^J} \circledast_{Jk}^2$ ; where  $\circledast_{Jk}$  is the empirical wavelet coe $\mathbb{C}$ cient at the scale J: One starts from the initial scale J = 0 and checks how much the error changes from 0 to 1: The grid search is iterated until we get the scale J at which the error increases most rapidly. Then, one obtains the ...nest scale. In our simulation, we choose the ...nest scale J for which the change in error between J and J + 1 exceeds 100 %. We note that this method is more suitable for estimation of f(!) on [i ¼;¼] rather than at frequency zero. Nevertheless, the simulation below shows that it works relatively well in the present context.

We compare  $S_1$  and  $S_2$  with three one-sided ARCH tests—Hong's (1997) kernel test (denoted K), Lee and King's (LK; 1993) locally most mean powerful test, and Demos and Sentana's (1998) one-sided LM test (DS). We also include Engle's (1982) two-sided LM test (LM); which is commonly used in practice. For the K test; we use Quadratic-Spectral kernel and select a data-driven bandwidth via Andrews' (1991) plug-in method based on an ARCH(1,1) approximating model. For the LK test, we use the version of the test statistic which is robust to non-normality (see Lee and King 1993, (13)). The tests of  $S_1$ ;  $S_2$ ; K; and LK are all asymptotically one-sided N(0; 1) under H<sub>0</sub>. The DS test is computed as the sum of the squared t-statistics of the positive coe¢cients in the regression of  $\frac{n^2}{t}$  on a constant and the ... rst q lags of  $\frac{n^2}{t}$ . This test has a nonstandard mixed chi-square distribution, whose critical values are given in Demos and Sentana's (1998, Table 1). The LM test has asymptotic  $\hat{A}_{\alpha}^2$  distribution under H<sub>0</sub> and is computed as (n j q)R<sup>2</sup>; where  $R^2$  is the squared correlation coeCcient in the regression of  $\frac{n^2}{t}$  on a constant and the ...rst q lags of  $n_t^2$ : For LK; DS and LM; the lag order q has to be chosen a priori. These tests will attain their maximal powers when using the optimal lag order, which depends on the alternative. When the order of the alternative is unknown, as is often the case in practice, these tests may sumer from power losses when using a suboptimal lag order. To investigate the exect of using dixerent choices of q for these tests; we consider q = 1 and 12 (denoted LK(1); LK(12); DS(1); DS(12); LM(1); and LM(12)):

Consider the data generating process

$$Y_t = X_t^0 b_0 + "_t; "_t = *_t h_t^{1=2};$$
  $t = 1; 2; ...; n;$ 

where  $X_t = (1; m_t)^0$ ;  $m_t = 0.8m_{t_i 1} + A_t$  and  $A_t \gg i.i.d$ . N(0; 4);  $*_t \gg i.i.d$ . N(0; 1): Both  $f_tg$  and  $fA_tg$  are mutually independent. We set  $b_0 = (1; 1)^0$  and estimate them by OLS. As in Engle et al. (1985), the exogenous variable  $m_t$  is generated for each experiment and held ...xed from iteration to iteration. Two sample sizes, n = 100; 200; are considered. To

reduce the possible exects of the initial condition, n + 1000 observations are generated and then the ...rst 1000 ones are discarded. Also, the initial values for "t; t  $\cdot$  0 are set to be zero, and ht; t  $\cdot$  0 is set to be 1: For each experiment, 1000 iterations are generated using the GAUSS random number generator on a personal computer.

We …rst study the size by setting  $h_t = 1$ : Table 1 reports the size at the 10 % and 5 % levels using asymptotic critical values. The tests  $S_1$ ;  $S_2$  and K attain reasonable sizes, though they tend to slightly underreject. The tests LK(1) and DS(1) have best sizes. The tests LK(12) and LM(12) show some underrejections, while DS(12) tends to overreject slightly.

Next, we investigate the power under the following alternatives.

ARCH(1):	$h_t = 1 + \frac{-12}{4};$
ARCH(12a):	$h_t = 1 + \frac{P_{12}}{P_{j=1}^{j=1}} \frac{P_{2}}{t_i j};$
ARCH(12b):	$h_t = 1 + \frac{-\mu_{12}}{j=1}(1 j j = 13)''_{t_i j};$
GARCH(1,1):	$h_t = 1 + {}^{\textcircled{R}} {}^{"2}_{t_i 1} + {}^{-} h_{t_i 1}$ :

For these alternatives, we choose the values of parameters (®; <sup>-</sup>) to ensure strictly positive conditional variance and ...nite unconditional variance. For ARCH(1), we consider <sup>-</sup> = 0:3; 0:95: It does not have a sharp spectral peak at any frequency. In contrast, ARCH(12a) and ARCH(12b) are allowed to have a relatively long distributional lag, which generates a spectral peak at frequency zero. Linearly declining weights in ARCH(12b) were often considered in the literature (e.g., Engle 1982, Engle et al. 1987). We consider <sup>-</sup> = 0:95=12 for ARCH(12a) and <sup>-</sup> = 0:95=  $P_{j=1}^{12}(1 \text{ j } j=13)$  for ARCH(12b). GARCH(1,1) is a workhorse in modelling economic and ...nancial time series (cf. Bollerslev 1986). When (e) + <sup>-</sup> < 1; GARCH(1,1) can be expressed as ARCH(1) with coe¢cients declining at exponential rate. We set ((e); <sup>-</sup>) = (0:3; 0:3); (0:3; 0:65): The latter displays relatively persistent ARCH, which yields a spectral peak at frequency zero. Tables 2-4 report the size-corrected power under these alternatives. The empirical critical values are obtained from 1000 replications under H<sub>0</sub>.

Table 2 reports the power against ARCH(1). For  $\bar{} = 0.3$ ; LK(1) and DS(1) have similar powers and are the most powerful. The K test has power very close to that of LK(1) and DS(1): These three tests have better power than LM(1); which in turn has better power than S<sub>1</sub> and S<sub>2</sub>. Compared to the kernel test K; wavelets su¤er from nontrivial power loss when there is no sharp spectral peak. The fact that LK(1) and DS(1) are most powerful here is not surprising, because they use the optimal lag q = 1: The powers of LK(12); DS(12) and LM(12) are substantially smaller, with LK(12) the smallest. These tests are less powerful than  $S_1$  and  $S_2$ : This suggests that power loss may be severe when one uses a suboptimal q for LM; DS and LM: Note that the power rankings remain largely the same when  $^- = 0.95$ :

Table 3 reports the power under ARCH(12a) and ARCH(12b). Under ARCH(12a), LK (12) has the best power, and dominates DS(12): These two tests use the optimal lag order q = 12: Both S<sub>1</sub> and S<sub>2</sub> have power close to that of LK (12): They have better power than K: The S<sub>2</sub> test is slightly better than DS(12) and is substantially better than LM(12) for n = 100; although the latter uses the optimal lag. This indicates that wavelets work pretty well when ARCH e<sup>xect</sup> has a relatively long distributional lag. Under ARCH(12b), S<sub>1</sub>; S<sub>2</sub> and LK (12) have comparable power and are more powerful than DS(12); LM (12); K; LK (1) and DS(1):

Table 4 reports the power against GARCH(1,1). When (®; <sup>-</sup>) = (0:3; 0:3); there is relatively weak ARCH e<sup>a</sup>ect. In this case K attains the best power, followed very closely by LK(1) and DS(1); then by S<sub>1</sub> and S<sub>2</sub>; and ...nally by LM(1): Nevertheless, the power di<sup>a</sup>erence among these tests is marginal. The tests DS(12); LM(12) and LK(12) su<sup>a</sup>er from severe power losses, especially for LK(12): When (®; <sup>-</sup>) = (0:3; 0:65); there is relatively persistent ARCH, Here, S<sub>1</sub> and S<sub>2</sub> perform the best. They outperform K; which, in turn, is more powerful than LK(1); DS(1) and LM(1): The powers of LK(12); DS(12) and LM(12) are smaller than those of LK(1); DS(1) and LM(1) respectively, but the di<sup>a</sup>erences are rather small. This suggests that the use of a long lag order may not su<sup>a</sup>er from severe power loss when there exists persistent ARCH. Finally, we note that while DS(1) and LK(1) have similar power when (®; <sup>-</sup>) = (0:3; 0:3) and (0:3; 0:65); DS(12) has better power than LK(12) when (®; <sup>-</sup>) = (0:3; 0:3); and similar power when (®; <sup>-</sup>) = (0:3; 0:65):

In summary, we ...nd:

1) The wavelet tests,  $S_1$  and  $S_2$ ; have similar size and power in almost all the cases. The choice of wavelet function is not important.

2) The relative power performance of the one-sided kernel and wavelet tests depends on the spectral shape of the squared residuals. When ARCH is of a short memory (as in ARCH(1), GARCH(1,1) with ( $^{(R)}$ ;  $^{-}$ ) = (0:3; 0:3)), the one-sided kernel test is more powerful than the one-sided wavelet test. When there exists relatively persistent ARCH (i.e., GARCH(1,1) with ( $^{(R)}$ ;  $^{-}$ ) = (0:3; 0:65); or when ARCH e<sup>x</sup>ect has a long distributional lag (i.e., ARCH(12)), there is a spectral peak at frequency for the squared time series process. In this case, the wavelet test outperforms the kernel test.

3) The tests LK, DS and LM attain their own maximal powers when the optimal lag order is used, but they may sumer severe power loss when a suboptimal lag is used. Under each alternative, the two-sided LM test is always dominated by some one-sided tests using the same lag order. This suggests nontrivial power gain of exploiting the one-sided nature of the ARCH alternative.

4) None of the one-sided tests dominates the others in power for the alternatives under study. When ARCH exect has short memory (ARCH(1) and GARCH(1,1) with  $(^{(R)}; ^{-}) = (0:3; 0:3)$ ), the one-sided kernel test has power comparable to that of LK(1) and DS(1), which use the correct lag order and are most powerful. When ARCH exect has relatively long memory (ARCH(12a,b) and GARCH(1,1) with  $(^{(R)}; ^{-}) = (0:3; 0:65)$ ); the one-sided wavelet test has power close to or even better than that of LK and DS with the optimal lag orders. We note that both the kernel and wavelet tests do not require the knowledge of the optimal lag.

The fact that the kernel test K has good power when ARCH e<sup>max</sup> ect is weak or of relatively short memory while the wavelet tests S<sub>1</sub> and S<sub>2</sub> have good power when ARCH e<sup>maxx</sup> e<sup>maxx</sup> exect is persistent suggests that a suitable Bonferoni procedure that combines the kernel and wavelet tests may have good power against both weak and persistent ARCH. We consider two simple Bonferoni procedures, BF<sub>1</sub>; which combines S<sub>1</sub> and K; and BF<sub>2</sub>; which combines S<sub>2</sub> and K: The simple BF<sub>1</sub> procedure works as follows: Let P<sub>1</sub> and P<sub>2</sub> be the smaller and larger asymptotic p-values of test statistics fS<sub>1</sub>; Kg: Then one rejects H<sub>0</sub> at level ® if P<sub>1</sub> < ®=2: The same procedure applies to BF<sub>2</sub>: Table 5 reports the size and power of BF<sub>1</sub> and BF<sub>2</sub> at the 10% and 5% levels. Both BF<sub>1</sub> and BF<sub>2</sub> show some underrejections, which is consistent with the conservative nature of Bonferoni procedures. In spite of this underrejection in size, however, they do have all-round good power against all the alternatives under study. In particular, they have better power than the wavelet tests S<sub>1</sub> and S<sub>2</sub> when ARCH is less persistent, and have better power than the K test when ARCH is persistent. This suggests that BF<sub>1</sub> and BF<sub>2</sub> do combine the advantages of the wavelet and kernel approaches.

#### 8. CONCLUSION

We consider a wavelet-based one-sided test for ARCH. The test statistic is based on a wavelet spectral density estimator at frequency zero of the square of estimated residuals

from a regression model. An essential feature of ARCH is that the squared process is positively correlated at all lags, thus resulting in a spectral mode at frequency zero. In particular, a spectral peak arises when there exists persistent ARCH, or when ARCH exect carries over a long distributional lag, although its exect may be small at each lag. Because the kernel method tends to underestimate modes or peaks, it may not be a powerful tool when there exists persistent ARCH. In contrast, wavelets can e¢ciently capture such inhomogeneous features as spectral peaks, and are expected to perform well in these situations. This is con...rmed in a simulation study. Since there exists unknown smoothness from the data, the wavelet-based test for ARCH is a useful complement to the existing one-sided tests for ARCH.

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### MATHEMATICAL APPENDIX

To prove Theorems 1-2, we ... rst state some useful lemmas.

Lemma A.1: De...ne

$$d_{J}(I) = \bigotimes_{j=0}^{X} (2\frac{1}{2}I = 2^{j}); I; J 2 Z;$$

where (z) as in (4.1). Then

(i)  $d_{J}(0) = 0$  and  $d_{J}(i) = d_{J}(i)$ ;

(ii)  $jd_J(I)j \cdot C$  uniformly in J and I;

- (iii) For any given I 2 Z; I  $\in$  0; d<sub>J</sub>(I) ! 1 as J ! 1; (iv) For r 1;  $P_{I=1}^{n_i \ 1} j d_J(I) j^r = O(2^J)$  as J; n ! 1:

Proof of Lemma A.1: See Hong and Lee (1999, Proof of Lemma A.1).

Lemma A.2: Let  $V_n(J)$  and  $V_0$  be de...ned as in Theorem 1. Suppose  $J ! 1 ; 2^J = n ! 0$ : Then  $V_n(J)=2^J ! V_0$  as n ! 1:

**Proof of Lemma A.2:** Recalling the de...nition of  $d_J(I)$ ; we put

$$\forall_{n}(J) = \bigvee_{I=1}^{\mathbf{X}^{1}} d_{J}^{2}(I) = \bigvee_{p=i \ J \ j = jpj \ I=1}^{\mathbf{X}^{1}} (2^{i}_{A}I = 2^{j}) (2^{jpj}2^{i}_{A}I = 2^{j});$$

where the second equality follows by reindexing. We shall show  $\forall_n(J)=2^{J+1}$ !  $V_0$ ; which, with dominated convergence, implies  $V_n(J)=2^{J+1}$ !  $V_0$ : Let  $I = I_n$ ! 1; I=J! 0 as n! 1 : Decompose

$$\forall_n(J) = \forall_n(I) + Q_{1n} + Q_{2n};$$
 (A1)

where

$$Q_{1n} = (2^{j})_{(2^{j}p_{2})} (2^{jp_{2}}2^{j}|_{2^{j}});$$

$$Q_{2n} = (2^{j})_{(2^{j}p_{2})} (2^{jp_{2}}2^{j}|_{2^{j}});$$

$$Q_{2n} = (2^{j})_{(2^{j}p_{2})} (2^{jp_{2}}2^{j}|_{2^{j}});$$

For the second term  $Q_{1n}$  in (A1), we have that as n ! 1 ;

$$Q_{1n} = 2^{J} \underbrace{\mathbf{X} \mathbf{X}}_{p=i \ J \ j=l+1} \underbrace{\mathbf{Z}}_{p=i \ 1} \underbrace{\mathbf{X}}_{2^{i} \ (J \ i \ j)} \frac{1}{2^{j}} \underbrace{(2^{j}+2^{j})}_{l=1} \underbrace{(2^{j}+2^{j})}_{l=1} \underbrace{(2^{j}+2^{j})}_{l=1} \underbrace{(2^{j}+2^{j})}_{l=1} \underbrace{(2^{j}+2^{j})}_{l=1} \underbrace{(2^{j}+2^{j}+2^{j})}_{l=1} \underbrace{(2^{j}+2^{j}+2^{j})}_{l=1} \underbrace{(2^{j}+2^{j}+2^{j})}_{l=1} \underbrace{(2^{j}+2^{j}+2^{j}+2^{j})}_{l=1} \underbrace{(2^{j}+2^{j}+2^{j}+2^{j}+2^{j})}_{l=1} \underbrace{(2^{j}+2^{j}+2^{j}+2^{j}+2^{j}+2^{j})}_{l=1} \underbrace{(2^{j}+2^$$

by dominated convergence,

and symmetry of  $_{(z)}$  given Assumption A.5: Using a similar reasoning, for the last term in (A1), we have

$$Q_{2n} = 0(2^{J+1})$$
: (A3)

Finally, for the ...rst term in (A1), we can show

by Assumption A.5, where we used the fact that for any I > 0; j > 0;

$$2^{i j} \overset{\mathbf{X}^{1}}{\overset{2}{\underset{l=1}{}}} (2^{i j} \overset{2}{\underset{l=1}{}}) = 2^{i j} \overset{\mathbf{X}^{i}}{\underset{l=1}{}} + \overset{\mathbf{X}^{1}}{\underset{l=2^{j}+1}{}} \overset{\mathbf{A}_{s}^{2}(2^{i j} \underset{l=2^{j})}{\overset{2}{\underset{l=2^{j}+1}{}}} \overset{\mathbf{X}^{1}}{\underset{l=2^{j}+1}{}} C(2^{i j} \underset{l=2^{j}+1}{\overset{2}{\underset{l=2^{j}+1}{}}})$$

$$\cdot 2^{i j} \overset{\mathbf{X}^{i}}{\underset{l=1}{}} C(2^{i j} \underset{l=2^{j}+1}{\overset{2}{\underset{l=2^{j}+1}{}}}) \overset{\mathbf{X}^{1}}{\underset{l=2^{j}+1}{}} C(2^{i j} \underset{l=2^{j}+1}{\overset{2}{\underset{l=2^{j}+1}{}}})$$

$$\cdot C + C 2^{i j} \overset{\mathbf{X}^{i}}{\underset{l=2^{j}+1}{}} (1 + 2^{i j} \underset{l=2^{j})^{i 2^{i j}}}{\overset{2^{i j}}{\underset{l=2^{j}+1}{}}} \overset{\mathbf{X}^{1}}{\underset{l=2^{j}+1}{}})$$

$$\cdot C + C 2^{i j} \overset{\mathbf{X}^{i}}{\underset{l=2^{j}+1}{}} (1 + 2^{i j} \underset{l=2^{j})^{i 2^{i j}}}{\overset{2^{i j}}{\underset{l=2^{j}+1}{}}} \overset{\mathbf{X}^{i}}{\underset{l=2^{j}+1}{}})$$

where the ...rst inequality follows by Assumption A.5 and the last one follows from the fact that  $(1 + x)^{i} \frac{2i}{i}$  is decreasing in x > 0: Note that  $\prod_{i=0}^{n} (1 + x)^{i} \frac{2i}{i} dx < 1$  given  $i \ge 1$ : Collecting (A1)-(A4) and I=J ! 0 yields the desired result.

Lemma A.3: Let  $\bar{(I)}$  be a sequence of autocovariances with  $P_{I=1}^{1}j^{-}(I)j < 1$ ; and let  $d_{J}(I)$  be demned as in Lemma A.1: Then  $P_{I=1}^{n_{i}1}d_{J}(I)^{-}(I)! P_{I=1}^{1}^{-}(I)$  as J; n! 1:

Proof of Lemma A.3: We write

For the second term, we have

$$\begin{array}{c} \mathbf{X} & \mathbf{X} \\ \mathbf{J} & \mathbf{I} \\ \mathbf$$

as n ! 1 given  $P_{I=1}^{1}j^{-}(I)j < 1$ : For the ...rst term, we have

$$\mathbf{X}^{1}$$
 fd<sub>J</sub>(l) i 1g<sup>-</sup>(l) i 0 (A7)

as J; n ! 1 by dominated convergence,  $d_J(I)_i$  1 ! 0 for any I 2 Z as J ! 1; and  $jd_J(I)_i$  1j · C from Lemma A.1: Collecting (A6)-(A7) yields the desired result.

Lemma A.4: Let  $V_n(J)$  be as de...ned in (4.3). Suppose  $\int 2 Z$  is a data-driven integer such that  $\int_{i}^{J} J = o_P(1)$ ; where  $J \ge Z$  is nonstochastic, then  $V_n(J)=V_n(J)$ ! <sup>p</sup> 1:

**Proof of Lemma A.4**: By the de...nition of  $V_n(J)$  in (4.3) and the Cauchy-Schwarz inequality; we have

$$\begin{bmatrix} V_{n}(J) & V_{n}(J) \end{bmatrix}^{\frac{1}{2}} \cdot \begin{bmatrix} X^{1} & J_{j}(I) & J_{j}(I) \\ I = 1 \end{bmatrix} = \begin{bmatrix} d_{j}(I) & J_{j}(I) & J_{j}(I) \end{bmatrix}^{\frac{1}{2}} = \begin{bmatrix} d_{j}(I) & J_{j}(I) & J_{j}(I) \end{bmatrix}^{\frac{1}{2}} \end{bmatrix}$$

Now, given Assumptions A.5 and A.7, we have  $jd_{j}(I)_{i} d_{J}(I)_{j} \cdot P_{max(j;J)}_{j=min(j;J)} j_{s}(2^{1}_{4}I=2^{j})_{j;}$ and so

$$\begin{aligned} \mathbf{X}^{1} & \text{fd}_{J}(\mathbf{I})_{\mathbf{i}} \, d_{J}(\mathbf{I})g^{2} & \cdot & C^{2} \\ \mathbf{X}^{1} & \overset{\mathbf{R}}{\leftarrow} \max_{\mathbf{X}}^{(\mathbf{J},\mathbf{J})} & \overset{\mathbf{P}_{2}}{=} & \mathbf{X}^{1} & \overset{\mathbf{R}}{\leftarrow} \max_{\mathbf{X}}^{(\mathbf{J},\mathbf{J})} & \overset{\mathbf{P}_{2}}{=} \\ & \cdot & (2^{\mathcal{H}}\mathbf{I}=2^{\mathbf{J}})^{q}; & + C^{2} & (2^{\mathcal{H}}\mathbf{I}=2^{\mathbf{J}})^{i}; \\ & \cdot & C^{2}(\mathbf{J}_{\mathbf{i}} \, \mathbf{J})^{2}2^{i} \overset{2q\min(\mathbf{J},\mathbf{J})}{\mathbf{m}} & \overset{\mathbf{P}_{2}}{=} & (\mathbf{J}_{\mathbf{i}} \, \mathbf{J})^{2}2^{i} \overset{2q\min(\mathbf{J},\mathbf{J})}{\mathbf{m}} & \overset{\mathbf{P}_{2}}{=} \\ & = & (\mathbf{J}_{\mathbf{i}} \, \mathbf{J})^{2} & 2^{i} \overset{2q}2^{i} \overset{2q\min(\mathbf{J},\mathbf{J})}{\mathbf{m}} & \overset{\mathbf{P}_{2}}{=} & \mathbf{M}^{1} & \overset{\mathbf{R}}{\leftarrow} & \overset{\mathbf{M}}{=} \\ & = & O_{P} \mathbf{f}(\mathbf{J}_{\mathbf{i}} \, \mathbf{J})^{2}2^{\mathbf{J}}g \end{aligned}$$

$$(A9)$$

by choosing  $m = 2^J$  and noting  $\int_i^{J} J = o_P(1)$ : This, together with  $V_n(J) = O(2^J)$  from Lemma A.2; implies

$$jV_n(\hat{J})=V_n(J)_i \quad 1j = V_n(J)^{i-1}jV_n(\hat{J})_i \quad V_n(J)j = O_P(\hat{J}_i \quad J) = o_P(1):$$

Proof of Theorem 1: Put  $u_t = w_t^2 i$  1: De...ne

$$f(0) = \frac{1}{2\frac{1}{4}} + \frac{\mathbf{X} \ \mathbf{X}}{\substack{j=0 \ k=0}} \ \mathbf{B}_{jk}^{a} \ _{jk}(0); \tag{A10}$$

Write  $f(0)_i$  (24)<sup>i 1</sup> = ff(0)<sub>i</sub> f(0)g + ff(0)<sub>i</sub> 1=24g: We shall prove Theorem 1 by showing Theorems A.1-A.2 below.

Theorem A.1:  $V_n^{i\frac{1}{2}}n^{\frac{1}{2}}f(0)_i f(0)g!^p 0$ : Theorem A.2:  $V_n^{i\frac{1}{2}}n^{\frac{1}{2}}\chi ff(0)_i (2\chi)^{i\frac{1}{2}}g!^d N(0;1)$ :

Proof of Theorem A.1: Recall that  $a_{jk}(h)$  is the Fourier transform of  $a_{jk}(!)$ ; we have

$${}^{a}_{jk}(0) = (2\%)^{i\frac{1}{2}} \bigwedge_{h=i}^{A} {}_{jk}(h) = (2\%)^{i\frac{1}{2}} \bigwedge_{h=i}^{A} e^{i\frac{i2\%hk=2^{j}}{2}} (2\%=2^{j})^{\frac{1}{2}} \hat{A}(2\%h=2^{j})$$
(A11)

given (3.11). Moreover, by (3.11) and (3.16), we have

$${}^{\circledast}_{jk} = (2 \%)^{i \frac{1}{2}} \prod_{I=1_{i} n}^{\mathbf{X}^{1}} \% (I) e^{i2 \% I k = 2^{j}} (2 \% = 2^{j})^{\frac{1}{2}} \hat{A}^{*} (2 \% I = 2^{j}) :$$
 (A12)

Collecting (3.15) and (A11)-(A12) with Lemma A.1 yields

where the third equality follows because by the change of variable I = h + m; we have

where we used the well-known fact that  $\mathbf{P}_{k=1}^{2^{j}} e^{i2^{j}4mk=2^{j}} = 2^{j}$  if  $m = 2^{j}q; q \ 2 \ Z$  and  $\mathbf{P}_{k=1}^{2^{j}} e^{i2^{j}4mk=2^{j}} = 0$  otherwise (e.g., Priestley 1981, (6.19), p.392). Moreover, the last equality in (A13) follows from  $\frac{1}{2}(j \ l) = \frac{1}{2}(l); d_{j}(0) = 0$  and  $d_{j}(j \ l) = d_{j}(l)$  by Lemma A.1. Similarly, we have

$$f(0) = (2\%)^{i} + \%^{i} d_{J}(I)\%(j):$$
(A14)

Combining (A13)-(A14), we can write

$${}^{n}_{4} f(0) = {}^{n}_{I=1} d_{J}(I) f_{2}(I) = {}^{n}_{I=1} d_{J}(I) f_{2}(I) = (A15)$$

Because  $\hat{R}(0)_{i} R(0) = O_{P}(n^{i\frac{1}{2}})$  given Assumptions A.4-A.5, it succes to show

$$V_n^{i\frac{1}{2}}(J)n^{\frac{1}{2}} \prod_{I=1}^{M^1} d_J(I)f\hat{R}(I) = R(I)g!^p 0:$$
 (A16)

We shall show (A16) for large J (i.e., J ! 1 as n ! 1); where  $V_n(J) = 2^J V_0 f1 + o(1)g$  by Lemma A.2: The proof for ...xed J is similar, with  $V_n(J)$  !  $V_0(J) = O(1)$ , where  $V_0(J)$  is as in Theorem 1(i):

Put  $\hat{s}_t = r_t = 4$  and recall  $u_t = s_t^2 i$  1: Straightforward algebra yields  $\hat{R}(I) i R(I) = \hat{A}_1(I) + \hat{A}_2(I) + \hat{A}_3(I)$ ; where

Noting  $*_t = "_t = \frac{3}{4}_0$  under  $H_0$ ; where  $\frac{3}{4}_0 = E("_t^2)$ ; we have

where

$$\hat{A}_{11}(I) = n^{i} \prod_{\substack{t=l+1 \\ t=l+1}}^{X} u_t (n_{t_i \mid i} \prod_{t_i \mid l}^{t_i})^2;$$

$$\hat{A}_{12}(I) = n^{i} \prod_{\substack{t=l+1 \\ X}}^{X} u_t \prod_{t_i \mid l}^{t_i} (n_{t_i \mid i} \prod_{t_i \mid l}^{t_i});$$

$$\hat{A}_{13}(I) = n^{i} \prod_{\substack{t=l+1 \\ t=l+1}}^{X} u_t \prod_{t_i \mid l}^{t_i};$$

By the Cauchy-Schwarz inequality, the mean value theorem and Assumptions A.1 and A.4–A.5, we have

$$= O_{P}(2^{J}=n);$$

$$= O_{P}(2^{J}=n);$$

$$= O_{P}(2^{J}=n);$$

$$(X_{1}) = (X_{1}) = (X_{1})$$

where  $\mathbf{P}_{\substack{n_i \ 1 \ I=1}}^{n_i \ 1} jd_J(I)j = O(2^J)$  by Lemma A.1(iv).

Next, by a second order Taylor series expansion and Assumptions A.1 and A.4-A.5, we have

$$\begin{bmatrix} \mathbf{X}^{1} \\ \mathbf{J}^{1} \\ \mathbf{J}^{$$

by Markov's inequality and Lemma A.1, where we have used

$$E\overset{\circ}{\circ}n^{i-1} \overset{\mathbf{X}}{\underset{t=1}{\overset{}}} u_{t}\overset{\ast}{\underset{t_{i}}{\overset{}}} \frac{@}{@b}}g(X_{t};b_{0})\overset{\circ}{\overset{\circ}{\circ}} = O(n^{i-1})$$

given  $E(u_t j I_{t_i 1}) = 0$  a:s: Finally, we also have

$$\begin{bmatrix} \mathbf{X}^{1} \\ d_{J}(\mathbf{I})\hat{A}_{13}(\mathbf{I}) \end{bmatrix} = O(2^{J} = n^{\frac{1}{2}})$$
(A19)

by Markov's' inequality and  $\sup_{0 < l < n} E \hat{A}_{13}^2(l) = O(n^{i-1})$ , which follows from  $E(u_t j I_{t_i-1}) = 0$ a:s: and Assumption A.2. Combining (A17)-(A19) and  $\frac{3}{4}^2 i \frac{3}{4}^2 = O_P(n^{i\frac{1}{2}})$ ; we obtain

$$\mathbf{X}^{1} d_{J}(\mathbf{I}) \hat{A}_{1}(\mathbf{I}) = O_{P}(2^{J} = \mathbf{n}):$$
(A20)

Similarly, we have

$$\mathbf{X}^{1}$$
  
 $d_{J}(\mathbf{I})\hat{A}_{2}(\mathbf{I}) = O_{P}(2^{J}=\mathbf{n}):$  (A21)

Next, we consider  $\hat{A}_3$ : As shown in Hong (1997, p.272),

I

$$\sup_{\substack{0 < l < n \\ l = 1}} j\hat{A}_{3}(l)j \cdot n^{i} \stackrel{\mathbf{X}}{\underset{t=1}{\overset{(*)}{\overset{2}{\overset{2}{t}}}}_{t} | *^{2}_{t} )^{2} = O_{P}(n^{i} )^{1}:$$
This, together with 
$$P_{\substack{n_{i} \\ l=1}}^{n_{i} 1} jd_{J}(l)j = O(2^{J}) \text{ from Lemma A.1(iv); implies}$$

$$\begin{bmatrix} \mathbf{X}^{1} \\ \mathbf{J} \\ \mathbf{J} \\ \mathbf{J} \end{bmatrix}_{l=1}^{t} d_{J}(l)\hat{A}_{3}(l) \stackrel{1}{\underset{l=1}{\overset{2}{t}}} \sup_{0 < l < n} j\hat{A}_{3}(l)j = O_{P}(2^{J} = n): \quad (A22)$$

Collecting (A20)-(A22) and  $V_n(J) = 2^{J+1}V_0f1 + o(1)g$  by Lemma A.2, we have **X**<sup>1</sup>

$$V_n^{i\frac{1}{2}}n^{\frac{1}{2}} = O_P(2^{J=2}=n^{\frac{1}{2}}) = O_P(1)$$

given 2<sup>J</sup>=n! 0: This completes the proof for (A16), and thus for Theorem A.1. Proof of Theorem A.2: Put  $\hat{W} = \Pr_{I=1}^{n_i \ I} d_J(I) R(I) = R(0)$ : By (A14), we have

given R(0);  $R(0) = O_P(n^{\frac{1}{2}})$  by Assumption A.1 and  $H_0$ .

Write

$$\hat{W} = n^{i-1} \frac{X}{t=2} W_t;$$
 (A24)

where  $W_t = R^{i}(0)u_t \frac{P_{t_i}}{1-1} d_J(1)u_{t_i}$ : Observe that  $fW_t$ ;  $I_tg$  is an adapted martingale di¤erence sequence, we shall prove the asymptotic normality of  $\hat{W}$  by the martingale theorem (e.g. Hall and Heyde 1980, pp.10-11). First, from (A24), we have

$$V \operatorname{ar}(n^{\frac{1}{2}} \hat{W}) = R^{i^{2}}(0)n^{i^{1}} \sum_{t=2}^{\infty} EW_{t}^{2} = \sum_{t=2}^{\infty} d_{J}^{2}(I)$$
$$= (1 + 1) (1 +$$

By Hall and Heyde (1980, pp.10-11),  $V_n^{i\frac{1}{2}}(J)n^{\frac{1}{2}}\hat{W}$  ! <sup>d</sup> N (0; 1) if

$$V_{n}^{i^{2}}(J)n^{i^{1}} \prod_{t=2}^{X} W_{t}^{2} \mathbf{1} \mathbf{f} \mathbf{j} W_{t} \mathbf{j} > (n^{\frac{1}{2}} V_{n}^{\frac{1}{2}}(J) \mathbf{g} \text{ for any } (N > 0);$$
 (A26)

and

$$V_n^{i^2}(J)n^{i^1} \sum_{t=2}^{\infty} fE(W_t^2 j I_{t_i^1})_i EW_t^2 g ! 0:$$
 (A27)

For sake of space, we shall show the central limit theorem for  $\hat{W}$  for large J (i.e., J ! 1): The proof for ...xed J is similar and simpler because d<sub>J</sub>(I) is ...nite and summable.

Given (A25) and Lemma A.2, we shall verify condition (A26) by showing  $2^{i} {}^{2J}n^{i} {}^{2} \mathbf{P}_{t=1}^{n} \mathbb{E}W_{t}^{4}$ ! 0: Put  ${}^{1}_{4} = \mathbb{E}(u_{t}^{4})$ : By Assumption A.1, we have

$$EW_{t}^{4} = {}^{1}{}_{4}R^{i}{}^{4}(0)E \begin{pmatrix} \mathbf{x}^{1} \\ \mathbf{x}^{2}(0) \begin{pmatrix} \mathbf{x}^{1} \\ \mathbf{x}^{1$$

It follows that  $2^{i} {}^{2J}n^{i} {}^{2} \mathbf{P}_{t=1}^{n} EW_{t}^{4} = O(n^{i} {}^{1})$ ; ensuring condition (A26). Given Lemma A.2, it su¢ces for (A27) if  $2^{i} {}^{2J}V \operatorname{arfn}^{i} {}^{1} \mathbf{P}_{t=2}^{n} E(W_{t}^{2}jI_{t_{i}})g!$  0; which

Given Lemma A.2, it su¢ces for (A27) if  $2^{i} {}^{2J}V$  arfn<sup>i 1</sup>  $_{t=2}^{n} E(W_{t}^{2}jI_{t_{i}})g!$  0; which we now focus on: By the de...nition of  $W_{t}$ , we have

$$E(W_{t}^{2}jI_{t_{i}}) = R^{i}(0) \sum_{l=1}^{t_{i}} d_{J}(l)u_{t_{i}}$$

$$= EW_{t}^{2} + R^{i}(0) \sum_{l=1}^{t_{i}} d_{J}(l)fu_{t_{i}}^{2} + R(0)g$$

$$+2R^{i}(0) \sum_{l=2}^{t_{i}} d_{J}(l)d_{J}(h)u_{t_{i}}u_{t_{i}}h$$

$$= EW_{t}^{2} + R^{i}(0)A_{t} + 2R^{i}(0)B_{t};$$

it follows that

$$n^{i^{1}} \sum_{t=2}^{N} fE(W_{t}^{2}jI_{t_{i}})_{i} EW_{t}^{2}g = R^{i^{1}}(0)n^{i^{1}} \sum_{t=2}^{N} A_{t} + 2R^{i^{1}}(0)n^{i^{1}} \sum_{t=2}^{N} B_{t}$$
$$= R^{i^{1}}(0)\hat{A} + 2R^{i^{1}}(0)\hat{B}; \text{ say.}$$
(A28)

Therefore, it su¢ces to show that  $2^{i} {}^{2J} fV ar(\hat{A}) + V ar(\hat{B})g! 0$ : First, note that  $A_t$  is a weighted sum of independent variables  $u_{t_i j j}^2 R(0)$ ; we have  $EA_t^2 = f_{4i}^1 R^2(0)g P_{I=1}^{t_i 1} d_J(I)^4$ : It follows by Minkowski's inequality that

$$E\hat{A}^{2} \cdot 2^{i} {}^{2J} n^{i} {}^{1} \sum_{t=2}^{4} (EA_{t}^{2})^{\frac{1}{2}} \cdot f^{1}{}_{4} i R^{2}(0)g \sum_{I=1}^{4} d_{J}^{4}(I) = O(2^{J})$$
(A29)

where  $\mathbf{P}_{\substack{n_{i} \ 1 \ l=1}}^{n_{i} \ 1} d_{j}^{4}(l) = O(2^{J})$  by Lemma A.1(iv).

Next, we consider V ar( $\hat{B}$ ): For all t  $_{s}$  s; we have

$$EB_{t}B_{s} = R^{2}(0) \overset{\mathbf{X}^{1} \mathbf{X}^{1} \mathbf{X}^{1} \mathbf{X}^{1}}{}_{I_{2}=2} \overset{I}{}_{h_{2}=1} \overset{I}{}_{I_{1}=2} \overset{I}{}_{h_{1}=1} \overset{I}{}_{h_{1}=1} \overset{I}{}_{h_{1}=2} \overset{I}{}_{h_{1}=1} \overset{I}{}_{h_{1}=1} \overset{I}{}_{h_{1}=2} \overset{I}{}_{h_{1}=1} \overset{I}{}_{h_{1}=1$$

where, as before,  $\pm_{jh} = 1$  if h = j and  $\pm_{jh} = 0$  otherwise. It follows that

$$E\dot{B}^{2} \cdot 2n^{i^{2}} \times EB_{t}B_{s} \cdot 2R^{2}(0)n^{i^{1}} \times^{1} \times^{1} \times^{1} jd_{J}(i + 1)d_{J}(i + h)d_{J}(1)d_{J}(h)j$$

$$\cdot 2R^{2}(0)n^{i^{1}} \times^{1} d_{J}^{2}(i) = 0 \quad i = 1 \quad jd_{J}(1)j$$

$$= O(2^{3J} = n) \quad (A30)$$

where  $P_{I=1}^{n_i \ 1} jd_J(I)j^r = O(2^J)$  for r > 1; by Lemma A.1(iv). Collecting (A28)-(A30) yields  $2^{i \ 2J} fV ar(\hat{A}) + V ar(\hat{B})g = O(2^{i \ J} + 2^J = n) ! 0$  given J ! 1;  $2^J = n ! 0 as n ! 1$ : Thus, condition (A27) holds. By Hall and Heyde (1980,pp.10-11),  $V_n^{i \ \frac{1}{2}}(J)n^{\frac{1}{2}}\hat{W} ! ^d N(0; 1)$ :

Proof of Theorem 2: Put

$$\mathsf{R}(\mathsf{I}) = \sum_{t=\mathsf{I}+1}^{\mathsf{X}} ("_t^2 = \mathscr{U}_0^2; 1) ("_{t_i}^2 = \mathscr{U}_0^2; 1)$$
(A31)

where  $\frac{4}{3}_{0}^{2} = E(\overset{2}{t})$  under  $H_{a}(a_{n})$ : Note that we have  $\overset{2}{t} = \frac{4}{3}_{0} \Leftrightarrow \overset{2}{s}_{t}$  under  $H_{a}$ : Instead, we have

$$"_{t}=\overset{\mathbf{X}}{}_{0} = \underset{I=1}{\overset{\mathbf{X}}{}}_{1} f 1 + a_{n} \overset{\mathbf{X}}{\underset{I=1}{}}_{1} (\overset{\mathbf{X}}{}_{1} i 1)g^{2}:$$
(A32)

We now de...ne

$$f_{-}(0) = \frac{\overset{}{\mathbf{X}}^{i} \overset{}{\mathbf{X}}^{i}}{\underset{j=0 \ k=1}{\overset{@}{\rightarrow} k}^{a} _{jk}(0)}$$

where  $\mathbb{B}_{jk} = (24)^{i} \mathbb{P}_{\substack{l=1 \ l=1 \ j=1 \$ 

Theorem A.4:  $V_n^{i^{1=2}}(J)n^{1=2}$ /4ff-(0) i 1=2/4g! d N(1;1):

**Proof of Theorem A.3**: The proof is analogous to that for Theorem A.1 with the more restrictive condition J ! 1;  $2^{2J}=n !$  0. We omit it here for the sake of space.

Proof of Theorem A.4: We shall only show for the case where J ! 1: Because  $\frac{1}{4} \int_{I=1}^{n_i - 1} d_J(I) R(j)$ ; it success to show

$$V_{n}^{i} {}^{1=2}(J) n^{1=2} \bigotimes_{I=1}^{M} d_{J}(I) R(I) = R(0) ! {}^{d} N(1;1);$$
(A33)

where  ${}^{1} = V_{0}^{i} {}^{\frac{1}{2}} {P_{j=1}}^{-}_{j:1}$ ; Recall  $u_{t} = *_{t}^{2} {}^{i}_{t}$  1 and put  $V_{t} = *_{t}^{2} {P_{j=1}}^{-}_{j} {}^{i}_{t}_{t,j}$ ; By (A32)-(A33) and  $H_{a}(a_{n})$ , we have

$$\begin{aligned} \mathsf{R}(\mathsf{I}) &= n^{i} \, {}^{1} \sum_{\substack{t=l+1\\t=l+1}}^{\mathbf{X}} ( *_{t}^{2} h_{t} = *_{0}^{2} i_{l} 1 ) ( *_{t_{1}}^{2} h_{t_{1}} = *_{0}^{2} i_{l} 1 ) \\ &= n^{i} \, {}^{1} \sum_{\substack{t=l+1\\t=l+1}}^{\mathbf{X}} fu_{t} + a_{n} \mathsf{V}_{t} \mathsf{g} fu_{t_{1}} + a_{n} \mathsf{V}_{t_{1}} \mathsf{g} \\ &= n^{i} \, {}^{1} \sum_{\substack{t=l+1\\t=l+1}}^{\mathbf{X}} u_{t} u_{t_{1}} + a_{n} n^{i} \, {}^{1} \sum_{\substack{t=l+1\\t=l+1}}^{\mathbf{X}} \mathsf{V}_{t} u_{t_{1}} + a_{n} n^{i} \, {}^{1} \sum_{\substack{t=l+1\\t=l+1}}^{\mathbf{X}} \mathsf{V}_{t} \mathsf{V}_{t_{1}} + a_{n} n^{i} \, {}^{1} \sum_{\substack{t=l+1\\t=l+1}}^{i} \sum_{\substack{t=l+1\\t=l+1}}^{i} \sum_{\substack{t=l+1\\t=l+1}}^{i} \sum_{\substack{t=l+1\\t=l+1}}^{i} \sum_{\substack{t=l+1\\t=l+1}}^{i} \sum_{\substack{t=l+1\\t=l+1}}^{i} \sum_{\substack{t=l+1\\t=l+1}}^{i} \sum_{\substack{t=l+1\\t=l+1}}^{i} \sum_{\substack{t=l+1\\t=l+1}}^{i} \sum_{\substack{t=$$

where  $\mathbb{R}(I) = n^{i-1} \frac{\mathbf{P}_{t=j|j+1} u_t u_{t_i j|j}}{u_{t_i j|j}}$  as before: Put  $V_t(I) = v_t^2 \frac{\mathbf{P}_{1}}{j=1;j=1} - j u_{t_i j}$ : For the second term in (A34), we have

$$\mathbf{X}^{1}_{I=1} d_{J}(I) \hat{A}_{4}(I) = \mathbf{X}^{1}_{I=1} d_{J}(I) n^{i}{}^{1} \mathbf{X}_{t=l+1} s^{2}_{j=1} j^{i}{}^{1}_{j} u_{t_{i}j} u_{t_{i}l}$$

$$= R(0) \mathbf{X}^{1}_{J} d_{J}(I) (1_{i} I=n)^{-1}_{I}$$

$$= R(0) \mathbf{X}^{1}_{J} d_{J}(I) (1_{i} I=n)^{-1}_{I}$$

$$+ d_{J}(I)^{-1}_{I} n^{i}{}^{1} \mathbf{X}_{t} s^{2}_{t} fu^{2}_{t_{i}l} i R(0)g$$

$$+ d_{J}(I)^{-1}_{I} n^{i}{}^{1} \mathbf{X}_{t} v_{t}(I) u_{t_{i}l}$$

$$+ d_{J}(I)^{-1}_{I} n^{i}{}^{1} v_{t}(I) u_{t_{i}l}$$

$$= R(0) \sum_{I=1}^{\mathbf{X}} (2^{J=2} = n^{1=2})$$
 (A35)

where  $P_{I=1}^{n_i \ 1} d_J(I)(1_i \ I=n)^- I = P_{I=1}^{n_i \ -} < 1$  as J = 1 by Lemma A.3 and dominated convergence, and

$$\sum_{I=1}^{7} d_{J}(I)^{-} n^{i}^{1} \sum_{t=1+1}^{7} w_{t}^{2} f u_{t_{i}}^{2} i R(0) g = O_{P}(2^{J=2}=n^{1=2})$$

by the Cauchy-Schwarz inequality, Lemma A.1(iv);  $\frac{P_1}{\sum_{j=1}^{j-2} < 1}$  and  $\frac{1}{\sum_{j=1}^{j-2} < 1}$ 

$$E_{t=1+1}^{2} *_{t=1}^{2} R(0)g_{t}^{2} \cdot Cn^{i}$$

given Assumption A.1. Similarly, for the last term in (A34), we have

$$\mathbf{X} \quad (\mathbf{I})_{|\mathbf{I}|}^{T} \quad \mathbf{N}^{|\mathbf{I}|}^{T} \quad \mathbf{X} \quad \mathbf{V}_{t}(\mathbf{I}) \mathbf{u}_{t_{|\mathbf{I}|}}^{T} = O_{P}(2^{J=2}=n^{1=2})$$

given independence between  $V_t(I)$  and  $u_{t_i I}$ : Moreover, we have

$$\mathbf{X}^{1} d_{J}(\mathbf{I}) \hat{A}_{5}(\mathbf{I}) = O_{P}(2^{J=2}=n^{1=2})$$
(A36)

by the Cauchy-Schwarz inequality, Lemma A.1(iv) and  $E\hat{A}_{4}^{2}(I) \cdot Cn^{i-1}$  given independence between  $u_{t}$  and  $V_{t_{i}}$  for I > 0:

For the last term  $\hat{A}_6(I)$  in (A34), we put  $R_V(I) = Cov(V_t; V_{t_i|I})$  and  $R_V(I) = n^{i|I|} \frac{P_n}{t_{t_i|I}} V_t V_{t_i|I}$ : Then  $\mathbf{X}^1$   $\mathbf{X}^1$   $\mathbf{X}^1$ 

$$\mathbf{C}^{1} = \mathbf{X}^{1} = \mathbf{M}^{1} = \mathbf{M}^{1}$$

Because  $V_t = P_{j=1}^{I_{j=1}} (w_t^2 u_{t_i})$  is a linear process with  $P_{j=1}^{I_{j=1}} P_j^1 (v_t^2 u_{t_i})^4 < 1$ ; the cumulant condition  $P_{j=1}^{I_{j=1}} P_{j=1}^{I_{j=1}} P_{j=1}^{I_{j=1}} k(0; j; m; l) < 1$ ; where k(0; j; m; l) is the fourth order cumulant of  $V_t V_{t+j} V_{t+m} V_{t+l}$  (e.g., Hannan 1970, p.211). It follows that  $\sup_{0 < l < n} V \operatorname{arf} \mathbb{R}_V(l)$   $Cn^{i-1}$  by Hannan (1970, (5.1)): Consequently, we have

$$\begin{bmatrix} \mathbf{X}^{1} & & & \\ d_{J}(I) \mathbf{f} \mathbf{R}_{V}(I) \mathbf{j} & \mathbf{R}_{V}(I) \mathbf{g}_{-}^{-} & \\ \mathbf{I} = 1 & & \\ \end{bmatrix} \begin{bmatrix} \mathbf{X}^{1} & & \\ \mathbf{J} = \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{X}^{1} & \mathbf{I} \\ \mathbf{J} = \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} & \mathbf{I} \\ \mathbf{I} = \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \\ \mathbf{I} \\ \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \\ \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \\ \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \\ \mathbf{I} \end{bmatrix} \end{bmatrix} \begin{bmatrix} \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \\ \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \\ \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \\ \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \end{bmatrix} \end{bmatrix} \begin{bmatrix} \mathbf{I} \\ \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{I} \\ \mathbf{I} \end{bmatrix} \end{bmatrix}$$

by Markov's inequality and Lemma A.1(iv): On the other hand,  $R_V(I)$  is absolutely summable (i.e.,  $P_{I=i}^1 jR_V(I)j < 1$ ); it follows from Lemma A.3 that

$$\mathbf{X}^{1} d_{J}(\mathbf{I}) R_{V}(\mathbf{I}) \mathbf{I} \mathbf{X}_{I=1} R_{V}(\mathbf{I}) < 1$$

as J ! 1 : Therefore,  $\hat{A}_6 = O_P(1)$ : This, with (A34)-(A36),  $a_n = (2^J = n)^{\frac{1}{2}}$  and  $2^{2J} = n ! 0$ ; yields

$$\mathbf{X}^{1} \underset{I=1}{\overset{d_{J}(I)R(I)=R(0)}{=}} \mathbf{X}^{1} \underset{I=1}{\overset{d_{J}(I)R(I)=R(0)}{=}} + (2^{J}=n)^{\frac{1}{2}} \underset{j=1}{\overset{j=1}{=}} - _{j} + o_{P}(2^{J=2}=n^{1=2}):$$

Consequently, we have (A33) by Theorem 1. It follows that  $S_n ! d N(1; 1)$  given  $\forall_n(J) ! 2^{J+1}V_0f1 + o(1)g$  and Slutsky theorem. This completes the proof.

**Proof of Theorem 3:** (i) We shall show for large J only; the proof for ...xed J is similar. Here we explicitly denote  $f_{J}^{A}(0)$  as the spectral estimator (3.15) with the ...nest scale J: Recall the de...nition of  $S_n(J)$ ; we have

$$\begin{split} S_{n}(\hat{J})_{i} S_{n}(J) &= V_{n}(\hat{J})^{i\frac{1}{2}} n^{\frac{1}{2}} \chi_{f} f_{\hat{J}}^{c}(0)_{i} (2\%)^{i\frac{1}{2}} g_{i} V_{n}(J)^{i\frac{1}{2}} n^{\frac{1}{2}} \chi_{f} f_{\hat{J}}^{c}(0)_{i} (2\%)^{i\frac{1}{2}} g_{i} \\ &= f V_{n}(\hat{J}) = V_{n}(J) g^{\frac{1}{2}} V_{n}(J)^{i\frac{1}{2}} n^{\frac{1}{2}} \chi_{f} f_{\hat{J}}^{c}(0)_{i} f_{\hat{J}}^{c}(0) g_{i} \\ &+ f [V_{n}(J) = V_{n}(\hat{J})]^{i\frac{1}{2}} i 1g S_{n}(J) \end{split}$$

Because  $S_n(J) = O_P(1)$  by Theorem 1 and  $V_n(\hat{J})=V_n(J)$  ! <sup>p</sup> 1 by Lemma A.4, we have  $S_n(\hat{J})_i S_n(J)$  ! <sup>p</sup> 0 provided  $V_n^{i\frac{1}{2}}(J)n^{\frac{1}{2}} \# ff_{\hat{J}}(0)_i f_{\hat{J}}(0)g$  ! <sup>p</sup> 0; which we shall show below. (The asymptotic normality of  $S_n(\hat{J})$  follows from  $S_n(\hat{J})_i S_n(J)$  ! <sup>p</sup> 0 and Theorem 1.)

Because  $V_n(J) = O(2^J)$ ; it succes to show  $f_{j}(0) = o_P(2^{J=2}=n^{1=2})$ : Write

$${}^{1}_{4}ff_{j}^{c}(0)_{i}f_{J}^{c}(0)g = \hat{R}^{i}{}^{1}(0) \sum_{l=1}^{i}{}^{1}fd_{j}(l)_{i}d_{J}(l)gf\hat{R}(l)_{i}R(l)g + \hat{R}^{i}{}^{1}(0) \sum_{l=1}^{i}{}^{1}fd_{j}(l)_{i}d_{J}(l)gR(l):$$
(A37)

Given  $jd_{j}(I)_{i} d_{J}(I)_{j} \cdot P_{\max(\hat{J};J)}_{j=\min(\hat{J};J)} j_{a}(2\frac{1}{4}I=2^{j})_{j}$ ; we have, by Assumption A.5,

$$\begin{aligned} \mathbf{X}^{1} & \text{jd}_{J}(\mathbf{i}) \mathbf{j} \ \mathbf{R}(\mathbf{i})^{T} \mathbf{R}(\mathbf{i})^{T} \\ \stackrel{i=1}{\overset{j=\min(\mathcal{J};J)}{\overset{j=\min(\mathcal{J};J)}{\overset{j=1}{$$

by choosing  $m = 2^{J}$  and using  $\hat{J}_{i} J = o_{P}(2^{i J=2})$ ; where  $\Pr_{l=1}^{m} I^{q} j R(l) j = O_{P}(m^{q+1}=n^{\frac{1}{2}})$ and  $\Pr_{l=m+1}^{n_{i}1} I^{i} j R(l) j = O_{P}(m^{1_{i}j}=n^{\frac{1}{2}})$  by Markov's inequality, j > 1 in Assumption A.3 and  $E j R(l) j = O(n^{i \frac{1}{2}})$ :

Next, following reasoning analogous to that of (A16), we can obtain

$$\mathbf{X}^{1} d_{j}(\mathbf{I}) \mathbf{f} \hat{\mathbf{R}}(\mathbf{I}) \mathbf{j} \quad \mathbf{R}(\mathbf{I}) \mathbf{g} = \mathbf{0}_{\mathbf{P}} (2^{J} = \mathbf{n})$$
(A39)

given  $\hat{J}_{i} = o_{P}(1)$ ;  $P_{I=1}^{n_{i}1} d_{J}(I) = f_{I=1}^{n_{i}1} d_{J}(I)gf1 + o_{P}(1)g$  and  $P_{I=1}^{n_{i}1} d_{J}(I) = O(2^{J})$  by Lemma A.1. Combining (A37)-(A39) and (A16), we obtain  $f_{J}(0)_{i} f_{J}(0) = o_{P}(2^{J=2}=n^{1=2})$ : This completes the proof.

	n =	100	n =	200
	10%	5%	10%	5%
S <sub>1</sub>	8.9	5.8	7.6	4.3
S <sub>2</sub>	9.0	5.4	8.1	4.2
К	8.4	4.0	7.5	3.5
LK (1)	9.8	5.0	8.5	4.0
DS(1)	9.9	5.3	8.3	4.1
LM (1)	7.8	4.0	8.0	4.3
LK (12)	6.3	2.8	6.8	3.0
DS(12)	11.6	7.3	11.5	6.7
LM (12)	6.1	1.9	7.1	3.2

Table 1: Size at the 10 % and 5 % Levels

- 1) Model:  $Y_t = 1 + m_t + "_t; m_t = 0.8m_{t_i \ 1} + A_t;$  $A_t \ s \ NID(0; 4); "_t = *_t h_t^{1=2}; *_t \ s \ NID(0; 1); h_t = 1:$
- 2) 1000 iterations.

	- = 0:3					- =	= 0:95		
	n = 100		n =	n = 200		100	n =	n = 200	
	10%	5%	10%	5%	10%	5%	10%	5%	
S <sub>1</sub>	56.4	41.7	71.1	62.3	87.5	82.5	97.6	96.5	
S <sub>2</sub>	55. <b>9</b>	43.5	70.1	62.1	87.9	82.4	96.1	94.7	
К	70.8	60.4	88.8	82.7	97.5	94.8	100	99.7	
LK (1)	72.8	62.7	90.8	86.0	97.3	95.4	100	100	
DS(1)	73.1	61.7	90.9	85.7	97.4	95.7	100	99.9	
LM (1)	64.7	56.0	85.8	81.2	95.9	93.4	100	99.2	
LK (12)	24.1	16.0	36.8	27.6	46.4	33.6	73.3	63.1	
DS(12)	40.2	30.4	62.7	54.1	77.5	70.0	94.5	92.1	
LM (12)	35.4	23.8	60.7	50.8	72.5	60.0	92.3	89.4	

Table 2: Size-adjusted Power against ARCH(1) at 10 % and 5 % Levels

1) Model:  $Y_t = 1 + m_t + "_t; m_t = 0.8m_{t_i 1} + A_t; A_t \le NID(0; 4); "_t = *_t h_t^{1=2}; *_t \le NID(0; 1);$  $h_t = 1 + \frac{-}{t_i} \frac{2}{t_i}$ :

2) 1000 iterations.

ARCH 12(a)						ARC	H 12(b)		
	n =	100	n =	200	n =	100	n =	= 200	
	10%	5%	10%	5%	10%	5%	10%	5%	
S <sub>1</sub>	59.1	43.3	88.4	82.9	76.6	62.1	95.8	92.9	
S <sub>2</sub>	60.1	51.2	89.3	86.4	77.2	66.6	93.0	90.8	
К	39.6	32.9	65.1	59.3	57.3	49.7	81.4	76.8	
LK (1)	36.8	29.2	64.6	53.9	53.5	44.6	80.7	72.4	
DS(1)	36.9	28.3	65.1	53.7	53.9	43.4	80.8	72.4	
LM(1)	31.3	25.4	54.1	46.7	46.7	39.0	72.2	65.8	
LK (12)	65.8	59.3	93.0	89.8	72.8	65.7	94.1	92.0	
DS(12)	57.1	46.5	89.8	84.1	67.1	55.6	93.2	89.0	
LM (12)	49.7	41.2	87.0	81.1	60.0	50.6	91.6	88.1	

Table 3: Size-adjusted Power against ARCH(12a) and ARCH(12b) at 10 % and 5 % Levels

1) Model:  $Y_t = 1 + m_t + "_t$ ;  $m_t = 0.8m_{t_i 1} + A_t$ ;  $A_t \le NID(0; 4)$ ;  $"_t = w_t h_t^{1=2}$ ;  $w_t \le NID(0; 1)$ : 2) ARCH(12a):  $h_t = 1 + - P_{12}^{12} "_{t_i j}^2$ ; - = 0.95=12: 3) ARCH(12b):  $h_t = 1 + - P_{12}^{12} (1 - j) = 13$ ;  $T_{t_i j}^{12}$ ;  $- = 0.95= P_{12}^{12} (1 - j) = 13$ ;

4) 1000 iterations.

	(®; <sup>-</sup> ) = (0:3; 0:3)						₽; <sup>−</sup> ) =	(0:3	3; 0:6!	5)
	n =	100	n =	n = 200		n = 100			n = 200	
	10%	5%	10%	5%	· ·	10%	5%		10%	5%
S <sub>1</sub>	70.7	57.5	86.9	81.0		88.6	78.1		98.5	97.8
$S_2$	67.9	58.2	83.9	77.6	;	85.2	77.3		94.3	93.1
К	75.2	66.5	91.6	88.6	.	78.8	72.8		95.4	93.9
LK (1)	73.7	64.4	91.0	86.6	.	76.1	66.7		95.1	90.4
DS(1)	73.3	63.8	91.6	86.2	·	76.2	66.3		95.2	90.4
LM(1)	66.3	57.8	86.2	82.6		68.3	62.5		90.6	86.3
LK (12)	35.8	24.3	54.3	43.5	·	70.0	63.1		92.0	88.9
DS(12)	46.2	34.0	70.5	61.5	·	70.4	58.6		94.2	89.3
LM (12)	41.1	30.6	67.8	59.5		65.3	56.3		93.0	88.7

Table 4: Size-adjusted Power against GARCH(1,1) at 10 % and 5 % Levels

1) Model:  $Y_t = 1 + m_t + "_t$ ;  $m_t = 0.8m_{t_i 1} + A_t$ ;  $A_t \le NID(0; 4)$ ;  $"_t = *_t h_t^{1=2}$ ;  $*_t \le NID(0; 1)$ ;  $h_t = 1 + @"_{t_i 1}^2 + h_{t_i 1}$ : 2) 1000 iterations.

	n = 100					n =	200	
	BF1		BF2		BF1		BF	- 2
	10%	5%	10%	5%	10%	5%	10%	5%
Size	7.3	4.2	6.8	4.3	6.2	2.8	5.6	3.3
Power								
ARCH(1): $- = 0:3$	60.3	50.3	60.1	50.9	81.5	73.4	81.4	72.9
ARCH(1): - = 0:95	93.4	89.9	93.3	90.3	99.6	98.8	99.7	98.9
ARCH 12(a)	48.2	39.7	54.5	47.9	81.7	76.9	87.3	84.7
ARCH 12(b)	67.1	59.6	70.5	65.8	92.0	88.7	94.9	93.4
GARCH(1,1): (0:3;0:3)	69.5	61.5	69.9	63.2	89.9	85.5	89.5	85.9
GARCH(1,1): (0:3; 0:65)	83.1	76.7	84.1	78.8	97.7	96.4	98.2	97.7
Size-Adjusted Power								
ARCH(1): - = 0:3	66.0	54.0	67.2	55.0	87.7	79.8	86.4	79.5
ARCH(1): - = 0:95	95.8	91.9	96.4	92.0	99.9	99.5	99.9	99.6
ARCH 12(a)	54.2	43.1	59.0	50.4	85.9	80.4	89.1	86.7
ARCH 12(b)	71.8	62.0	76.1	67.7	94.5	90.8	95.8	94.7
GARCH(1,1): (0:3;0:3)	74.6	64.7	75.8	66.0	92.8	89.1	93.2	88.9
GARCH(1,1): (0:3; 0:65)	86.3	79.2	87.5	80.8	98.2	97.3	99.0	98.0

Table 5: Size and Power of Bonferroni Procedures at 10 % and 5 % Levels

1) BF<sub>1</sub>; Bonferoni procedure combining S<sub>1</sub> and K; BF<sub>2</sub>; Bonferoni procedure consisting of S<sub>2</sub> and K:

2) The size-adjusted power of  $BF_1$  and  $BF_2$  is based on their empirical p-values under  $H_0$ :

3) 1000 iterations.