

Computing Optimal Strata Bounds Using Dynamic Programming

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Motivation

- ▶ Sampling can be costly.
- ▶ Sample size is often chosen so that point estimates achieve a minimum level of precision.
- ▶ A stratified sampling design can reduce costs by improving efficiency relative to simple random sampling.

Stratified Sampling Design

- ▶ A stratification variable is used to partition the population into homogeneous subgroups. Simple random sampling is performed within each group.
- ▶ We want to choose the set of strata boundary points that minimizes the within-stratum variance and maximizes the between-strata variance.
- ▶ This can improve the precision of point estimates.

Optimal Stratification

- ▶ Number of strata (based on the needs of the end user)
- ▶ Optimal sample allocation (simple closed form solution exists)
- ▶ Optimal strata bounds

Optimal Stratification: Previous Research

- ▶ Approximation methods - Delenius and Hodges (1959), Gunning and Horgan (2004)
- ▶ Numerical optimization methods - Lavallee and Hidiroglou (1988), Kozak (2004)
- ▶ Dynamic Programming - Buhler and Deutler (1975), Khan, Nand and Ahmad (2008)

Contribution

- ▶ Use dynamic programming to determine optimal strata bounds.
- ▶ Build on the work of Khan, et. al. (2008) and take the theory to the data.
- ▶ Describe the user-written Stata command **optbounds** which calculates optimal strata boundary points.
- ▶ Assess margin of error (for a 95% confidence interval) and design effect.

Optimal Stratification for Variance Reduction

Let X be a random variable that is defined on $[a, b]$ and is partitioned into L strata. We want to minimize the following expression:

$$\text{Var}(\bar{x}_{st}) = \sum_{h=1}^L W_h^2 \cdot \text{Var}(\bar{x}_h) \quad (1)$$

- ▶ W_h is the weight given to stratum h , \bar{x}_h is the sample mean within stratum h and \bar{x}_{st} is the stratified sample mean.
- ▶ If we make a certain stratum smaller, the other strata must necessarily become larger.
- ▶ As a result, the strata variances must be minimized simultaneously.

Optimal Stratification: Sequential Formulation

We can rewrite (1) as a function of the strata boundary points (d_0, \dots, d_L) . An optimal stratification scheme solves the following problem:

$$\begin{aligned} \min_{\{d_1, \dots, d_{L-1}\}} \sum_{h=1}^L \phi_h(d_h, d_{h-1}), \quad (2) \\ \text{subject to } a = d_0 \leq d_1 \leq \dots \leq d_{L-1} \leq d_L = b \end{aligned}$$

- ▶ d_h and d_{h-1} are the boundary points for stratum h
- ▶ ϕ_h depends on the allocation method
- ▶ For example, under Neyman (optimal) allocation $\phi_h = W_h \sigma_h$, $n_h = \frac{n W_h \sigma_h}{\sum_{k=1}^L W_k \sigma_k}$ and $\sigma_h^2 = \frac{\sum_{i=1}^{N_h} (x_{hi} - \bar{x}_h)^2}{N_h - 1}$

Optimal Stratification as a Multi-Stage Problem

- ▶ We can rewrite (2) as a series of simple recursive equations.
- ▶ Dynamic programming provides a method for finding the set of decision rules (policy functions) that solve these equations.
- ▶ It can be shown that the solutions to the sequential and recursive problems are identical. This is referred to as the principle of optimality (Bellman 1957).

Optimal Stratification: Recursive Formulation

We can solve the recursive problem below using standard dynamic programming techniques (Rust 2008).

$$V_h(d_h) = \min_{d_{h-1}} \left[\phi_h(d_h, d_{h-1}) + V_{h-1}(d_{h-1}) \right], h \geq 2 \quad (3)$$

$$V_1(d_1) = \phi_1(d_1)$$

Subject to $d_h \geq d_{h-1} \geq 0$

Example: Triangular Distribution

Let X be a continuous random variable with support $[a, b]$ and mode m . This variable is said to follow a triangular distribution if it has the following density function:

$$f(x) = \begin{cases} \frac{2(x-a)}{(b-a)(m-a)}; & a \leq x \leq m \\ \frac{2(b-x)}{(b-a)(b-m)}; & m < x \leq b \end{cases} \quad (4)$$

Estimating the Mode of a Triangular Distribution

Let X be a random variable with pdf (4). For a random sample $\underline{X} = (X_1, \dots, X_s)$ with order statistics $X_{(1)} < X_{(2)} < \dots < X_{(s)}$, the likelihood for X is:

$$L(\underline{X}; a, m, b) = \left(\frac{2}{b-a}\right)^s \left\{ \prod_{i=1}^r \frac{X_{(i)} - a}{m - a} \prod_{i=r+1}^s \frac{b - X_{(i)}}{b - m} \right\} \quad (5)$$

- ▶ r is implicitly defined by $X_{(r)} \leq m < X_{(r+1)}$
- ▶ For given values of a and b we can easily compute m . In general, a and b are unobserved population parameters (Kotz and van Dorp 2004).
- ▶ The ML estimates of endpoints a and b can be computed using numerical methods (e.g. Nelder-Mead).

Experiment

- ▶ Compare the results of stratification using dynamic programming and the popular cumulative square root frequency (CSRF) algorithm.
- ▶ Use the variable *price* from the Stata auto dataset (74 observations).
- ▶ Use a sample size of 15 and allocate sampled items between three strata using Neyman allocation.
- ▶ *Price* is assumed to follow a triangular distribution.
- ▶ For the CSRF algorithm *price* is grouped into 9 equal classes.

Stata Output

```
.  
. optbounds price, distribution(Triangular) stratanum(3) endpts(1 2) nooutput  
> ins(9)
```

```
ML estimate of the mode  
3798  
-----
```

Stratification Results

```
Minimized Standard Deviation  
1161.825181
```

```
Optimal Strata Bounds  
1
```

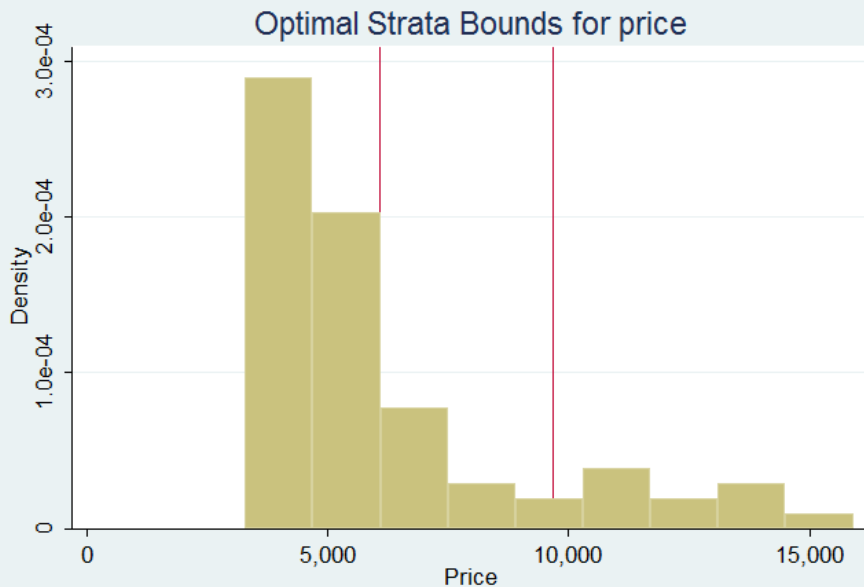
1	6079.705973
2	9674.824836

```
.  
. sum price
```

Variable	Obs	Mean	Std. Dev.	Min	Max
price	74	6165.257	2949.496	3291	15906

```
.  
.
```

Optimal Strata Bounds



Note: Strata boundary points are shown in red.

Results

Method	Point Estimate (Population Mean)	Standard Error	Margin of Error as % of Point Estimate	Design Effect
DP	5,969	163	4.9%	.091
CSRF	8,451	419	8.8%	.220

Sensitivity Analysis

Method	Margin of Error as % of Point Estimate	Design Effect
DP	4.9%	.091
CSRF		
3 Classes	5.5%	.094
5 Classes	9.6%	.236
7 Classes	8.2%	.195
9 Classes	8.8%	.220
11 Classes	9.0%	.203
13 Classes	8.9%	.201
15 Classes	4.5%	.053
17 Classes	8.6%	.197

Conclusion

- ▶ A stratified sampling design can improve the precision of point estimates.
- ▶ In practice, optimal stratification using dynamic programming compares favorably with the commonly used CSR algorithm.
- ▶ Dynamic programming methods are flexible and theoretically appealing.

References

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