

Using STATA's - ml method d2 - to estimate a  
multistate Markov transition model with unobserved  
heterogeneity

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# 1 CAVEAT....

Inference on the basis of ONE observation...

## 2 STATA's - ml methods -

If "linear form restrictions" are met, i.e.  $\ln L = \sum_i \ln L_i$ ;

- - lf - supply likelihood function only

If "linear form restrictions" are violated;

- - d0 - code likelihood function only
- - d1 - code analytical gradient
- - d2 - code analytical Hessian

### 3 The main message ....

When - ml method d0 -

- has trouble converging (“numerical derivatives cannot be computed”)
- or is just too slow,

STATA’s - ml method d2 - can offer HUGE improvements

- convergence and
- speed of convergence

Coding a - ml method d2 - estimator

- is in principle straightforward,
- **BUT** can be complicated by STATA’s limited matrix capabilities.  
[NOTE: Bobby Gutierrez pointed out during the meeting that there is an undocumented routine - mlmatbysum - that solves my problem]

## 4 The state transition model

- time is discrete  $t$
- there are  $S$  discrete states
- in each period  $t$ , we observe each individual  $i$ , its
  - state  $s_{it}$
  - individual specific characteristics  $x_{it}$  (potentially time varying)

$t$	0	1	2	3	4	5	...
$s_t$	2	2	1	2	3	2	...
$x_t$	$x_0$	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	...
<i>Transprob</i>	$P(22 x_0)$	$P(21 x_1)$	$P(12 x_2)$	$P(23 x_3)$	$P(32 x_4)$	...	...

- without unobserved heterogeneity: MNL ( - mlogit - ) for each state separately;
- consider unobserved heterogeneity in the form of discrete types a la Heckman-Singer (1984)  
location and mass of types to be estimated jointly with other parameters

So, conditional on  $x_{it}$ , we get transition matrices:

Type 1 (mass $q_1$ )		Type 2 (mass $q_2$ )				
State in $t + 1$		State in $t + 1$				
	1	2	3			
1	·	·	·	1	·	·
2	·	·	·	2	·	·
3	·	·	·	3	·	·
State in $t$				State in $t$		

## 5 The likelihood function

Conditional on individual  $i$  being of type  $j$ , the likelihood of observing the sequence of states  $\{s_{it}\}_{t=t_0}^{t_1}$  is

$$L_{ij} = \prod_{t=t_0}^{t_1-1} P(s_{it} \rightarrow s_{it+1} | x_{it}, \gamma = j, \beta_{s_{it}, s_{it+1}})$$

The unconditional likelihood for the individual becomes:

$$L_i = \sum_{j \in \Gamma} q_j L_{ij}$$

And the sample log likelihood takes the form:

$$\ln L = \sum_{i=1}^N \ln L_i = \sum_{i=1}^N \ln \left( \sum_{j \in \Gamma} q_j L_{ij} \right)$$

Note: "Linear form restrictions" are not met. The total coefficient vector to be estimated is:

$$(\beta_{1,1}, \beta_{1,2}, \dots, \beta_{n,n-1}, \beta_{n,n}, q_1, \dots, q_m)$$

## 5.1 The gradient:

”Typical element”:

$$\frac{\partial \ln L}{\partial \beta_{kl}} = \sum_{i=1}^N \sum_{j=1}^M \sum_{t=0}^{t_1} q_j \frac{L_{ij}}{L_i} \frac{1}{P_{ijt}} \frac{\partial P_{ijt}}{\partial \beta_{kl}}$$

## 5.2 The Hessian:

”Typical element”:

$$\frac{\partial \ln L}{\partial \beta_{kl} \partial \beta_{mn}} = \sum_{i=1}^N \sum_{j=1}^M \sum_{t=0}^{t_1} q_j \frac{L_{ij}}{L_i} \frac{1}{P_{ijt}} \left\{ \frac{1}{L_{ij}} \frac{\partial L_{ij}}{\partial \beta_{kl}} \frac{\partial P_{ijt}}{\partial \beta_{mn}} - \frac{1}{L_i} \frac{\partial L_i}{\partial \beta_{kl}} \frac{\partial P_{ijt}}{\partial \beta_{mn}} - \frac{1}{P_{ijt}} \frac{\partial P_{ijt}}{\partial \beta_{kl}} \frac{\partial P_{ijt}}{\partial \beta_{mn}} + \frac{\partial P_{ijt}}{\partial \beta_{kl} \partial \beta_{mn}} \right\}$$



## 6 Computational issues

### 6.1 Constraints:

- System memory
- Computing time

→ want to generate as few temporary variables as possible

### 6.2 Issues:

- Expand data (which has  $N * T$  obs. to start with) by a factor  $M$  to facilitate computation
- Log likelihood and gradient straightforward to compute

### 6.3 Problem:

- Hessian involves computation of terms of the form:

$$A'WB$$

where  $A = (a * [1, 1, \dots, 1]) * X$  (element by element)

$B = (b * [1, 1, \dots, 1]) * X$  (element by element)

$W$ - block diagonal with blocks of ones

- STATA cannot do this!! Or at least I couldn't...  
[NOTE: As Bobby Gutierrez pointed out during the meeting, STATA CAN DO THIS with the, so far, undocumented -ML MATBYSUM- so the problem is solved] .
- $W$  is square with dimensions  $N * T * M$  (i.e. potentially very big (> max matsize SE: 11000))

## 6.4 ”Solution”

Circumvent problem by manually multiplying in weights:

- create  $A$  : each variable in  $X$  multiplied by  $a$ .
- create  $B$  : each variable in  $X$  multiplied by  $a$ .
- use - matrix glsaccum - to get  $(A, B)'W(A, B) = \begin{bmatrix} A'WA & A'WB \\ B'WA & B'WB \end{bmatrix}$   
and only use the  $A'WB$  part.

- This involves generating LOADS of temporary variables

... takes a long time to compute

... and a lot of memory – I once ran out of memory on a 256M machine

(recall that data is already expanded)

...BUT: IT WORKS !!!